

Nenzyklisch IVPs des Runge-Kutta (2-Gliedern) (Hilfensystem)

μ	0	$ $	μ
$1-2\mu$	μ		$1-\mu$
$\frac{1}{2}$	$\frac{1}{2}$		

⇒ $\mu \in \mathbb{R}$ & Stabilität von n ist α abhängig
 $D=2$, $\mu \in \mathbb{R}$ & $D=3$ $\mu = \frac{1}{2} \pm \frac{\sqrt{3}}{6}$

$$t_{n,1} = t_n + \mu h \quad t_{n,2} = t_n + (1-\mu)h$$

$$J_{n,1} = y(t_n) + \mu h f(t_{n,1}, J_{n,1}) \quad J_{n,2} = y(t_n) + h((1-2\mu)f(t_{n,1}, J_{n,1}) + \mu f(t_{n,2}, J_{n,2}))$$

$$y(t_{n+1}) \approx y(t_n) + \frac{1}{2} (k_1 + k_2), \quad k_1 = f(t_{n,1}, J_{n,1}), \quad k_2 = f(t_{n,2}, J_{n,2})$$

Ausrechnung Taylor um k_1 & k_2 für $(t_n, y(t_n))$

$$\hat{f} = f(t_n, y(t_n)), \quad \hat{f}_t = \frac{d}{dt} f(t_n, y(t_n))$$

$$k_1 = f(t_{n,1}, J_{n,1}) = f(t_n, J_{n,1}) + \mu h f_t(t_n, J_{n,1}) + \frac{(\mu h)^2}{2} f_{tt}(t_n, J_{n,1}) + O(h^3)$$

$$= \tilde{f} + \mu h k_1 \tilde{f}_y + \frac{(\mu h f_1)^2}{2} \tilde{f}_{yy} + O(h^3) + \mu h \left[\tilde{f}_t + \mu h k_1 \tilde{f}_{ty} + O(h^2) \right] + \frac{(\mu h)^2}{2} \left[\tilde{f}_{tt} + O(h) \right]$$

$$= \tilde{f} + \mu h \tilde{f}_y \left[\tilde{f} + \mu h k_1 \tilde{f}_y + \mu h \tilde{f}_t + O(h^2) \right] + \frac{(\mu h)^2}{2} \left[\tilde{f} + O(h) \right]^2 \tilde{f}_{yy} + \mu h \tilde{f}_t \\ + (\mu h)^2 \tilde{f}_{ty} \left[\tilde{f} + O(h) \right] + \frac{(\mu h)^2}{2} \tilde{f}_{tt} + O(h^3)$$

$$= \tilde{f} + \mu h (\tilde{f}_t + \tilde{f} \tilde{f}_y) + (\mu h)^2 \tilde{f} \tilde{f}_y^2 + (\mu h)^2 \tilde{f}_t \tilde{f}_y + \frac{(\mu h)^2}{2} \tilde{f} \tilde{f}_{yy} + (\mu h)^2 \tilde{f}_{ty} \tilde{f} + \frac{(\mu h)^2}{2} \tilde{f}_{tt} + O(h^3)$$

$$= \tilde{f} + \mu h (\tilde{f}_t + \tilde{f} \tilde{f}_y) + \frac{(\mu h)^2}{2} \left[\tilde{f}_{tt} + \tilde{f} \tilde{f}_{yy} + 2 \tilde{f}_{ty} \tilde{f} + 2 \tilde{f}_y (\tilde{f}_t + \tilde{f} \tilde{f}_y) \right] + O(h^3)$$

$$K_2 = f(t_{n,2}, J_{n,2}) = f(t_n, J_{n,2}) + (1-\mu) h f_t(t_n, J_{n,2}) + \frac{(1-\mu)^2 h^2}{2} f_{tt}(t_n, J_{n,2}) + O(h^3)$$

$$= \hat{f} + h((1-2\mu)\kappa_1 + \mu\kappa_2) \hat{f}_y + \frac{h^2}{2} ((1-2\mu)\kappa_1 + \mu\kappa_2)^2 \hat{f}_{yy} + O(h^3)$$

$$+ (1-\mu) h \left[\hat{f}_t + h((1-2\mu)\kappa_1 + \mu\kappa_2) \tilde{f}_{ty} + O(h^2) \right] + \frac{(1-\mu)^2 h^2}{2} \tilde{f}_{tt} + O(h^3)$$

=

$$= \hat{f} + h(1-\mu)(\hat{f}_t + \hat{f}\hat{f}_y) + \frac{h^2}{2} \left\{ (1-\mu)^2 \tilde{f}_{tt} + (1-\mu)^2 \hat{f}_{yy} \hat{f} + 2(1-\mu)^2 \hat{f} \tilde{f}_{ty} \right\}$$

$$+ h^2 \left\{ (1-2\mu)\mu + \mu(1-\mu) \right\} (\hat{f}_t + \hat{f}\hat{f}_y) + O(h^3)$$

$$S_n = y(t_{n+1}) - \left\{ y_n + \frac{h}{2} (k_1 + k_2) \right\}$$

$$y(t_{n+1}) = y(t_n) + h \tilde{f} + \frac{h^2}{2} (\tilde{f}_t + \tilde{f} \tilde{f}_y) + \frac{h^3}{6} \left\{ \tilde{f}_{tt} + \tilde{f}^2 \tilde{f}_{yy} + 2 \tilde{f}_{ty} \tilde{f} + f_y (f_t + \tilde{f} \tilde{f}_y) \right\} + O(h^4)$$

Οι παραγόντες των $y(t_n) + \frac{h}{2} (k_1 + k_2)$, ως σημείο συναρτήσεων h .

$$h^0 : y(t_n), \quad h^1 : \tilde{f}, \quad h^2 : \frac{1}{2} (\tilde{f}_t + \tilde{f} \tilde{f}_y) + \frac{(1-\mu)}{2} (\tilde{f}_t + \tilde{f} \tilde{f}_y) = \frac{1}{2} (\tilde{f}_t + \tilde{f} \tilde{f}_y)$$

Τυχαίων ή με $\mu \in \mathbb{R}$. $S_n = O(h^3)$, Τυχαίων ταύτης αριθμούς 2.

$$h^3 : \frac{\mu^2}{4} (\hat{f}_{tt} + \hat{f}_{yy} \hat{f} + 2\hat{f}\hat{f}_{ty} + 2\hat{f}_{ty}(\hat{f}_t + \hat{f}_y \hat{f})) \\ + \frac{(1-\mu)^2}{4} (\hat{f}_{tt} + \hat{f}_{yy} \hat{f} + 2\hat{f}\hat{f}_{ty}) + \frac{1}{2}(2-3\mu)\mu (\hat{f}_t + \hat{f}\hat{f}_{ty}) \hat{f}_y$$

Για να μπορέω να αναλύσω τις σπουδές h^3

$$\frac{\mu^2}{4} + \frac{(1-\mu)^2}{4} = \frac{1}{6} \quad \text{και} \quad \frac{1}{2}(\mu(2-3\mu) + \mu^2) = \frac{1}{6}$$

$$\frac{1}{4}(\mu^2 + \mu^2 + 1 - 2\mu) = \frac{1}{6} \quad \text{in} \quad 2\mu^2 - 2\mu + 1 = \frac{2}{3} \quad \text{in} \quad \mu^2 - \mu + \frac{1}{2} - \frac{1}{3} = 0, \quad \text{πλην} \quad \underline{\underline{\mu = \frac{1}{2} \pm \frac{\sqrt{3}}{6}}}$$

Τα δύο μ μεταβολές και τη $2 = 6 \times \text{const.}$

Τοτε η τέλη αριθμείται ως $\underline{\underline{p=3}}$.