

## Topological manifold

A **topological manifold of dimension  $n$**  is a set  $M$  together with a set of subsets  $\{U_i \subseteq M : i \in \mathcal{A}\}$  such that

1. the  $U_i$  cover  $M$ , that is  $M = \bigcup_{i \in \mathcal{A}} U_i$ ,
2. for every  $i \in \mathcal{A}$ , there is a bijection  $\varphi_i : U_i \rightarrow B^n$  from  $U_i$  to the unit ball in  $\mathbb{R}^n$ ,  $B^n = \{x \in \mathbb{R}^n : |x| < 1\}$ .
3. for every  $i, j \in \mathcal{A}$  with  $U_i \cap U_j \neq \emptyset$ , the mapping

$$\varphi_j \circ \varphi_i^{-1} : \varphi_i(U_i \cap U_j) \rightarrow \varphi_j(U_i \cap U_j)$$

is continuous as a mapping between subsets of  $\mathbb{R}^n$ .

The mapping  $\varphi_i : U_i \rightarrow B^n$  is a **coordinate chart** for the topological manifold  $M$ . The set  $\{U_i \subseteq M : i \in \mathcal{A}\}$  together with the set of coordinate charts  $\{\varphi_i : U_i \rightarrow B^n, i \in \mathcal{A}\}$  is an **atlas** for the topological manifold  $M$ . The mappings  $\varphi_j \circ \varphi_i^{-1} : \varphi_i(U_i \cap U_j) \rightarrow \varphi_j(U_i \cap U_j)$  are the **transition functions** of the atlas.

**Example 1**  $\mathbb{R}^n$  itself is a topological manifold of dimension  $n$ . For every point  $a \in \mathbb{R}^n$ , we define  $U_a = \{x \in \mathbb{R}^n : |x - a| < 1\}$ , and the coordinate chart  $\varphi_a : x \mapsto x - a$ . The set  $\{U_a : a \in \mathbb{R}^n\}$  is clearly a covering of  $\mathbb{R}^n$ , and the transition functions are continuous,  $\varphi_a \circ \varphi_b^{-1}(y) = y + b - a$ .

**Example 2** The circle  $S^1 = \{x \in \mathbb{R}^2 : |x| = 1\}$  is a topological manifold of dimension 1. We can define an atlas with two coordinate charts.

Let  $g : (-1, 1) \rightarrow S^1$  be the mapping  $t \mapsto (\cos \pi t, \sin \pi t)$ . The image of  $g$  is the set  $U_1 = S^1 \setminus \{(-1, 0)\}$  and  $g$  is an injection. So there is an inverse  $g^{-1} : U_1 \rightarrow (-1, 1)$ . We define the coordinate chart  $\varphi_1(x) = g^{-1}(x)$ .

Similarly, we define  $g : (-1, 1) \rightarrow S^1$  to be the mapping  $t \mapsto (-\cos \pi t, \sin \pi t)$ . The image of  $h$  is the set  $U_2 = S^1 \setminus \{(1, 0)\}$  and  $h$  is an injection. So there is an inverse  $h^{-1} : U_2 \rightarrow (-1, 1)$ . We define the coordinate chart  $\varphi_2(x) = h^{-1}(x)$ .

Check that the transition functions are continuous.

**Example 3** We shall define the structure of a topological manifold of dimension 2 on the set  $S^2 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1\}$ : We define an atlas consisting of a covering by 6 subsets,  $U_u, U_d, U_l, U_r, U_f, U_b$  (where the indices stand for *up, down, left, right, front* and *back*),

$$\begin{aligned} U_u &= \{(x, y, z) \in S^2 : z > 0\}, & \varphi_u(x, y, z) &= (x, y) \in \mathbb{R}^2, \\ U_d &= \{(x, y, z) \in S^2 : z < 0\}, & \varphi_d(x, y, z) &= (x, y) \in \mathbb{R}^2, \\ U_l &= \{(x, y, z) \in S^2 : y < 0\}, & \varphi_l(x, y, z) &= (x, z) \in \mathbb{R}^2, \end{aligned}$$

$$\begin{aligned}
U_r &= \{(x, y, z) \in S^2 : y > 0\}, & \varphi_r(x, y, z) &= (x, z) \in \mathbb{R}^2, \\
U_f &= \{(x, y, z) \in S^2 : x > 0\}, & \varphi_f(x, y, z) &= (y, z) \in \mathbb{R}^2, \\
U_b &= \{(x, y, z) \in S^2 : x < 0\}, & \varphi_b(x, y, z) &= (y, z) \in \mathbb{R}^2.
\end{aligned}$$

Check that for  $(s, t) \in B^2$ ,  $\varphi_u^{-1}(s, t) = (s, t, \sqrt{1 - s^2 - t^2})$ , and that if  $t < 0$ ,  $\varphi_u^{-1}(s, t) \in U_u \cap U_l$  and the transition function is  $\varphi_l \circ \varphi_u^{-1}(s, t) = (s, \sqrt{1 - s^2 - t^2})$ , which is clearly a continuous mapping between subsets of  $\mathbb{R}^2$ .