CONVERGENCE OF MULTIPLE ERGODIC AVERAGES FOR SOME COMMUTING TRANSFORMATIONS

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Abstract. We prove the $L^2$ convergence for the linear multiple ergodic averages of commuting transformations $T_1, \ldots, T_l$, assuming that each map $T_i$ and each pair $T_i T_j^{-1}$ is ergodic for $i \neq j$. The limiting behavior of such averages is controlled by a particular factor, which is an inverse limit of nilsystems. As a corollary we show that the limiting behavior of linear multiple ergodic averages is the same for commuting transformations.

1. Introduction

We consider the multiple ergodic averages

\[ \frac{1}{N} \sum_{n=0}^{N-1} f_1(T_1^n x) \cdot f_2(T_2^n x) \cdots f_l(T_l^n x), \]

where $T_1, T_2, \ldots, T_l$ are commuting measure preserving transformations of a probability space $(X, \mathcal{X}, \mu)$. Such averages, with $T_1 = T, T_2 = T^2, \ldots, T_l = T^l$, were originally studied by Furstenberg [F77] in his proof of Szemerédi’s Theorem, and for general commuting transformations by Furstenberg and Katznelson [FK79] in their proof of the multidimensional Szemerédi Theorem. The convergence in $L^2(\mu)$ for the first case was proved in [HK03].

With certain hypotheses on the transformations, convergence for three commuting transformations was proven by Zhang [Zh96]. Under the same hypotheses, we generalize this convergence result for $l$ commuting transformations:

**Theorem 1.1.** Let $l \geq 1$ be an integer. Assume that $T_1, T_2, \ldots, T_l$ are commuting invertible ergodic measure preserving transformations of a measure space $(X, \mathcal{X}, \mu)$ so that $T_i T_j^{-1}$ is ergodic for all $i, j \in \{1, 2, \ldots, l\}$ with $i \neq j$. Then if $f_1, f_2, \ldots, f_l \in L^\infty(\mu)$ the averages

\[ \frac{1}{N} \sum_{n=0}^{N-1} f_1(T_1^n x) \cdot f_2(T_2^n x) \cdots f_l(T_l^n x) \]

converge in $L^2(\mu)$ as $N \to +\infty$.

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In order to prove convergence, we show that in the average (1) we can replace each function by its conditional expectation on a certain factor and that this factor is an inverse limit of translations on a nilmanifold. However, this does not hold for general commuting transformations. In Section 3 we show that certain ergodic assumptions on the differences \( T_i T_j^{-1} \), such as the ones we impose in Theorem 1.1, are necessary for the characteristic factor to be an inverse limit of transformations on a nilmanifold. The general case for commuting transformations remains open and only is known for \( l = 2 \) [CL84]. Convergence for certain distal systems was obtained in [Ls93].

Using the machinery developed for the proof of Theorem 1.1 and a result of Ziegler [Zi03], in Section 4 we prove an identity illustrating that for ergodic commuting transformations the limiting behavior of the corresponding linear multiple ergodic averages is the same:

**Theorem 1.2.** Suppose that \( T \) and \( S \) are commuting invertible measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\) and that both \( T \) and \( S \) are ergodic. Then for all integers \( l \geq 1 \) and any \( f_1, \ldots, f_l \in L^\infty(\mu) \) we have:

\[
\lim_{N \to \infty} \frac{1}{N} \sum_{n=0}^{N-1} f_1(T^n x) \cdot \ldots \cdot f_l(T^{ln} x) = \lim_{N \to \infty} \frac{1}{N} \sum_{n=0}^{N-1} f_1(S^n x) \cdot \ldots \cdot f_l(S^{ln} x)
\]

in \( L^2(\mu) \).

We summarize the strategy of the proof of Theorem 1.1. The factors that control the limiting behavior of the averages (1) are the same as those that arise in the proof of the convergence of multiple ergodic averages along arithmetic progressions in [HK03]. These factors are defined by certain seminorms and the starting point for the convergence of the averages (1) is that commuting ergodic systems have the same associated seminorms (Proposition 3.1). We use this observation in Proposition 3.2 to bound the limsup of the \( L^2 \)-norm of the averages by the seminorms of the individual functions. The structure theorem of [HK03] then implies that it suffices to check convergence when every transformation \( T_i \) is isomorphic to an inverse limit of translations on a nilmanifold. The main technical difficulty is to prove that this isomorphism can be taken to be simultaneous and that the factor sub-\( \sigma \)-algebras that appear in the inverse limits can be chosen to be the same for all transformations \( T_i \) (Theorems 4.1 and 4.2).

**Notation.** For \( l \) commuting maps \( T_1, \ldots, T_l \), we use the shorthand \((X, \mu, T_1, \ldots, T_l)\), omitting the \( \sigma \)-algebra, to denote the measure preserving system obtained by the maps \( T_1, \ldots, T_l \) acting on a fixed measure space \((X, \mathcal{X}, \mu)\). For simplicity of notation, we assume that all functions in this article are real valued. With minor modifications, the same definitions and results hold for complex valued functions.

2. **Seminorms and factors \( Z_k \)**

Assume that \((X, \mu, T)\) is an ergodic system; we summarize a construction and some results from [HK03].
For an integer $k \geq 0$, we write $X^{[k]} = X^{2^k}$ and $T^{[k]} : X^{[k]} \to X^{[k]}$ for the map $T \times T \times \ldots \times T$, taken $2^k$ times. We let $V_k = \{0, 1\}^k$ and write elements of $V_k$ without commas or parentheses. Elements of $X^{[k]}$ are written $x = (x_\epsilon : \epsilon \in V_k)$.

We define a probability measure $\mu^{[k]}$ on $X^{[k]}$, that is invariant under $T^{[k]}$, by induction. Set $\mu^{[0]} = \mu$. For $k \geq 0$, let $\mathcal{I}^{[k]}$ be the $\sigma$-algebra of $T^{[k]}$-invariant subsets of $X^{[k]}$. Then $\mu^{[k+1]}$ is the relatively independent square of $\mu^{[k]}$ over $\mathcal{I}^{[k]}$. This means that if $F', F''$ are bounded functions on $X^{[k]}$ then

$$
\int_{X^{[k+1]}} F'(x') F''(x'') \, d\mu^{[k+1]}(x', x'') := \int_{X^{[k]}} \mathbb{E}(F' | \mathcal{I}^{[k]}) \mathbb{E}(F'' | \mathcal{I}^{[k]}) \, d\mu^{[k]}.
$$

For a bounded function $f$ on $X$ and integer $k \geq 1$ we define

$$
\|f\|_{k}^{2^k} = \int_{X^{[k]}} \prod_{j=0}^{2^k - 1} f(x_j) \, d\mu^{[k]}(x),
$$

and we note that the integral on the right hand side is nonnegative. We immediately have that $\|f\|_1 = |\int f \, d\mu|$. It is shown in [HK03] that for every integer $k \geq 1$, $\| \cdot \|_k$ is a seminorm on $L^\infty(\mu)$ and using the Ergodic Theorem it is easy to check that

$$
\|f\|_{k+1}^{2^k+1} = \lim_{N \to +\infty} \frac{1}{N} \sum_{n=0}^{N-1} \|f \cdot T^n f\|_k^{2^k}.
$$

Furthermore, it is shown in [HK03] that for every integer $k \geq 1$ the seminorms define factors $Z_{k-1}(X)$ in the following manner: the $T$-invariant sub-$\sigma$-algebra $Z_{k-1}(X)$ is characterized by

$$
\|f\|_k = 0 \text{ if and only if } \mathbb{E}(f | Z_{k-1}) = 0,
$$

then $Z_{k-1}(X)$ is defined to be the factor of $X$ associated to the sub-$\sigma$-algebra $Z_{k-1}(X)$. Thus defined, $Z_0(X)$ is the trivial factor, $Z_1(X)$ is the Kronecker factor and more generally, $Z_k(X)$ is a compact abelian group extension of $Z_{k-1}(X)$. We denote the restriction of $\mu$ to $Z_k(X)$ by $\mu_k$.

Define $\mathcal{G} = \mathcal{G}(X, T)$ to be the group of measure preserving transformations $S$ of $X$ which satisfy for every integer $k \geq 1$: the transformation $S^{[k]}$ of $X^{[k]}$ leaves the measure $\mu^{[k]}$ invariant and acts trivially on the invariant $\sigma$-algebra $\mathcal{I}^{[k]}$.

In our context, there is more than one transformation acting on the space and so we need some notation to identify the transformation with respect to which the seminorm is defined. We write $\| \cdot \|_{k,T}$ for the $k$-th seminorm with respect to the map $T$. Similarly we write $Z_k(X, T)$ for the $k$-th factor associated to $T$, $\mu_T^{[k]}$ for the measure defined by (3), and $\mathcal{I}^{[k]}(T)$ for the $T^{[k]}$-invariant subsets of $X^{[k]}$. 
3. Characteristic factors for commuting transformations

Let \( T_1, T_2, \ldots, T_l \) be commuting invertible measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\). We say that a sub-\(\sigma\)-algebra \( \mathcal{C} \) of \( \mathcal{X} \) is a characteristic factor for \( L^2(\mu) \)-convergence of the averages (1) if \( \mathcal{C} \) is \( T_i \) invariant for \( i = 1, \ldots, l \), and the averages (1) converge in \( L^2(\mu) \) to zero whenever \( \mathbb{E}(f_i | \mathcal{C}) = 0 \) for some \( i \in \{1, \ldots, l\} \).

In this section we show that under the assumptions of Theorem 1.1, the averages (1) converge in \( L^2(\mu) \). Let \( l \geq 1 \) be an integer. Assume that \( T_1, T_2, \ldots, T_l \) are commuting invertible ergodic measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\) such that \( T_i T_j^{-1} \) is ergodic for all \( i, j \in \{1, 2, \ldots, l\} \) with \( i \neq j \).

Example. Consider the measure preserving transformations \( T_1 = R \times S_1, T_2 = R \times S_2 \), acting on the measure space \((X = Y \times Z, \mathcal{Y} \times \mathcal{Z}, \mu \times \nu)\) and suppose that \( T_1 \) and \( T_2 \) commute. Taking \( l = 2, f_1(y, z) = f(y) \), and \( f_2(y, z) = \bar{f}(y) \) we see that the limit of the averages in (1) is zero if and only if \( f \) is zero almost everywhere. It follows that any sub-\(\sigma\)-algebra that is characteristic for \( L^2(\mu) \)-convergence of these averages contains \( \mathcal{Y} \).

So if \( \mathcal{Y} \not\subset \mathcal{Z}_1(Y, R) \), meaning that \( (Y, \mu, R) \) is not a Kronecker system for ergodic \( R \), then \( \mathcal{Z}_1(X, T_1) \) is not a characteristic factor. More generally, if there exists a function that is \( T_i T_j^{-1} \) invariant but not \( \mathcal{Z}_i(X, T_i) \)-measurable, for \( i = 1, 2 \), the same argument gives that \( \mathcal{Z}_i(X, T_i) \) is not a characteristic factor for \( i = 1, 2 \).

We turn now to the proof of the main result of the section. The most important ingredient of the proof is the next observation. This result, as well as Proposition 3.2, were also obtained independently by I. Assani (personal communication).

Proposition 3.1. Assume that \( T \) and \( S \) are commuting measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\) and that both \( T \) and \( S \) are ergodic. Then \( S \in \mathcal{G}(X, T) \), \( \mathcal{G}(X, T) = \mathcal{G}(X, S) \), and for all integers \( k \geq 1 \) and all \( f \in L^\infty(\mu), \mu_T^{[k]} = \mu_S^{[k]}, \mathcal{I}^{[k]}(T) = \mathcal{I}^{[k]}(S), \|f\|_{k, T} = \|f\|_{k, S} \), and \( Z_k(X, T) = Z_k(X, S) \).

Proof. By Lemma 5.5 in [HK03], \( S \in \mathcal{G}(X, T) \). We use induction on \( k \) to show that \( \mu_T^{[k]} = \mu_S^{[k]} \) and \( \mathcal{I}^{[k]}(T) = \mathcal{I}^{[k]}(S) \). The statement is obvious for \( k = 0 \). Suppose that it holds for some integer \( k \geq 1 \). By Equation (3), we have that \( \mu_T^{[k+1]} = \mu_S^{[k+1]} \). Since \( S \in \mathcal{G}(X, T) \), we have that \( S^{[k+1]} \) leaves the measure \( \mu_T^{[k+1]} = \mu_S^{[k+1]} \) invariant and acts trivially on \( \mathcal{I}^{[k+1]} \). Hence, \( \mathcal{I}^{[k+1]}(T) \subset \mathcal{I}^{[k+1]}(S) \). Reversing the roles of \( T \) and \( S \), we have that \( \mathcal{I}^{[k+1]}(T) = \mathcal{I}^{[k+1]}(S) \). This completes the induction.

By the definition of \( \mathcal{G}(X, T) \) and Equations (4) and (6), the equalities \( \mathcal{G}(X, T) = \mathcal{G}(X, S), \|f\|_{k, T} = \|f\|_{k, S} \) and \( Z_k(X, T) = Z_k(X, S) \) follow. \( \square \)

Proposition 3.2. Let \( l \geq 1 \) be an integer. Assume that \( T_1, T_2, \ldots, T_l \) are commuting invertible ergodic measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\) such that \( T_i T_j^{-1} \) is ergodic for all \( i, j \in \{1, 2, \ldots, l\} \) with \( i \neq j \).
Proof. Note that by Proposition 3.1, we can take these seminorms and the sub-$\sigma$-algebras $Z_l$ with respect to any of the maps $T_i$ with $i \in \{1, 2, \ldots, l\}$, since they are all the same.

Part (ii) follows immediately from part (i) and the definition of the sub-$\sigma$-algebra $Z_{l-1}$. We prove the inequality of part (i) by induction. For $l = 1$, this follows from the ergodic theorem.

Assume the statement holds for $l - 1$ functions and that $f_1, f_2, \ldots, f_l \in L^\infty(\mu)$ with $\|f_j\|_\infty \leq 1$ for $j = 1, 2, \ldots, l$. First assume that $i \in \{2, 3, \ldots, l\}$. (The case $i = 1$ is similar, with the roles of $T_1$ and $T_2$ reversed.) Let

$$u_n = f_1(T_1^n x) \cdot f_2(T_2^n x) \cdot \ldots \cdot f_i(T_i^n x).$$

For convenience we use the notation $T^n f(x) = f(T^n x)$. By the Van der Corput Lemma (see Bergelson [B87]),

$$\limsup_{N \to \infty} \left\| \frac{1}{N} \sum_{n=0}^{N-1} u_n \right\|^2_{L^2(\mu)} \leq \limsup_{M \to \infty} \frac{1}{M} \sum_{m=0}^{M-1} \limsup_{N \to \infty} \left\| \frac{1}{N} \sum_{n=0}^{N-1} \langle u_{n+m}, u_n \rangle \right\|,$$

(7)

A simple computation gives that

$$\frac{1}{N} \sum_{n=0}^{N-1} \langle u_{n+m}, u_n \rangle \leq \left\| \frac{1}{N} \sum_{n=0}^{N-1} (T_2 T_1^{-1})^n (T_2^m f_2 f_2) \cdot \ldots \cdot (T_i T_1^{-1})^n (T_i^m f_i f_i) \right\|_{L^2(\mu)}.$$

For $j = 2, 3, \ldots, l$, define $S_j = T_j T_1^{-1}$. The maps $S_2, S_3, \ldots, S_l$ commute, since the maps $T_1, T_2, \ldots, T_l$ do, and they also commute with $T_1, \ldots, T_l$. Furthermore for $i \neq j$, the transformation $S_i S_j^{-1} = T_i T_j^{-1}$ is ergodic by assumption. Hence, we can use the inductive assumption and (5) to bound the right hand side in (7) by

$$\limsup_{M \to \infty} \frac{1}{M} \sum_{m=0}^{M-1} \left\| f_i T_i^m f_i \right\|_{l^{-1}, S_i} \leq \limsup_{M \to \infty} \left( \frac{1}{M} \sum_{m=0}^{M-1} \left\| f_i T_i^m f_i \right\|^{2^{l-1}}_{l^{-1}, S_i} \right)^{1/2^{l-1}} = \left\| f_i \right\|^2_{l^{-1}, T_i},$$

where the last equality follows from (5) and Proposition 3.1.

4. Structure of the characteristic factor and the proof of convergence

We have shown that under the assumptions of Theorem 1.1, a characteristic factor for $L^2(\mu)$-convergence of the averages (1) is $Z_{l-1}$. The structure theorem of [HK03] gives
that for \(i = 1, \ldots, l\) the system \((Z_{i-1}, \mu_{i-1}, T_i)\) is isomorphic to an inverse limit of \((l-1)\)-step nilsystems. But this isomorphism apriori depends on the transformation \(T_i\), and the sub-\(\sigma\)-algebras that appear in the inverse limits depend on the transformations. In this and the following section we extend several results from [HK03] and use them to deal with these technical difficulties.

Throughout this section, \(T_1, \ldots, T_l\) are commuting, ergodic, measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\). If \(S_1, \ldots, S_l\) are measure preserving transformations of a probability space \((Y, \mathcal{Y}, \nu)\), we say that the system \((X, \mu, T_1, \ldots, T_l)\) is isomorphic to \((Y, \nu, S_1, \ldots, S_l)\) if there exist sets \(X' \subset X, Y' \subset Y\) of full measure that are invariant under all the transformations on their respective spaces, and a measurable bijection \(\phi: X' \rightarrow Y'\) carrying \(\mu\) to \(\nu\) that satisfies \(\phi(T_i(x)) = S_i(\phi(x))\) for every \(x \in X'\) and all \(i = 1, \ldots, l\). When \(\phi\) is not assumed to be injective, then we say that \((Y, \nu, S_1, \ldots, S_l)\) is a factor of \((X, \mu, T_1, \ldots, T_l)\). For simplicity of notation we assume that \(X = X'\) and \(Y = Y'\).

We say that the system \((X, \mu, T_1, \ldots, T_l)\) is an extension of its factor \((Y, \nu, S_1, \ldots, S_l)\) (let \(\pi: X \rightarrow Y\) denote the factor map) by a compact abelian group \((V, +)\) if there exist measurable cocycles \(\rho_1, \ldots, \rho_l: Y \rightarrow V\) and a measure preserving bijection \(\phi: X \rightarrow Y \times V\) (we let \(m_V\) denote the Haar measure on \(V\)), satisfying:

(i) \(\phi\) preserves \(Y\), meaning that \(\phi^{-1}(\mathcal{Y} \times V) = \pi^{-1}(\mathcal{Y})\) up to sets of measure zero, where \(\mathcal{Y} \times V = \{A \times V: A \in \mathcal{Y}\}\), and

(ii) \(\phi(T_i(x)) = T'_i(\phi(x))\) for all \(x \in X, y \in Y, v \in V\) and \(i \in \{1, \ldots, l\}\), where

\[
T'_i(y, v) = (S_i(y), v + \rho_i(y))
\]

Setting \(\tilde{\rho} = (\rho_1, \ldots, \rho_l)\), we let \(Y \times_{\tilde{\rho}} V\) denote the system \((Y \times V, \nu \times m_V, T'_1, \ldots, T'_l)\).

We say that the system \((X, \mu, T_1, \ldots, T_l)\) has order \(k\) if \(X = Z_k(X)\). (Note that \(Z_k(X) = Z_k(X, T_i)\) does not depend on \(i\) by Proposition 3.1.) It has toral Kronecker factor if \((Z_1, \mu_1, T_1, \ldots, T_l)\) is isomorphic to a system \((V, m_V, R_1, \ldots, R_l)\), where \(V\) is a compact abelian Lie group, \(m_V\) is the Haar measure, and \(R_i\), for \(i = 1, \ldots, l\), is a rotation on \(V\). Finally, it is toral if it is of order \(k\) for some integer \(k \geq 1\), it has toral Kronecker factor, and for \(j = 1, \ldots, k - 1\), the system \((Z_{j+1}, \mu_{j+1}, T_1, \ldots, T_l)\) is an extension of \((Z_j, \mu_j, T_1, \ldots, T_l)\) by a finite dimensional torus.

We say that the system \((X, \mu, T_1, \ldots, T_l)\) is an inverse limit of a sequence of factors \(\{(X_j, \mu_j, T_1, \ldots, T_l)\}_{j \in \mathbb{N}}\), if \(\{X_j\}_{j \in \mathbb{N}}\) is an increasing sequence of sub-\(\sigma\)-algebras invariant under the transformations \(T_1, \ldots, T_l\), and such that \(\bigvee_{j \in \mathbb{N}} X_j = X\) up to sets of measure zero. If in addition for every \(j \in \mathbb{N}\) the factor system \((X_j, \mu_j, T_1, \ldots, T_l)\) is isomorphic to a toral system of order \(k\), we say that \((X, \mu, T_1, \ldots, T_l)\) is an inverse limit of a sequence of toral systems of order \(k\).

The next result extends Theorem 10.3 from [HK03] to the case of several commuting transformations and we postpone the proof until Section 5.
Theorem 4.1. Any system \((X, \mu, T_1, \ldots, T_l)\) of order \(k\) is an inverse limit of a sequence \(\{(X_i, \mu_i, T_1, \ldots, T_l)\}_{i \in \mathbb{N}}\) of toral systems of order \(k\).

To describe the characteristic factors, we briefly review the definition of a nilsystem. Given a group \(G\), we denote the commutator of \(g, h \in G\) by \([g, h] = g^{-1}h^{-1}gh\). If \(A, B \subset G\), then \([A, B]\) is defined to be the subgroup generated by the set of commutators \(\{[a, b] : a \in A, b \in B\}\). Set \(G^{(1)} = G\) and for integers \(k \geq 1\), we inductively define \(G^{(k+1)} = [G, G^{(k)}]\). A group \(G\) is said to be \(k\)-step nilpotent if its \((k+1)\) commutator \([G, G^{(k)}]\) is trivial. If \(G\) is a \(k\)-step nilpotent Lie group and \(\Gamma\) is a discrete cocompact subgroup, then the compact space \(X = G/\Gamma\) is said to be a \(k\)-step nilmanifold. The group \(G\) acts on \(G/\Gamma\) by left translation and the translation by a fixed element \(a \in G\) is given by \(T_a(g\Gamma) = (ag)\Gamma\). There exists a unique probability measure \(m_{G/\Gamma}\) on \(X\) that is invariant under the action of \(G\) by left translations (called the Haar measure). Fixing elements \(a_1, \ldots, a_l \in G\), we call the system \((G/\Gamma, m_{G/\Gamma}, T_{a_1}, \ldots, T_{a_l})\) a \(k\)-step nilsystem and call each map \(T_a\) a nilrotation.

The next result extends the structure theorem of [HK03] (Theorem 10.5) to the case of several ergodic commuting transformations:

Theorem 4.2. Let \(l \geq 1\) be an integer and let \((X, \mu, T_1, \ldots, T_l)\) be a toral system of order \(k\). Then there exist a \(k\)-step nilpotent Lie group \(G\), a discrete and cocompact subgroup \(\Gamma\) of \(G\), and commuting elements \(a_1, \ldots, a_l\) of \(G\), such that the system \((X, \mu, T_1, \ldots, T_l)\) is isomorphic to the \(k\)-step nilsystem \((G/\Gamma, m_{G/\Gamma}, T_{a_1}, \ldots, T_{a_l})\).

Proof. Let \(G = G(X, T_1)\). By the structure theorem in [HK03] the group \(G\) is \(k\)-step nilpotent, and by Proposition 3.1 we have that \(T_1, \ldots, T_l \in G\). Let \(G\) be the subgroup of \(G\) that is spanned by the connected component of the identity and the transformations \(T_1, \ldots, T_l\). At the end of the proof of Theorem 10.5 in [HK03], it is shown that there exist a discrete cocompact subgroup \(\Gamma\) of \(G\) and a measurable bijection \(\phi : G/\Gamma \to X\) that carries the Haar measure \(m_{G/\Gamma}\) to \(\mu\), such that for all \(S \in G\) the transformation \(\phi^{-1}S\phi\) of \(G/\Gamma\) is the left translation on \(G/\Gamma\) by \(S\). Since \(\phi\) does not depend on \(S \in G\), and \(T_1, \ldots, T_l \in G\), the proof is complete.

We now combine the previous results to prove Theorem 1.1:

Proof of Theorem 1.1. If \(\mathbb{E}(f_i | Z_{l-1}) = 0\) for some \(i \in \{1, \ldots, l\}\), then \(\|f_i\|_l = 0\) and by Proposition 3.2 the limit of the averages (1) is zero. Hence, we can assume that \(X = Z_{l-1}\). By Theorem 4.1, the system \((X, \mu, T_1, \ldots, T_l)\) is an inverse limit of toral systems \((X_i, \mu_i, T_1, \ldots, T_l)\) of order \(l-1\). It follows from Theorem 4.2 that \((X_i, \mu_i, T_1, \ldots, T_l)\) is isomorphic to an \((l-1)\)-step nilsystem. Using an approximation argument, we can assume that \(X = G/\Gamma\), \(\mu = m_{G/\Gamma}\), and the transformations \(T_i\) are given by nilrotations \(T_a\) on \(G/\Gamma\) where \(a_i\) are commuting elements of \(G\) for \(i = 1, \ldots, l\). If \(a = (a_1, \ldots, a_l) \in (G/\Gamma)^l\),
then by [Lb03] the average
\[ \lim_{N \to \infty} \frac{1}{N} \sum_{n=0}^{N-1} T^n_a f \]
converges everywhere in \((G/\Gamma)^l\) as \(N \to \infty\) for \(f\) continuous. Using the convergence on the diagonal and a standard approximation argument the result follows. \(\square\)

We also now have the tools to prove Theorem 1.2:

**Proof of Theorem 1.2.** The \(L^2(\mu)\) convergence for these averages was proved in [HK03]. From Proposition 3.1 we have that \(Z_{l-1}(X, T) = Z_{l-1}(X, S)\), and by Proposition 3.2 this common factor is characteristic for \(L^2\)-convergence of the averages in (2). Hence, we can assume that \(X = Z_{l-1}\). Then by Theorem 4.1, the system \((X, \mu, T, S)\) is an inverse limit of toral systems \((X_i, \mu_i, T, S)\) of order \(l - 1\). It follows by Theorem 4.2 that \((X, \mu, T, S)\) is isomorphic to an \((l - 1)\)-step nilsystem. Using an approximation argument, we can assume \(X = G/\Gamma\), \(\mu = m_{G/\Gamma}\), and the transformations \(T\) and \(S\) are given by ergodic nilrotations \(T_a, T_b\) on \(G/\Gamma\).

In [Zi03], Ziegler gives a formula for the limit of the averages in (2) when the transformations are nilrotations. Using this identity it is clear that the limit is the same for all ergodic nilrotations on \(G/\Gamma\). Since both \(T_a\) and \(T_b\) are ergodic, the result follows. \(\square\)

5. **Proof of Theorem 4.1**

The proof of Theorem 4.1 is carried out in three steps, as in [HK03] for a single transformation. We give all the statements of the needed modifications, but only include the proof when it is not a simple rephrasing of the corresponding proof in [HK03]. We summarize the argument. Suppose that the system \((X, \mu, T_1, \ldots, T_l)\) is of order \(k + 1\), meaning that \(X = Z_{k+1}\). First we prove that the system \((Z_{k+1}, \mu_{k+1}, T_1, \ldots, T_l)\) is a connected compact abelian group extension of \((Z_k, \mu_k, T_1, \ldots, T_l)\). Next we show that if \((Z_k, \mu_k, T_1, \ldots, T_l)\) is an inverse limit of systems \(\{(Z_{k,i}, \mu_{k,i}, T_1, \ldots, T_l)\}_{i \in \mathbb{N}}\), then the cocycle that defines the extension is measurable with respect to some \(Z_{k,i}\). Finally, we combine the first two steps to complete the proof by induction. To prove Lemmas 5.1 and 5.2, we make use of the analogous results in [HK03] for a single transformation, extending them to several transformations. The argument given in Step 3 is similar to the one used in [HK03] and we include it as it ties together the previous lemmas.

**Step 1.** We extend Theorem 9.5 from [HK03].

**Lemma 5.1.** Let \(k, l \geq 1\) be integers and let \(T_1, \ldots, T_l\) be commuting ergodic measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\). Then the system \((Z_{k+1}, \mu_{k+1}, T_1, \ldots, T_l)\) is an extension of the system \((Z_k, \mu_k, T_1, \ldots, T_l)\) by a connected compact abelian group.
Proof. Using the analogous result for a single transformation in [HK03] (part (ii) of Theorem 9.5), we get that there exist a connected compact abelian group $V$, a cocycle $\rho_1 : Z_k \to V$, a measure preserving bijection $\phi : Z_{k+1} \to Z_k \times V$ that preserves $Z_k$ such that $T_1(\phi(x)) = \phi(T_1(x, v))$ for $y \in Z_k$, $v \in V$, and a measure preserving transformation $S_1 : V \to V$ such that

$$T_1'(y, v) = (S_1(y), v + \rho_1(y)).$$

For $i = 2, \ldots, l$, define $T_i' = \phi^{-1}T_i\phi$. Since both $\phi$ and $T_i$ preserve $Z_k$, we have that $T_i'$ has the form

$$T_i'(y, v) = (S_i(y), Q_i(y, v)),$$

for some measurable transformation $Q_i : Z_k \times V \to V$ for $i = 2, \ldots, l$. By Corollary 5.10 in [HK03] all maps $R_u : Z_k \times V \to Z_k \times V$ defined by $R_u(y, v) = (y, v + u)$ belong to the center of $G(T_i')$. By Proposition 3.1, $T_i' \in G(T_i')$ and so $T_i'$ commutes with $R_u$ for all $u \in V$. This can only happen if $Q_i$ has the form $Q_i(y, v) = v + \rho_i(y)$ for some measurable $\rho_i : Y \to V$. This completes the proof. \qed

Step 2. For $i = 1, \ldots, l$ define the coboundary operator $\partial_i$ by $\partial_i(f) = f \circ T_i - f$. If $U$ is a compact abelian group and $\rho_i : X \to U$ are cocycles, then the cocycle $\tilde{\rho} = (\rho_1, \ldots, \rho_l)$ is called an $l$-cocycle if

$$\partial_i \rho_j = \partial_j \rho_i,$$

for all $i, j \in \{1, \ldots, l\}$.

This is equivalent to saying that the maps $S_1, \ldots, S_l$ defined on $X \times U$ by $S_i(x, u) = (T_i x, u + \rho_i(x))$ commute.

If $U$ is a compact abelian group and $\rho_1, \ldots, \rho_l : X \to U$ are cocycles, then the cocycle $\tilde{\rho} = (\rho_1, \ldots, \rho_l)$ is an $l$-coboundary for the system $\langle X, \mu, T_1, \ldots, T_l \rangle$ if there exists a measurable function $f : X \to U$ such that $\rho_i = \partial_i f$ for $i = 1, \ldots, l$. Furthermore, $\tilde{\rho}$ is said to be an $l$-quasi coboundary for $\langle X, \mu, T_1, \ldots, T_l \rangle$ if there exists a measurable function $f : X \to U$ and $c_i \in U$ such that $\rho_i = c_i + \partial_i f$ for all $i = 1, \ldots, l$. Two $l$-cocycles are cohomologous if their difference is an $l$-coboundary.

For clarity of exposition, we include a few more definitions from [HK03]. Let $(X, \mu, T)$ be a measure preserving system and let $U$ be a compact abelian group. We say that the cocycle $\rho : X \to U$ is ergodic with respect to the system $(X, \mu, T)$ if the extension $(X \times U, \mu \times m_U, T_\rho)$, where $T_\rho : X \times U \to X \times U$ is given by $T_\rho(x, u) = (Tx, u + \rho(x))$, and $m_U$ is the Haar measure on $U$, is ergodic. An $l$-cocycle $\tilde{\rho} = (\rho_1, \ldots, \rho_l)$ is ergodic with respect to the system $(X, \mu, T_1, \ldots, T_l)$ if $\rho_i$ is ergodic with respect to $(X, \mu, T_i)$ for $i = 1, \ldots, l$.

For an integer $k \geq 1$ and $\epsilon \in V_k$, write $|\epsilon| = \epsilon_1 + \ldots + \epsilon_k$ and $s(\epsilon) = (-1)^{|\epsilon|}$. For each $k \geq 1$, we define the map $\Delta^k \rho : X^{[k]} \to U$ by

$$\Delta^k \rho(x) = \sum_{\epsilon \in V_k} s(\epsilon) \rho(x_\epsilon).$$
We say that the cocycle $\rho : X \to U$ is of type $k$ with respect to the system $(X, \mu, T)$ if the cocycle $\Delta^k \rho : X^k \to U$ is a coboundary of the system $(X^k, \mu^k, T^k)$. An $l$-cocycle $\tilde{\rho} : X \to U^l$ is said to be of type $k$ with respect to the system $(X, \mu, T_1, \ldots, T_l)$ if each coordinate cocycle is of type $k$.

Let $(Y, \mathcal{Y}, \nu)$ be a probability space, let $V$ be a compact abelian group with Haar measure $m_V$ and let $X = Y \times V$. The action $\{R_v : v \in V\}$ of measure preserving transformations $R_v : X \to X$ defined by $R_v(y, u) = (y, u + v)$ is called an action on $X$ by vertical rotations over $Y$.

Let $(X, \mathcal{X}, \mu)$ be a probability space, let $V$ be a connected compact abelian group and let $\{S_v : v \in V\}$ be an action of $V$ on $X$ by measure preserving transformations $S_v : X \to X$. The action $S_v$ is said to be free if there exists a probability space $(Y, \mathcal{Y}, \nu)$ and an action $R_v : Y \times V \to Y \times V$ by vertical rotations over $Y$ such that the actions $\{S_v : v \in V\}$ and $\{R_v : v \in V\}$ are isomorphic. This means that there exists a measurable bijection $\phi : Y \times V \to X$, mapping $v \times m_V$ to $\mu$ and satisfying $\phi(R_v(y, u)) = S_v(\phi(y, u))$ for all $y \in Y$ and all $v, u \in V$.

**Lemma 5.2.** Let $l \geq 1$ be an integer and let $T_1, \ldots, T_l$ be commuting ergodic measure preserving transformations of a probability space $(X, \mathcal{X}, \mu)$. Let $\{S_v : v \in V\}$ be a free action of a compact abelian group $V$ on $X$ that commutes with $T_i$ for $i = 1, \ldots, l$. Let $U$ be a finite dimensional torus and let $\tilde{\rho} = (\rho_1, \ldots, \rho_l) : X \to U^l$ be an $l$-cocycle of type $k$ for some integer $k \geq 2$. Then there exists a closed subgroup $V'$ of $V$ such that $V/V'$ is a compact abelian Lie group, and there exists an $l$-cocycle $\rho' = (\rho'_1, \ldots, \rho'_l)$, cohomologous to $\rho$, such that $\rho'_i \circ S_v = \rho'_i$ for every $v \in V'$.

**Proof.** As before, we define the operators $\partial_i$ by $\partial_i(f) = f \circ T_i - f$ for $i = 1, \ldots, l$ and define $\partial_v(f) = f \circ S_v - f$ for $v \in V$. Using the analogous result for a single transformation in [HK03] (Corollary 9.7), we get that for $i = 1, \ldots, l$ there exist closed subgroups $V_i$ of $V$ such that $V/V_i$ is a compact abelian Lie group, and measurable $f_i : X \to U$ such that $\tilde{\rho}_i = \rho_i + \partial_i f_i$ satisfies $\partial_v \tilde{\rho}_i = 0$ for all $v \in V_i$. If $W = \bigcap_{i=1}^l V_i$, then $V/W$ is a compact abelian Lie group and all the previous relations hold for $v \in W$. We take $V'$ to be the connected component of the identity element in $W$. For $i = 1, \ldots, l$ let $\rho'_i = \rho_i + \partial_i f_1$. Since $V/W$ is a compact abelian Lie group and $W/V'$ is finite, we have that $V/V'$ is also a compact abelian Lie group. It suffices to show that for $v \in V'$ we have $\partial_v \rho'_i = 0$ for all $i = 1, \ldots, l$.

Since $\partial_1 \rho_i = \partial_1 \rho_1$ and the operators $\partial_1$ commute, it follows that $\partial_1 \rho'_i = \partial_1 \rho'_1$. Moreover, since $S_v$ commutes with all the $T_i$, the operators $\partial_v$ and $\partial_1$ commute. It follows that

$$\partial_1 \partial_v \rho'_i = \partial_v \partial_1 \rho'_i = \partial_v \partial_1 \rho'_1 = \partial_1 \partial_v \rho'_1 = 0$$

for $v \in V'$, where the last equality holds since by assumption, $\partial_v \rho'_1 = 0$ for $v \in V'$. Since $\partial_1 \partial_v \rho'_1 = 0$ and $T_1$ is ergodic, we have that for $i = 1, \ldots, l$ and $v \in V'$ there exists a constant $c_{v,i} \in U$ such that $\partial_v \rho'_i = c_{v,i}$. It follows that for fixed $i$ the map $c_{v,i} : V' \to U$ is
a measurable homomorphism. Moreover, for \( i = 1, \ldots, l \) we have \( \rho'_i = \tilde{\rho}_i + \partial_i(f_1 - f_i) \), and \( \partial_v \tilde{\rho}_i = 0 \) for all \( v \in V' \). Hence, \( c_{v,i} = \partial_v \rho'_i = \partial_i g_i \) for all \( v \in V' \), where \( g_i = \partial_v(f_1 - f_i) \).

The spectrum of \( T_i \) is countable and so the last relation implies that \( c_{v,i} \) can only take on countably many values for \( v \in V' \). So \( c_{v,i} : V' \to U \) is a measurable homomorphism and takes on countably many values. Since \( V' \) is connected, it follows that \( c_{v,i} = 0 \) for \( i = 1, \ldots, l \) and \( v \in V' \).

Using the previous Lemma, the proof of the next result is identical to that of Lemma 10.4 in [HK03] and so we do not reproduce it.

**Lemma 5.3.** Let \( l \geq 1 \) be an integer, let \( T_1, \ldots, T_l \) be commuting ergodic measure preserving transformations of a probability space \((X, \mathcal{X}, \mu)\), let \( U \) be a finite dimensional torus, and let \( \tilde{\rho} : X \to U^l \) be an ergodic \( l \)-cocycle of type \( k \) and measurable with respect to \( Z_k \) for some integer \( k \geq 1 \). Assume that the system \((X, \mu, T_1, \ldots, T_l)\) is an inverse limit of the sequence of systems \( \{(X_i, \mu_i, T_1, \ldots, T_l)\}_{i \in \mathbb{N}} \). Then \( \tilde{\rho} \) is cohomologous to a cocycle \( \tilde{\rho}' : X \to U^l \), which is measurable with respect to \( X_i \) for some \( i \).

**Step 3.** We complete the proof of Theorem 4.1 by using induction on \( k \). If \( k = 1 \) we can assume that \((X, \mu, T_1)\) is an ergodic rotation on a compact abelian group \( V \). Since \( T_i \) commutes with \( T_1 \) for \( i = 1, \ldots, l \), it follows that each \( T_i \) is also a rotation on \( V \). A compact abelian group is a Lie group if and only if its dual is finitely generated. Hence, every compact abelian group is an inverse limit of compact abelian Lie groups and the result follows.

Suppose that the result holds for some integer \( k \geq 1 \). Assume that \((X, \mu, T_1, \ldots, T_l)\) is a system of order \( k + 1 \). By Lemma 5.1, we get that the system \((X, \mu, T_1, \ldots, T_l)\) is an extension of \((Z_k, \mu_k, T_1, \ldots, T_l)\) by a connected compact abelian group \( V \). Thus we can assume that \( X = Z_k \times \tilde{\rho} V \) where \( \tilde{\rho} = (\rho_1, \ldots, \rho_l) : Z_k \to V^l \) is the \( l \)-cocycle defining the extension. The cocycle \( \rho \) is an ergodic \( l \)-cocycle since every system \((X, \mu, T_i)\) is. Moreover, since \((X, \mu, T_i)\) and \((Z_k, \mu_k, T_i)\) are systems of order \( k + 1 \), by Corollary 7.7 in [HK03] the cocycle \( \rho_i \) is of type \( k + 1 \) for \( i = 1, \ldots, l \). Hence, \( \tilde{\rho} \) is an \( l \)-cocycle of type \( k + 1 \).

Since \( V \) is a connected compact abelian group it can be written as an inverse limit of finite dimensional tori \( V_j \). Let \( \tilde{\rho}_j : Z_k \to V_j^l \) be the projection of \( \tilde{\rho} \) on the quotient \( V_j \) of \( V \). By the inductive hypothesis, \((Z_k, \mu_k, T_1, \ldots, T_l)\) can be written as an inverse limit of toral systems \((Z_{k,i}, \mu_{k,i}, T_1, \ldots, T_l)\). By Lemma 5.3, for every integer \( j \) there exist an integer \( i_j \), and an \( l \)-cocycle \( \tilde{\rho}'_j : Y \to V_j^l \) cohomologous to \( \tilde{\rho}_i \) and measurable with respect to \( Z_{k,i,j} \). Without loss of generality, we can assume that the sequence \( i_j \) is increasing. Let \( X_j = Z_k \times V_j \). Then the system \((X, \mu, T_1, \ldots, T_l)\) is isomorphic to the toral system \((X_j, \mu_j, T_1, \ldots, T_l)\). Since \((X, \mu, T_1, \ldots, T_l)\) is an inverse limit of the sequence \( \{(X_j, \mu_j, T_1, \ldots, T_l)\}_{j \in \mathbb{N}} \), the proof is complete.
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References


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