## Provided for non-commercial research and education use. Not for reproduction, distribution or commercial use.



This article appeared in a journal published by Elsevier. The attached copy is furnished to the author for internal non-commercial research and education use, including for instruction at the authors institution and sharing with colleagues.

Other uses, including reproduction and distribution, or selling or licensing copies, or posting to personal, institutional or third party websites are prohibited.

In most cases authors are permitted to post their version of the article (e.g. in Word or Tex form) to their personal website or institutional repository. Authors requiring further information regarding Elsevier's archiving and manuscript policies are encouraged to visit:
http://www.elsevier.com/copyright

# A remark on the porous medium equation with nonlinear source 

Alkis S. Tersenov<br>Department of Mathematics, University of Crete, 71409 Heraklion - Crete, Greece

## ARTICLE INFO

## Article history:

Received 7 April 2010
Received in revised form 1 July 2011
Accepted 27 September 2011

## Keywords:

Slow diffusion equation
A priori estimates


#### Abstract

In the present paper, we obtain a new a priori estimate of the solution of the initialboundary value problem for the porous medium equation with nonlinear source and formulate the conditions guaranteeing the global solvability of this problem.


© 2011 Elsevier Ltd. All rights reserved.

## 1. Introduction and formulation of the result

Consider the following parabolic equation

$$
\begin{equation*}
u_{t}-\Delta u^{q}=k(t, \mathbf{x}) u^{p} \quad \text { in } Q_{T}=(0, T) \times \Omega, \Omega \subset \mathbf{R}^{n}, T>0 \tag{1.1}
\end{equation*}
$$

where $q>1, p>0,0 \leq k(t, \mathbf{x}) \leq \kappa$, coupled with initial and boundary conditions

$$
\begin{equation*}
\left.u\right|_{\Gamma_{T}}=\left.\phi\right|_{\Gamma_{T}} \geq 0, \quad \Gamma_{T}=\Omega \cup[0, T] \times \partial \Omega \tag{1.2}
\end{equation*}
$$

which imply that $u \geq 0$ in $Q_{T}$. This equation appears in different applications (see [1-3] and the references therein). It is well known $[4-6,1,7]$ that solutions of this problem may blow-up in finite time. The global solvability (i.e. for arbitrary $T>0$ ) was proved in [5] for $k \equiv 1$ and homogeneous boundary conditions in the following three cases (see also [1]):
if $q>p$;
if $q=p$ and the first eigenvalue of the problem $\Delta u=-\lambda u$ in $\Omega,\left.u\right|_{\partial \Omega}=0$ is greater than 1 ;
if $q<p$ and $\phi$ satisfies smallness type restrictions, for $n \geq 3$ the additional restriction $p \in\left(q, q \frac{n+2}{n-2}\right)$ is required.
In [4], the global solvability of problem (1.1), (1.2) with homogeneous boundary conditions in the one dimensional case ( $n=1, x \in(0,1)$ ) was proved under the similar assumptions, namely:
if $q>p$;
if $q=p$ and $\kappa$ is sufficiently small;
if $q<p$ and $\phi$ satisfies the smallness type restrictions.
(Note that in [4] more general equation $u_{t}=\left[h(u)_{x}+\varepsilon g(u)\right]_{x}+k f(u)$ was considered.)
The goal of the present paper is to obtain a new a priori estimate of the solution and to propose slightly different conditions guaranteeing the global solvability.

For simplicity, in order to work with classical solution, we suppose that

$$
\begin{equation*}
\left.u\right|_{\Gamma_{T}}=\left.\phi\right|_{\Gamma_{T}}>0 \tag{1.3}
\end{equation*}
$$

[^0]which implies that $u>0$ in $Q_{T}$. Assume that $\phi$ is continuous and $k$ is a continuously differentiable function. The domain $\Omega$ satisfies the exterior sphere condition and
$$
\Omega \subset\left\{\mathbf{x}:\left|x_{i}\right| \leq l_{i}, i=1, \ldots, n\right\}
$$
without loss of generality suppose that $l_{1}=\min _{i}\left\{l_{i}\right\}$. Define the constant $K$ by the following
$$
K=\max \left\{\left(\frac{\kappa}{q} l_{1}^{2(p-q+1)} 2^{2-p-q} \frac{(4 q-3)^{p}}{(q-1)^{q-1}}\right)^{\frac{1}{q-p}}, \frac{m}{2 l_{1}^{2}(q-1)}\right\}, \quad \text { for } q \neq p
$$
and
$$
K=\frac{m}{2 l_{1}^{2}(q-1)} \quad \text { for } q=p
$$
where
$$
m=\left.\max \phi\right|_{\Gamma_{\mathrm{T}}}
$$

Theorem. There exists a global classical solution of (1.1), (1.3) satisfying the estimate

$$
\begin{equation*}
0<u(t, \mathbf{x}) \leq \frac{l_{1}^{2}}{2}(4 q-3) K \quad \forall \mathbf{x} \in \Omega \text { and } t \geq 0 \tag{1.4}
\end{equation*}
$$

in the following three cases:

1. if $q>p$;
2. if $q=p$ and

$$
l_{1}^{2} \leq \frac{q}{\kappa} \frac{(4 q-4)^{q-1}}{(4 q-3)^{q}}
$$

3. if $q<p$ and

$$
m \leq 2 l_{1}^{2}(q-1)\left(\frac{\kappa}{q} l_{1}^{2(p-q+1)} 2^{2-p-q} \frac{(4 q-3)^{p}}{(q-1)^{q-1}}\right)^{\frac{1}{q-p}}
$$

Remark. In the case $q=p$ the smallness restriction on the size of the domain is only in one direction and estimate (1.4) takes the form

$$
0<u(t, \mathbf{x}) \leq \frac{4 q-3}{4 q-4} m
$$

In the case $q<p$ we do not need any additional restrictions on $p$ for $n \geq 3$.

## 2. Proof of the Theorem

Rewrite Eq. (1.1) in the following form

$$
\begin{equation*}
u_{t}=q u^{q-1} \Delta u+q(q-1) u^{q-2}|\nabla u|^{2}+k(t, \mathbf{x}) u^{p} \tag{2.1}
\end{equation*}
$$

Consider the auxiliary equation

$$
\begin{equation*}
u_{t}-q u^{q-1} \Delta u=q(q-1) u^{q-2}|\nabla u|^{2}+k(t, \mathbf{x}) g(u) \tag{2.2}
\end{equation*}
$$

where

$$
g(u)= \begin{cases}u^{p}, & \text { if } u \leq \frac{1}{2} l_{1}^{2}(4 q-3) K \\ \left(\frac{1}{2} l_{1}^{2}(4 q-3) K\right)^{p}, & \text { if } u>\frac{1}{2} l_{1}^{2}(4 q-3) K\end{cases}
$$

The existence of a classical solution of problem (2.2), (1.3) follows from the standard theory (see, for example, [8]). Our goal is to obtain the a priori estimate $u \leq \frac{l_{1}^{2}}{2}(4 q-3) K$ for the solution of problem (2.2), (1.3) and by this to show that Eqs. (2.2) and (2.1) coincide.

Consider the function

$$
h\left(x_{1}\right)=\frac{K}{2}\left(l_{1}^{2}-x_{1}^{2}\right)+2 l_{1}^{2}(q-1) K .
$$

For $v(t, \mathbf{x}) \equiv u(t, \mathbf{x})-h\left(x_{1}\right)$ we have

$$
\begin{aligned}
v_{t}-q u^{q-1} \Delta v & =q(q-1) u^{q-2}|\nabla u|^{2}+k(t, \mathbf{x}) g(u)+q u^{q-1} h^{\prime \prime} \\
& =q(q-1) u^{q-2}|\nabla u|^{2}+k(t, \mathbf{x}) g(u)-q u^{q-1} K
\end{aligned}
$$

Assume that the function $v$ attains its positive maximum at the point $N \in \bar{Q}_{T} \backslash \Gamma_{T}$, at this point $v>0$ and $\nabla v=0$, i.e.

$$
u>h \geq 2 l_{1}^{2}(q-1) K, \quad u_{x_{1}}=h^{\prime}=-K x_{1}, \quad u_{x_{i}}=0 \quad \text { for } i=2, \ldots, n .
$$

Thus we have

$$
\begin{aligned}
v_{t}-\left.q u^{q-1} \Delta v\right|_{N} & =q(q-1) u^{q-2}\left(-K x_{1}\right)^{2}+k(t, \mathbf{x}) g(u)-\left.q u^{q-1} K\right|_{N} \\
& <q(q-1) u^{q-2} K^{2} l_{1}^{2}+\kappa\left(\frac{l_{1}^{2}}{2}(4 q-3) K\right)^{p}-\left.q u^{q-1} K\right|_{N} \\
& =\left(q(q-1) u^{q-2} K^{2} l_{1}^{2}-\frac{q}{2} u^{q-1} K\right)+\left.\left(\kappa\left[\frac{l_{1}^{2}}{2}(4 q-3) K\right]^{p}-\frac{q}{2} u^{q-1} K\right)\right|_{N} \\
& <\frac{q}{2} u^{q-2} K\left(2 l_{1}^{2}(q-1) K-u\right)+\left.\left(\kappa\left[\frac{l_{1}^{2}}{2}(4 q-3) K\right]^{p}-\frac{q}{2}\left[2 l_{1}^{2}(q-1) K\right]^{q-1} K\right)\right|_{N} \\
& <K^{p}\left[\kappa\left(\frac{l_{1}^{2}}{2}(4 q-3)\right)^{p}-\frac{q}{2}\left(2 l_{1}^{2}(q-1)\right)^{q-1} K^{q-p}\right] \leq 0 .
\end{aligned}
$$

Hence we obtain that $v_{t}-\left.q u^{q-1} \Delta v\right|_{N}<0$ which is impossible. Taking into account the fact that $v \leq 0$ on $\Gamma_{T}$ we conclude that

$$
u(t, \mathbf{x}) \leq h\left(x_{1}\right) \leq h(0)=\frac{l_{1}^{2}}{2}(4 q-3) K
$$

The inequality

$$
\begin{equation*}
\kappa\left(\frac{l_{1}^{2}}{2}(4 q-3)\right)^{p}-\frac{q}{2}\left(2 l_{1}^{2}(q-1)\right)^{q-1} K^{q-p} \leq 0 \tag{2.3}
\end{equation*}
$$

for $q>p$ follows directly from the definition of $K$, for $q=p$ it follows from the restriction on $l_{1}$. If $q<p$ then (2.3) takes the form

$$
K^{p-q} \leq \frac{q}{2}\left(2 l_{1}^{2}(q-1)\right)^{q-1}\left[\kappa\left(\frac{l_{1}^{2}}{2}(4 q-3)\right)^{p}\right]^{-1}
$$

which is fulfilled if

$$
\frac{m}{2 l_{1}^{2}(q-1)} \leq\left(\frac{\kappa}{q} l_{1}^{2(p-q+1)} 2^{2-p-q} \frac{(4 q-3)^{p}}{(q-1)^{q-1}}\right)^{\frac{1}{q-p}}
$$

## References

[1] A.A. Samarskii, V.A. Galaktionov, S.P. Kurdyumov, A.P. Mikhailov, Blow-Up in Quasilinear Parabolic Equations, in: de Gruyter Expositions in Mathematics, vol. 19, de Gruyter, Berlin, 1995, p. 535.
[2] B. Straughan, Stability and Wave Motion in Porous Media, in: Applied Mathematical Sciences, vol. 165, Springer, New York, 2008, p. 437.
[3] J.L. Vazquez, The porous medium equation, in: Mathematical Theory, in: Oxford Mathematical Monographs, The Clarendon Press, Oxford University Press, Oxford, 2007, p. 624.
[4] J.R. Anderson, K. Deng, Global existence for nonlinear diffusion equations, J. Math. Anal. Appl. 196 (2) (1995) 479-501.
[5] V.A. Galaktionov, A boundary value problem for the nonlinear parabolic equation $u_{t}=\Delta u^{\sigma+1}+u^{\beta}$, Differ. Equ. 17 (5) (1981) $551-555$.
[6] H.A. Levine, P.E. Sacks, Some existence and nonexistence theorems for solutions of degenerate parabolic equations, J. Differential Equations 52 (2) (1984) 135-161.
[7] M. Tsutsumi, Existence and nonexistence of global solutions for nonlinear parabolic equations, Publ. Res. Inst. Math. Sci. 8 (1972) 211-229.
[8] O.A. Ladyzhenskaja, V.A. Solonnikov, N.N. Ural'ceva, Linear and Quasilinear Equations of Parabolic Type, in: Translations of Mathematical Monographs, vol. 23, American Math. Society, Providence, R.I, 1967, p. 648.


[^0]:    E-mail address: tersenov@math.uoc.gr.

