# Existence of Lipschitz continuous solutions to the Cauchy-Dirichlet problem for anisotropic parabolic equations 

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#### Abstract

The Cauchy-Dirichlet and the Cauchy problem for the degenerate and singular quasilinear anisotropic parabolic equations are considered. We show that the time derivative $u_{t}$ of a solution $u$ belongs to $L_{\infty}$ under a suitable assumption on the smoothness of the initial data. Moreover, if the domain satisfies some additional geometric restrictions, then the spatial derivatives $u_{x_{i}}$ belong to $L_{\infty}$ as well. In the singular case we show that the second derivatives $u_{x_{i} x_{j}}$ of a solution of the Cauchy problem belong to $L_{2}$.


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## 1. Introduction and main results

Let $\Omega$ be a bounded domain in $\mathbf{R}^{n}$ satisfying the exterior sphere condition and $\Omega_{T}=$ $(0, T) \times \Omega$ with an arbitrary $T \in(0, \infty)$. We denote by $x=\left(x_{1}, \ldots, x_{n}\right)$ the points in

[^0]$\Omega$ and by $t$ the time variable that varies in the interval $[0, T]$. Consider the following quasilinear parabolic equation
\[

$$
\begin{equation*}
u_{t}=\sum_{i=1}^{n}\left(\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i}}\right)_{x_{i}} \text { in } \Omega_{T}, \tag{1.1}
\end{equation*}
$$

\]

coupled with the homogeneous Dirichlet boundary condition

$$
\begin{equation*}
u=0 \quad \text { on }[0, T] \times \partial \Omega \tag{1.2}
\end{equation*}
$$

and the initial condition

$$
\begin{equation*}
u(0, x)=u_{0}(x) \text { in } \Omega, u_{0}(x) \in C^{2}(\Omega) \text { and } u_{0}(x)=0 \text { on } \partial \Omega . \tag{1.3}
\end{equation*}
$$

Here $p_{i}>-1, i=1, \ldots, n$. Without loss of generality, we assume that the $p_{i}$ are ordered:

$$
-1<p_{1} \leq p_{2} \leq \ldots \leq p_{n}<+\infty .
$$

Let $-1<p_{i}<0$ for $i=1, \ldots, m$ and $p_{i} \geq 0$ for $i=m+1, \ldots, n$ where $0 \leq m \leq n$.
This class of equations has received considerable attention in the last years and not only, see, for example, $[1-5,10-13,22,23]$ and the references therein. Concerning the different aspects of the stationary case, see, for example, [6,7,17,22,23]. From [13] it follows that if $u_{0} \in L_{\infty}(\Omega)$, then there exists a unique weak solution of problem (1.1)-(1.3) which is defined as a function

$$
u \in L_{\infty}\left(\Omega_{T}\right) \cap V\left(\Omega_{T}\right) \cap C\left([0, T] ; L_{s}(\Omega)\right) \quad \forall s \in[1, \infty), \quad u_{t} \in V^{*}\left(\Omega_{T}\right)
$$

satisfying the integral identity

$$
\int_{\Omega_{T}}\left(u \phi_{t}-\sum_{i=1}^{n}\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i}} \phi_{x_{i}}\right) d x d t=-\int_{\Omega} u_{0} \phi(0, x) d x
$$

for an arbitrary smooth function $\phi(t, x)$ which is equal to zero for $x \in \partial \Omega$ and for $t=T$. Here $V^{*}\left(\Omega_{T}\right)$ is the adjoint space to $V\left(\Omega_{T}\right)=\cap_{i=1}^{n} L_{p_{i}+2}\left(0, T ; U_{i}(\Omega)\right)$ where $U_{i}(\Omega)$ is the closure of $C_{\infty}^{0}(\Omega)$ with respect to the norm $\|u\|_{U_{i}}=\|u\|_{L_{2}}+\left\|u_{x_{i}}\right\|_{L_{p_{i}+2}}$ (for more details see [13]).

The main goal of the present paper is to show that under the following assumption on the initial data $u_{0}$ :

$$
\begin{equation*}
\sum_{i=1}^{n} \max _{\Omega}\left|\left(\left|u_{0 x_{i}}\right|^{p_{i}} u_{0 x_{i}}\right)_{x_{i}}\right|<+\infty \tag{1.4}
\end{equation*}
$$

the derivative of a solution with respect to $t$ is an $L_{\infty}$ function. The proof is based on the idea of introducing a new time variable inspired by the idea of introducing a new
spatial variable. The last was proposed by Kruzhkov [8] in his investigations devoted to the second order quasilinear parabolic equations with one spatial variable. Based on this idea he obtained the estimate of the low order spatial derivative of a solution of initial boundary value problems. Later the idea of introducing a new spatial variable was modified and applied to a wide class of multidimensional quasilinear parabolic and elliptic equations $[14,15,17]$ (see also $[16,18]$ ).

It must be emphasized that the method we use does not require differentiation of the equation and can be applied to more general operator (for more details see remarks at the end of sections 2, 3). We restrict ourselves with equation (1.1) in order to avoid complicated assumptions and to make the idea as simple as possible.

Definition 1. We say that a function $u(t, x)$ is a weak solution of problem (1.1)-(1.3) if

$$
u \in L_{\infty}\left(\Omega_{T}\right), \quad u_{x_{i}} \in L_{p_{i}+2}\left(\Omega_{T}\right), \quad u_{t} \in L_{\infty}\left(\Omega_{T}\right)
$$

and the following integral identity

$$
\int_{\Omega_{T}}\left(u_{t} \phi+\sum_{i=1}^{n}\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i}} \phi_{x_{i}}\right) d x d t=0
$$

holds for an arbitrary smooth function $\phi$ which vanishes on $(0, T) \times \partial \Omega$. The initial condition is satisfied in the classical sense. The boundary condition is satisfied in the sense of the trace of function.

Theorem 1. Suppose that condition (1.4) is fulfilled and $\Omega$ satisfies the exterior sphere condition. Then for an arbitrary $T>0$, there exists a unique weak solution of problem (1.1)-(1.3). Moreover

$$
\left\|u_{t}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{0}=\sum_{i=1}^{n} \max _{\Omega}\left|\left(\left|u_{0 x_{i}}\right|^{p_{i}} u_{0 x_{i}}\right)_{x_{i}}\right| .
$$

Let us turn to the gradient estimates. The case

$$
0 \leq \min _{i} p_{i} \leq \max _{i} p_{i}<\min _{i} p_{i}+\frac{4}{n+2}
$$

was considered in [3], where the existence result for the Cauchy-Dirichlet problem with inhomogeneous initial-boundary data was proved under the above restriction on the exponents $p_{i}$. The obtained weak solution possess locally Lipschitz gradient with $u_{t} \in$ $L^{\frac{p}{q-1}}\left(0, T ; W^{-1, \frac{p}{q-1}}(\Omega)\right.$, where $p=\min p_{i}, q=\max p_{i}$. Moreover in [3] the following regularity result was established: if

$$
0 \leq \min _{i} p_{i} \leq \max _{i} p_{i}<\min _{i} p_{i}+\frac{4}{n}
$$

then any weak solution $u \in L^{p}\left(0, T ; W^{1, p}(\Omega)\right) \cap L_{l o c}^{q}\left(0, T ; W_{l o c}^{1, q}(\Omega)\right)$ admits a locally bounded spatial gradient $\nabla u$. Taking into account the fact that the equation under consideration is nonuniformly parabolic, we can not expect the global $L_{\infty}$ gradient estimate for arbitrary domains, but we show that for some classes of domains $\Omega$ the global gradient estimate takes place for arbitrary $p_{i}>-1, i=1, \ldots, n$.

Concerning the additional restriction on $\Omega$ we suppose that either it is orthogonal parallelepiped

$$
\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)
$$

or it satisfies the following $(A)$ condition
$\Omega$ is convex and the parts of $\partial \Omega$ lying in the half spaces $x_{i} \leq 0$ and $x_{i} \geq 0$ can be expressed as

$$
\begin{equation*}
x_{i}=F_{i} \quad \text { and } \quad x_{i}=G_{i}, \quad i=1, \ldots, n, \tag{A}
\end{equation*}
$$

respectively, where the $C^{2}$-functions $F_{i}$ and $G_{i}$ do not depend on variable $x_{i}$.

For example

$$
\Omega=\left\{x \in \mathbf{R}^{n}: \sum_{i=1}^{n} \frac{x_{i}^{2}}{\alpha_{i}^{2}}<1\right\}, \quad \alpha_{i} \in \mathbf{R} \backslash\{0\}, \quad i=1, \ldots, n .
$$

Theorem 2. Assume that condition (1.4) is fulfilled and $\Omega$ satisfies assumption $(A)$ or $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$. Then for an arbitrary $T>0$, there exists a unique weak solution of problem (1.1)-(1.3) such that $u_{x_{i}} \in L_{\infty}\left(\Omega_{T}\right)$. Moreover

$$
\left\|u_{t}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{0}, \quad\left\|u_{x_{i}}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{i}=\max _{\Omega}\left|u_{0 x_{i}}\right|, \quad i=1, \ldots, n
$$

(This implies that $u$ is continuous and so conditions (1.2), (1.3) are satisfied in the classical sense.)

If $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$ and the equation is singular, i.e. $p_{i} \in(-1,0) \forall i$, then the solution of the Cauchy-Dirichlet problem is more regular than in Theorem 2.

Definition 2. We say that a Lipschitz continuous function $u(t, x)$ is a strong solution of problem (1.1)-(1.3) if $u_{x_{i} x_{j}} \in L_{2}\left(\Omega_{T}\right), u(t, x)$ satisfies equation

$$
u_{t}=\sum_{i=1}^{n}\left(1+p_{i}\right)\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i} x_{i}}
$$

almost everywhere in $\Omega_{T}$ and the initial and boundary conditions are satisfied in the classical sense.

Theorem 3. Assume that condition (1.4) is fulfilled, $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$ and $-1<p_{1} \leq p_{2} \leq \ldots \leq p_{n}<0$. Then for an arbitrary $T>0$, there exists a unique strong solution of problem (1.1)-(1.3). Moreover

$$
\begin{gathered}
\left\|u_{t}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{0}, \quad\left\|u_{x_{i}}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{i} \\
\left\|u_{x_{i} x_{j}}\right\|_{L_{2}\left(\Omega_{T}\right)}^{2} \leq \frac{1}{2\left(p_{i}+1\right)} K_{i}^{2} C_{i}^{-p_{i}}, \quad K_{i}=\left\|u_{0 x_{i}}\right\|_{L_{2}(\Omega)}, \quad i, j=1, \ldots, n
\end{gathered}
$$

Now let us turn to the Cauchy problem: consider the equation

$$
\begin{equation*}
u_{t}=\sum_{i=1}^{n}\left(\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i}}\right)_{x_{i}} \text { in } \Pi_{T}=(0, T) \times \mathbf{R}^{n} \tag{1.5}
\end{equation*}
$$

coupled with the initial condition

$$
\begin{equation*}
u(0, x)=u_{0}(x) \text { in } \mathbf{R}^{n} . \tag{1.6}
\end{equation*}
$$

Suppose that $u_{0}(x)$ has a compact support which we denote by $\Omega$.
Definition 3. We say that a globally Lipschitz continuous function $u(t, x)$ is a weak solution of problem (1.5), (1.6) if $u(0, x)=u_{0}(x)$ and the following integral identity

$$
\int_{\Pi_{T}}\left(u_{t} \phi+\sum_{i=1}^{n}\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i}} \phi_{x_{i}}\right) d x d t=0
$$

holds for an arbitrary smooth function $\phi$ with compact support.

Theorem 4. Suppose that condition (1.4) is satisfied. Then for an arbitrary $T>0$, there exists a unique weak solution of problem (1.5), (1.6). Moreover

$$
\begin{aligned}
& \left\|u_{x_{i}}\right\|_{L_{\infty}\left(\Pi_{T}\right)} \leq C_{i}=\max _{\Omega}\left|u_{0 x_{i}}\right|, \quad i=1, \ldots, n \\
& \left\|u_{t}\right\|_{L_{\infty}\left(\Pi_{T}\right)} \leq C_{0}=\sum_{i=1}^{n} \max _{\Omega}\left|\left(\left|u_{0 x_{i}}\right|^{p_{i}} u_{0 x_{i}}\right)_{x_{i}}\right| .
\end{aligned}
$$

Definition 4. We say that a globally Lipschitz continuous function $u(t, x)$ is a strong solution of problem (1.5), (1.6) if $u_{x_{i} x_{j}} \in L_{2}\left(\Pi_{T}\right), u(0, x)=u_{0}(x)$ and $u(t, x)$ satisfies equation

$$
u_{t}=\sum_{i=1}^{n}\left(1+p_{i}\right)\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i} x_{i}}
$$

almost everywhere in $\Pi_{T}$.

Theorem 5. Suppose that (1.4) is fulfilled and assume that $-1<p_{1} \leq p_{2} \leq \ldots \leq p_{n}<0$. Then for an arbitrary $T>0$, there exists a unique strong solution of problem (1.5), (1.6). Moreover

$$
\left\|u_{x_{i}}\right\|_{L_{\infty}\left(\Pi_{T}\right)} \leq C_{i}, \quad\left\|u_{t}\right\|_{L_{\infty}\left(\Pi_{T}\right)} \leq C_{0}
$$

and

$$
\left\|u_{x_{i} x_{j}}\right\|_{L_{2}\left(\Pi_{T}\right)}^{2} \leq \frac{1}{2\left(p_{i}+1\right)} K_{i}^{2} C_{i}^{-p_{i}}, \quad K_{i}=\left\|u_{0 x_{i}}\right\|_{L_{2}(\Omega)}, \quad i, j=1, \ldots, n
$$

The paper is organized as follows. In sections 2, 3, 4 we prove Theorems 1, 2, 3 respectively, section 5 is devoted to Theorems 4,5 .

## 2. Proof of Theorem 1

### 2.1. Regularization

Regularize equation (1.1):

$$
\begin{equation*}
u_{\varepsilon t}=\sum_{i=1}^{n}\left(\left(u_{\varepsilon x_{i}}^{\alpha}+\varepsilon\right)^{p_{i} / \alpha} u_{\varepsilon x_{i}}\right)_{x_{i}} \text { in } \Omega_{T} \tag{2.1}
\end{equation*}
$$

where constant $\varepsilon \in\left(0, \varepsilon_{0}\right], \varepsilon_{0}>0$ is an arbitrary fixed number and $\alpha \in(0,1)$ is a constant such that $\alpha=r / \rho$ with positive integers $r$ and $\rho$, where $r<\rho$ and $r$ is even.

Note that for such $\alpha$

$$
\left(z^{\alpha}\right)^{p_{i} / \alpha}=|z|^{p_{i}}
$$

If $0<m \leq n$ (i.e. there exists at least one negative $p_{i}$ ) then we impose an additional condition on $\alpha$ : $\alpha$ is small enough so that

$$
\begin{equation*}
-1 \leq p_{i}-\alpha \text { for } i=1, \ldots, m \tag{2.2}
\end{equation*}
$$

We will use this condition below in the proof of Lemma 2.1.
Introduce functions $a_{i \varepsilon}\left(z_{i}\right)$

$$
a_{i \varepsilon}\left(z_{i}\right)=\left(z_{i}^{\alpha}+\varepsilon\right)^{\frac{p_{i}}{\alpha}-1}\left(\left(p_{i}+1\right) z_{i}^{\alpha}+\varepsilon\right) .
$$

Taking into account that

$$
\left(\left(u_{\varepsilon x_{i}}^{\alpha}+\varepsilon\right)^{p_{i} / \alpha} u_{\varepsilon x_{i}}\right)_{x_{i}}=\left(u_{\varepsilon x_{i}}^{\alpha}+\varepsilon\right)^{\frac{p_{i}}{\alpha}-1}\left(\left(p_{i}+1\right) u_{\varepsilon x_{i}}^{\alpha}+\varepsilon\right) u_{\varepsilon x_{i} x_{i}},
$$

we rewrite equation (2.1) in the following form

$$
\begin{equation*}
u_{\varepsilon t}=\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{\varepsilon x_{i}}\right) u_{\varepsilon x_{i} x_{i}} \text { in } \Omega_{T} \tag{2.3}
\end{equation*}
$$

Consider equation (2.3) coupled with conditions

$$
\begin{equation*}
u_{\varepsilon}=0 \quad \text { on }[0, T] \times \partial \Omega, \quad u_{\varepsilon}(0, x)=u_{0}(x) \text { in } \Omega . \tag{2.4}
\end{equation*}
$$

The existence of a classical solution $u_{\varepsilon}$ of problem (2.3), (2.4) follows from [13] (see p. 3024).

### 2.2. A priori estimates

Our goal in this section is to obtain uniform with respect to $\varepsilon$ estimates of solutions to (2.3), (2.4) which would enable us to pass to the limit as $\varepsilon \rightarrow 0$.

Denote by

$$
C\left(\varepsilon_{0}\right)=\sum_{i=1}^{m} \max _{\Omega}\left|\left(\left|u_{0 x_{i}}\right|^{p_{i}} u_{0 x_{i}}\right)_{x_{i}}\right|+\sum_{i=m+1}^{n} \max _{\Omega}\left|\left(\left(u_{0 x_{i}}^{\alpha}+\varepsilon_{0}\right)^{p_{i} / \alpha} u_{0 x_{i}}\right)_{x_{i}}\right| .
$$

For simplicity in the proofs we will omit the subindex $\varepsilon$.

Lemma 2.1. For every $\varepsilon \in\left(0, \varepsilon_{0}\right]$ and $(t, x) \in \bar{Q}_{T}$ the following estimate

$$
\left|u_{\varepsilon}(t, x)-u_{0}(x)\right| \leq C\left(\varepsilon_{0}\right) t
$$

takes place.

Proof. First let us show that

$$
\begin{equation*}
C\left(\varepsilon_{0}\right) \geq\left|\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right| \tag{2.5}
\end{equation*}
$$

To this end consider $\left|a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right|, i=1, \ldots, n$. We have

$$
\left|a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right|=\left(u_{0 x_{i}}^{\alpha}+\varepsilon\right)^{\frac{p_{i}}{\alpha}-1}\left[\left(p_{i}+1\right) u_{0 x_{i}}^{\alpha}+\varepsilon\right]\left|u_{0 x_{i} x_{i}}\right| \equiv f(\varepsilon, x) .
$$

By direct calculations we obtain

$$
\begin{equation*}
\frac{\partial f(\varepsilon, x)}{\partial \varepsilon}=\left(u_{0 x_{i}}^{\alpha}+\varepsilon\right)^{\frac{p_{i}}{\alpha}-2}\left(\frac{p_{i}}{\alpha} \varepsilon+p_{i} \frac{p_{i}+1-\alpha}{\alpha} u_{0 x_{i}}^{\alpha}\right)\left|u_{0 x_{i} x_{i}}\right| . \tag{2.6}
\end{equation*}
$$

Consequently $\partial f / \partial \varepsilon \geq 0$ for $p_{i} \geq 0$. Thus for $p_{i} \geq 0$ the function $\left|a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right|$ is increasing with respect to $\varepsilon$ for arbitrary $x$ and as a consequence $\max _{\Omega}\left|a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right|$ is increasing with respect to $\varepsilon$ as well. Hence

$$
\begin{aligned}
\left|\sum_{i=m+1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right| & \leq \sum_{i=m+1}^{n} \max _{\Omega}\left|\left(\left(u_{0 x_{i}}^{\alpha}+\varepsilon\right)^{p_{i} / \alpha} u_{0 x_{i}}\right)_{x_{i}}\right| \\
& \leq \sum_{i=m+1}^{n} \max _{\Omega}\left|\left(\left(u_{0 x_{i}}^{\alpha}+\varepsilon_{0}\right)^{p_{i} / \alpha} u_{0 x_{i}}\right)_{x_{i}}\right|
\end{aligned}
$$

From (2.6) we have that $\partial f / \partial \varepsilon \leq 0$ for $-1<p_{i}<0$ (see (2.2)). So we conclude that for negative $p_{i}$ the function $\left|a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right|$ is decreasing with respect to $\varepsilon$ for arbitrary $x$ an as a consequence $\max _{\Omega}\left|a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right|$ is decreasing with respect to $\varepsilon$ as well. Thus

$$
\left|\sum_{i=1}^{m} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}\right| \leq \sum_{i=1}^{m} \max _{\Omega}\left|\left(\left(u_{0 x_{i}}^{\alpha}+\varepsilon\right)^{p_{i} / \alpha} u_{0 x_{i}}\right)_{x_{i}}\right| \leq \sum_{i=1}^{m} \max _{\Omega}\left|\left(\left|u_{0 x_{i}}\right|^{p_{i}} u_{0 x_{i}}\right)_{x_{i}}\right|
$$

and (2.5) is proved.
Introduce the function

$$
h(t)=\left(C\left(\varepsilon_{0}\right)+\delta\right) t, \quad t \in[0, T],
$$

where constant $\delta>0$. Let us prove the following inequality

$$
\begin{equation*}
u(t, x)-u_{0}(x) \leq h(t) \tag{2.7}
\end{equation*}
$$

Consider the linear parabolic operator

$$
L \equiv \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) \frac{\partial^{2}}{\partial x_{i}^{2}}-\frac{\partial}{\partial t} .
$$

Define the function $\phi^{-} \equiv u-\left[u_{0}(x)+h(t)\right]$. Obviously

$$
\begin{align*}
L \phi^{-} & =\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-u_{t}-\left[\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}-h^{\prime}(t)\right] \\
& =\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-u_{t}-\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}+C\left(\varepsilon_{0}\right)+\delta \\
& >\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-u_{t} . \tag{2.8}
\end{align*}
$$

The last inequality is due to (2.5) and the positivity of $\delta$. Denote by $\Gamma_{T}$ the parabolic boundary of $\Omega_{T}$, i.e.

$$
\Gamma_{T}=\partial \Omega_{T} \backslash\{(T, x): x \in \Omega\}
$$

Suppose that at some point $N \in \bar{\Omega}_{T} \backslash \Gamma_{T}$ the function $\phi^{-}$attains its maximum, then at this point we have

$$
\begin{gathered}
\nabla \phi^{-}=0 \Leftrightarrow \nabla u=\nabla u_{0} \Rightarrow a_{i \varepsilon}\left(u_{x_{i}}\right)=a_{i \varepsilon}\left(u_{0 x_{i}}\right) \quad i=1, \ldots, n, \Rightarrow \\
\quad \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-\left.u_{t}\right|_{N}=\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) u_{x_{i} x_{i}}-\left.u_{t}\right|_{N}=0 .
\end{gathered}
$$

Hence, from (2.8),

$$
\left.L \phi^{-}\right|_{N}>0
$$

which contradicts the assumption that $\phi^{-}$attains its maximum at $N$. Consider $\phi^{-}$on $\Gamma_{T}$ :
for $x \in \partial \Omega, t \in[0, T]$ we have $\phi^{-}=-h(t) \leq 0$;
for $t=0, x \in \Omega$ we have $\phi^{-}=-h(0)=0$.
Thus $\phi^{-} \leq 0$ and (2.7) is proved.
Let us show now that

$$
\begin{equation*}
u(t, x)-u_{0}(x) \geq-h(t) \tag{2.9}
\end{equation*}
$$

Introduce the function $\phi^{+} \equiv u-\left[u_{0}(x)-h(t)\right]$. Similarly to the previous case we obtain

$$
\begin{align*}
L \phi^{+} & =\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-u_{t}-\left[\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}+h^{\prime}(t)\right] \\
& =\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-u_{t}-\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{0 x_{i} x_{i}}-C\left(\varepsilon_{0}\right)-\delta \\
& <\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-u_{t} \tag{2.10}
\end{align*}
$$

Suppose that at some point $N_{1} \in \bar{\Omega}_{T} \backslash \Gamma_{T}$ the function $\phi^{+}$attains its minimum, then at this point we have

$$
\begin{gathered}
\nabla \phi^{+}=0 \Leftrightarrow \nabla u=\nabla u_{0} \Rightarrow a_{i \varepsilon}\left(u_{0 x_{i}}\right)=a_{i \varepsilon}\left(u_{x_{i}}\right), \quad i=1, \ldots, n, \quad \Rightarrow \\
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{0 x_{i}}\right) u_{x_{i} x_{i}}-\left.u_{t}\right|_{N_{1}}=\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) u_{x_{i} x_{i}}-\left.u_{t}\right|_{N_{1}}=0 .
\end{gathered}
$$

Hence, from (2.10),

$$
\left.L \phi^{+}\right|_{N_{1}}<0
$$

which contradicts the assumption that $\phi^{+}$attains its minimum at $N_{1}$. Consider $\phi^{+}$ on $\Gamma_{T}$ :
for $x \in \partial \Omega, t \in[0, T]$ we have $\phi^{+}=h(t) \geq 0$;
for $t=0, x \in \Omega$ we have $\phi^{+}=h(0)=0$.

Thus $\phi^{+} \geq 0$ and (2.9) is proved. From (2.7) and (2.9) we have

$$
\left|u(t, x)-u_{0}(x)\right| \leq h(t)
$$

Passing to the limit as $\delta \rightarrow 0$ we finish the prove of Lemma 2.1.

Lemma 2.2. For every $\varepsilon \in\left(0, \varepsilon_{0}\right]$ and $(t, x) \in \bar{Q}_{T}$ the inequality

$$
\left|u_{\varepsilon t}\right| \leq C\left(\varepsilon_{0}\right)
$$

holds.

Proof. Consider equation (2.3) at two different points $(t, x)$ and $(\tau, x)$ :

$$
\begin{align*}
& \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) u_{x_{i} x_{i}}-u_{t}=0, \quad u=u(t, x)  \tag{2.11}\\
& \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) u_{x_{i} x_{i}}-u_{\tau}=0, \quad u=u(\tau, x) \tag{2.12}
\end{align*}
$$

Subtracting (2.12) from (2.11) for $v(t, \tau, x) \equiv u(t, x)-u(\tau, x)$, since

$$
v_{t}=u_{t}(t, x), \quad v_{\tau}=-u_{\tau}(\tau, x), \quad v_{x_{i} x_{i}}=u_{x_{i} x_{i}}(t, x)-u_{x_{i} x_{i}}(\tau, x),
$$

we obtain

$$
\begin{aligned}
& \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) v_{x_{i} x_{i}}-v_{t}-v_{\tau} \\
& \quad=\sum_{i=1}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right)-a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)\right] u_{x_{i} x_{i}}(\tau, x) .
\end{aligned}
$$

Consider the function

$$
\mathrm{w} \equiv v-C\left(\varepsilon_{0}\right)(t-\tau) \equiv u(t, x)-u(\tau, x)-C\left(\varepsilon_{0}\right)(t-\tau)
$$

in the domain

$$
P=\{(t, \tau, x): t \in(0, T), \tau \in(0, T), x \in \Omega, t>\tau\}
$$

Obviously for $\mathrm{w}(t, \tau, x)$ we have:

$$
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) \mathrm{w}_{x_{i} x_{i}}-\mathrm{w}_{t}-\mathrm{w}_{\tau}=\sum_{i=1}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right)-a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)\right] u_{x_{i} x_{i}}(\tau, x) .
$$

Introduce the function

$$
\omega \equiv \mathrm{w} e^{-\tau}
$$

which satisfies in $P$ the following linear ultraparabolic equation

$$
\begin{align*}
L \omega & \equiv \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) \omega_{x_{i} x_{i}}-\omega_{t}-\omega_{\tau}-\omega \\
& =e^{-\tau} \sum_{i=1}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right)-a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)\right] u_{x_{i} x_{i}}(\tau, x) . \tag{2.13}
\end{align*}
$$

Let

$$
\Gamma_{\tau}=\partial P \backslash\{(t, \tau, x): t=T, 0<\tau<T, x \in \Omega\}
$$

Suppose that the function $\omega$ attains its positive maximum at some point $N \in \bar{P} \backslash \Gamma_{\tau}$. At this point it should be

$$
\left.L \omega\right|_{N}=\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) \omega_{x_{i} x_{i}}-\omega_{t}-\omega_{\tau}-\left.\omega\right|_{N}<0
$$

since $\omega_{x_{i} x_{i}}(N) \leq 0,-\omega_{t}(N) \leq 0,-\omega_{\tau}(N)=0,-\omega(N)<0$. On the other hand at this point

$$
\nabla \omega=0 \quad \Leftrightarrow \quad \nabla u(t, x)=\nabla u(\tau, x)
$$

and hence, from (2.13),

$$
\left.L \omega\right|_{N}=0 .
$$

From this contradiction we conclude that $\omega$ can not attain its positive maximum in $\bar{P} \backslash \Gamma_{\tau}$.

Consider $\omega$ on $\Gamma_{\tau}$ :
for $x \in \partial \Omega, t \in[0, T], \tau \in[0, T], t>\tau$ we have $\omega=-C\left(\varepsilon_{0}\right)(t-\tau) e^{-\tau} \leq 0$;
for $t=\tau, x \in \bar{\Omega}, t \in[0, T]$ we have $\omega=0$;
for $\tau=0, t \in[0, T], x \in \bar{\Omega}$ we have $\omega=u(t, x)-u_{0}(x)-C\left(\varepsilon_{0}\right) t \leq 0$ due to Lemma 2.1.

Consequently $\omega \leq 0$ in $\bar{P}$, i.e.

$$
\begin{equation*}
u(t, x)-u(\tau, x) \leq C\left(\varepsilon_{0}\right)(t-\tau) \tag{2.14}
\end{equation*}
$$

Now subtracting (2.11) from (2.12) for $\tilde{v}(t, \tau, x) \equiv u(\tau, x)-u(t, x)$ we obtain

$$
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right) \tilde{v}_{x_{i} x_{i}}-\tilde{v}_{t}-\tilde{v}_{\tau}=\sum_{i=1}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)-a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right)\right] u_{x_{i} x_{i}}(t, x)
$$

Obviously the function $\tilde{\mathrm{w}} \equiv \tilde{v}-C\left(\varepsilon_{0}\right)(t-\tau)$ satisfies in $P$ the following relation

$$
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right) \tilde{\mathrm{w}}_{x_{i} x_{i}}-\tilde{\mathrm{w}}_{t}-\tilde{\mathrm{w}}_{\tau}=\sum_{i=1}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)-a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right)\right] u_{x_{i} x_{i}}(t, x) .
$$

Introduce the function $\tilde{\omega} \equiv \tilde{\mathrm{w}} e^{-\tau}$ which satisfies in $P$ the following ultraparabolic equation

$$
\begin{aligned}
& \sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right) \tilde{\omega}_{x_{i} x_{i}}-\tilde{\omega}_{t}-\tilde{\omega}_{\tau}-\tilde{\omega} \\
& \quad=e^{-\tau} \sum_{i=1}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)-a_{i \varepsilon}\left(u_{x_{i}}(\tau, x)\right)\right] u_{x_{i} x_{i}}(t, x)
\end{aligned}
$$

Similarly to the previous case we obtain that $\tilde{\omega}$ can not attain its positive maximum in $\bar{P} \backslash \Gamma_{\tau}$ and that $\tilde{\omega} \leq 0$ on $\Gamma_{\tau}$. The only difference is that for $\tau=0, t \in[0, T], x \in \bar{\Omega}$ we have $\tilde{\omega}=u_{0}(x)-u(t, x)-C\left(\varepsilon_{0}\right) t$, which is also nonpositive, due to Lemma 2.1.

Consequently, $\tilde{\omega} \leq 0$ in $\bar{P}$, i.e.

$$
\begin{equation*}
u(\tau, x)-u(t, x) \leq C\left(\varepsilon_{0}\right)(t-\tau) \text { in } \bar{P} . \tag{2.15}
\end{equation*}
$$

From (2.14) and (2.15) we conclude that

$$
\begin{equation*}
|u(t, x)-u(\tau, x)| \leq C\left(\varepsilon_{0}\right)(t-\tau) \text { in } \bar{P} . \tag{2.16}
\end{equation*}
$$

Taking into account the symmetry of the variables $t$ and $\tau$, we similarly consider the case $t<\tau$ to obtain that

$$
\begin{equation*}
|u(\tau, x)-u(t, x)| \leq C\left(\varepsilon_{0}\right)(\tau-t) \quad \text { in } \bar{P}_{1}, \tag{2.17}
\end{equation*}
$$

where

$$
P_{1}=\{(t, \tau, x): t \in(0, T), \tau \in(0, T), x \in \Omega, \tau>t\} .
$$

Note that here instead of $\Gamma_{\tau}$ we should take

$$
\Gamma_{t}=\partial P_{1} \backslash\{(t, \tau, x): \tau=T, 0<t<T, x \in \Omega\} .
$$

From (2.16) and (2.17) we conclude that in

$$
\{(t, \tau, x): t \in[0, T], \tau \in[0, T], x \in \bar{\Omega}\}
$$

the inequality

$$
|u(t, x)-u(\tau, x)| \leq C\left(\varepsilon_{0}\right)|t-\tau|
$$

holds. The last implies the required estimate.

Remark 2.1. Concerning the linear and nonlinear ultraparabolic equations see [19,21] and the references therein.

In order to pass to the limit in (2.3), (2.4) we also need the next estimates of the spatial derivatives of a solution.

Lemma 2.3. There exists a constant $C$ such that

$$
\int_{\Omega_{T}}\left|u_{\varepsilon x_{i}}(x, t)\right|^{p_{i}+2} d x d t \leq C, \quad i=1, \ldots, n
$$

for every $\varepsilon \in\left(0, \varepsilon_{0}\right]$.
The proof of Lemma 2.3 follows from [13] p. 3016. The proof of the next lemma follows from standard considerations based on the maximum principle.

Lemma 2.4. For every $\varepsilon \in\left(0, \varepsilon_{0}\right]$ the following estimate takes place

$$
\left|u_{\varepsilon}(x, t)\right| \leq \max _{\Omega}\left|u_{0}(x)\right|
$$

Now we are ready to pass to the limit as $\varepsilon \rightarrow 0$.

### 2.3. Passage to the limit

We will obtain a weak solution to problem (1.1)-(1.3) as a limit of the approximate solutions $u_{\varepsilon}$ constructed in Section 2.1.

Multiplying equation (2.1) by an arbitrary smooth function $\phi$, which vanishes on $(0, T) \times \partial \Omega$ and integrating by parts, we obtain

$$
\begin{equation*}
\int_{\Omega_{T}} u_{\varepsilon t} \phi d x d t+\int_{\Omega_{T}} \sum_{i=1}^{n}\left(u_{\varepsilon x_{i}}^{\alpha}+\varepsilon\right)^{p_{i} / \alpha} u_{\varepsilon x_{i}} \phi_{x_{i}} d x d t=0 . \tag{2.18}
\end{equation*}
$$

As it follows from Lemmas 2.2-2.4, there exists a sequence $\varepsilon_{k}$ such that

$$
\begin{gathered}
u_{\varepsilon_{k}} \rightarrow u^{*} \text {-weakly in } L_{\infty}\left(\Omega_{T}\right), \\
u_{\varepsilon_{k} x_{i}} \rightarrow u_{x_{i}} \text { weakly in } L_{p_{i}+2}\left(\Omega_{T}\right), \quad i=1, \ldots, n, \\
u_{\varepsilon_{k} t} \rightarrow u_{t}{ }^{*} \text {-weakly in } L_{\infty}\left(\Omega_{T}\right)
\end{gathered}
$$

as $\varepsilon_{k} \rightarrow 0$. Thus, in order to pass to the limit in (2.18), we only have to prove that

$$
\int_{\Omega_{T}} \sum_{i=1}^{n}\left(u_{\varepsilon_{k} x_{i}}^{\alpha}+\varepsilon_{k}\right)^{p_{i} / \alpha} u_{\varepsilon_{k} x_{i}} \phi_{x_{i}} d x d t \rightarrow \int_{\Omega_{T}} \sum_{i=1}^{n}\left|u_{x_{i}}\right|^{p_{i}} u_{x_{i}} \phi_{x_{i}} d x d t \text { as } \varepsilon_{k} \rightarrow 0 .
$$

This can be done exactly in the same way as in [13] (see [13] p. 3019 relation (2.25)).
Finally, passing to the limit as $\varepsilon_{0} \rightarrow 0$ we obtain the needed estimate

$$
\left\|u_{t}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{0}
$$

The uniqueness of the weak solution can be proved by standard considerations taking into account the monotonicity of the elliptic part of the operator (see [13], p. 3019).

Theorem 1 is proved.
Remark 2.2. The a priori estimate on $u_{\varepsilon t}$ can be obtained for more general case. Namely, instead of equation (2.3) we can consider the following one

$$
u_{\varepsilon t}=\sum_{i=1}^{n} a_{i \varepsilon}\left(x, \nabla u_{\varepsilon}\right) u_{\varepsilon x_{i} x_{i}}+\sum_{i=1}^{n} b_{i}\left(x, \nabla u_{\varepsilon}\right)+f\left(x, u_{\varepsilon}, \nabla u_{\varepsilon}\right)
$$

for a wide class of functions $a_{i \varepsilon}, b_{i}$ and $f$ under assumptions similar to the one dimensional case [20]. The problem here is the passage to the limit which is an open question. In some cases the passage to the limit is simple, for example if $a_{i \varepsilon}$ are as in (2.3), $b_{i}$ are linear with respect to $\nabla u$ and $f=f\left(x, u_{\varepsilon}\right)$ is a continuous non-increasing in $u_{\varepsilon}$ function such that $f(0)=0$.

## 3. Proof of Theorem 2

The proof of Theorem 2 is similar to the proof of Theorem 1 . The only difference is that we should prove the estimate $\left\|u_{\varepsilon x_{k}}\right\|_{L_{\infty}\left(\Omega_{T}\right)} \leq C_{k}, k=1, \ldots, n$ for a solution of problem (2.3), (2.4) under the additional assumption $(A)$ on the domain $\Omega$ or in the case when $\Omega$ is orthogonal parallelepiped. We will do this in two steps: first we obtain the boundary estimate and then the global estimate. As in the previous section we will omit index $\varepsilon$ in $u_{\varepsilon}$ in the proofs.

Lemma 3.1. For every $\varepsilon \in\left(0, \varepsilon_{0}\right]$ the following inequalities hold:
(i) if $\Omega$ satisfies assumption $(A)$ then

$$
\left|u_{\varepsilon}(t, x)\right| \leq C_{k}\left(G_{k}-x_{k}\right), \quad\left|u_{\varepsilon}(t, x)\right| \leq C_{k}\left(x_{k}-F_{k}\right), \quad k=1, \ldots, n
$$

(ii) if $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$ then

$$
\left|u_{\varepsilon}(t, x)\right| \leq C_{k}\left(l_{k}-x_{k}\right), \quad\left|u_{\varepsilon}(t, x)\right| \leq C_{k}\left(l_{k}+x_{k}\right), \quad k=1, \ldots, n
$$

Proof. (i) Assume that $\Omega$ satisfies assumption (A). Let $k=1$, the cases $k=2,3, \ldots, n$ are considered similarly. Introduce the function

$$
v(t, x)=u(t, x)-C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right)
$$

Obviously

$$
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) v_{x_{i} x_{i}}-v_{t}=-C_{1} \sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) G_{1 x_{i} x_{i}}
$$

and for $\tilde{v}=v e^{-t}$

$$
\begin{equation*}
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) \tilde{v}_{x_{i} x_{i}}-\tilde{v}_{t}-\tilde{v}=-C_{1} e^{-t} \sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) G_{1 x_{i} x_{i}} \geq 0 \tag{3.1}
\end{equation*}
$$

the last inequality is due to the convexity of $\Omega$ which implies the inequality $G_{1 x_{i} x_{i}} \leq 0$. From (3.1) it follows that the function $\tilde{v}$ cannot attain its positive maximum in $\bar{\Omega}_{T} \backslash \Gamma_{T}$ ( $\Gamma_{T}$ was defined in the proof of Lemma 2.1). On the parabolic boundary $\Gamma_{T}$ we have

1. for $x_{1}=G_{1}, t \in[0, T]: \tilde{v}=0$;
2. for $x_{1}=F_{1}, t \in[0, T]: \tilde{v}=e^{-t} C_{1}\left(F_{1}-G_{1}\right) \leq 0$;
3. for $t=0, x \in \Omega: \tilde{v}=u_{0}(x)-C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right) \leq 0$, because $\left.u_{0}\right|_{x_{1}=G_{1}}=0$ and $\left|u_{0 x_{1}}\right| \leq C_{1}$.

Consequently

$$
v \leq 0 \text { in } \bar{Q}_{T} \Leftrightarrow u \leq C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right) \text { in } \bar{Q}_{T} .
$$

Next we obtain a lower bound. Introduce the function

$$
w(t, x)=u(t, x)+C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right)
$$

Similarly to the previous case for $\tilde{w}=w e^{-t}$ we obtain

$$
\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) \tilde{w}_{x_{i} x_{i}}-\tilde{w}_{t}-\tilde{w}=C_{1} e^{-t} \sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) G_{1 x_{i} x_{i}} \leq 0
$$

hence the function $\tilde{w}$ cannot attain its negative minimum in $\bar{Q}_{T} \backslash \Gamma_{T}$. Taking into account that on the parabolic boundary $\Gamma_{T}$ we have $\tilde{w} \geq 0$ we conclude that

$$
w \geq 0 \text { in } \bar{Q}_{T} \Leftrightarrow u \geq-C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right) \text { in } \bar{Q}_{T}
$$

Thus

$$
|u(t, x)| \leq C_{1}\left(G_{1}-x_{1}\right)
$$

The proof of the second inequality (i.e. the inequality $\left.|u(t, x)| \leq C_{1}\left(x_{1}-F_{1}\right)\right)$ is similar. Instead of $v=u-C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right)$ and $w=u+C_{1}\left(G_{1}\left(x_{2}, \ldots, x_{n}\right)-x_{1}\right)$ we take $v=u-C_{1}\left(x_{1}-F_{1}\left(x_{2}, \ldots, x_{n}\right)\right)$ and $w=u+C_{1}\left(x_{1}-F_{1}\left(x_{2}, \ldots, x_{n}\right)\right)$ respectively and use the fact that the convexity of the domain $\Omega$ implies that $F_{1 x_{i} x_{i}} \geq 0$.
(ii) Assume that $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$. The proof is similar to the previous case. In the first estimate the only difference is that we take $v_{1}$ instead of $v$ and $w_{1}$ instead of $w$ where

$$
v_{1}=u-C_{1}\left(l_{1}-x_{1}\right) \text { and } w_{1}=u+C_{1}\left(l_{1}-x_{1}\right)
$$

In order to obtain the second estimate we take

$$
v_{1}=u-C_{1}\left(l_{1}+x_{1}\right) \text { and } w_{1}=u+C_{1}\left(l_{1}+x_{1}\right)
$$

Lemma 3.2. If $\Omega$ satisfies assumption (A) or $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$, then for every $\varepsilon \in\left(0, \varepsilon_{0}\right]$ the following estimates take place

$$
\left|u_{\varepsilon x_{k}}(t, x)\right| \leq C_{k}, \quad k=1, \ldots, n .
$$

Proof. 1). Suppose that $\Omega$ satisfies assumption (A). We will prove the estimate for $k=1$, for $k=2, \ldots, n$ the proof is similar. Consider the equations

$$
\begin{equation*}
a_{1 \varepsilon}\left(u_{x_{1}}\right) u_{x_{1} x_{1}}+\sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) u_{x_{i} x_{i}}-u_{t}=0, \quad u=u(t, x) \tag{3.2}
\end{equation*}
$$

and

$$
\begin{equation*}
a_{1 \varepsilon}\left(u_{\xi}\right) u_{\xi \xi}+\sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}\right) u_{x_{i} x_{i}}-u_{t}=0, \quad u=u(t, \tilde{x}) \tag{3.3}
\end{equation*}
$$

where $x=\left(x_{1}, x_{2}, \ldots, x_{n}\right), \tilde{x}=\left(\xi, x_{2}, \ldots, x_{n}\right)$. Subtracting (3.3) from (3.2), for

$$
v(t, \xi, x)=u(t, x)-u(t, \tilde{x})-C_{1}\left(x_{1}-\xi\right)
$$

we obtain

$$
\begin{aligned}
& a_{1 \varepsilon}\left(u_{x_{1}}(t, x)\right) v_{x_{1} x_{1}}+a_{1 \varepsilon}\left(u_{\xi}(t, \tilde{x})\right) v_{\xi \xi}+\sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) v_{x_{i} x_{i}}-v_{t} \\
& \quad=\sum_{i=2}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(t, \tilde{x})\right)-a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)\right] u_{x_{i} x_{i}}(t, \tilde{x}) .
\end{aligned}
$$

For $\tilde{v}=v e^{-t}$ we have

$$
\begin{align*}
& a_{1 \varepsilon}\left(u_{x_{1}}(t, x)\right) \tilde{v}_{x_{1} x_{1}}+a_{1 \varepsilon}\left(u_{\xi}(t, \tilde{x})\right) \tilde{v}_{\xi \xi}+\sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) \tilde{v}_{x_{i} x_{i}}-\tilde{v}_{t}-\tilde{v} \\
& \quad=e^{-t} \sum_{i=2}^{n}\left[a_{i \varepsilon}\left(u_{x_{i}}(t, \tilde{x})\right)-a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)\right] u_{x_{i} x_{i}}(t, \tilde{x}) . \tag{3.4}
\end{align*}
$$

Consider (3.4) in the domain

$$
P_{T}=\left\{(t, \xi, x): t \in(0, T), \xi \in\left(F_{1}, G_{1}\right), x_{1} \in\left(F_{1}, G_{1}\right), x_{1}>\xi,\left(x_{2}, \ldots, x_{n}\right) \in \Omega_{1}\right\}
$$

where $\Omega_{1}$ is a projection of $\Omega$ on the hyperplane $x_{1}=0$ (recall that $F_{1}=F_{1}\left(x_{2}, \ldots, x_{n}\right)$, $\left.G_{1}=G_{1}\left(x_{2}, \ldots, x_{n}\right)\right)$. Denote by $\Gamma$ the parabolic boundary of $P_{T}$ i.e.

$$
\Gamma=\partial P_{T} \backslash\left\{(T, \xi, x): \xi \in\left(F_{1}, G_{1}\right), x_{1} \in\left(F_{1}, G_{1}\right), x_{1}>\xi,\left(x_{2}, \ldots, x_{n}\right) \in \Omega_{1}\right\} .
$$

Suppose that at some point $N \in \bar{P}_{T} \backslash \Gamma$ the function $\tilde{v}$ attains its positive maximum. On the one hand we have

$$
a_{1 \varepsilon}\left(u_{x_{1}}(t, x)\right) \tilde{v}_{x_{1} x_{1}}+a_{1 \varepsilon}\left(u_{\xi}(t, \tilde{x})\right) \tilde{v}_{\xi \xi}+\sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) \tilde{v}_{x_{i} x_{i}}-\tilde{v}_{t}-\left.\tilde{v}\right|_{N}<0
$$

on the other

$$
\begin{gathered}
\left.\nabla \tilde{v}\right|_{N}=0 \Leftrightarrow u_{x_{i}}(t, x)-\left.u_{x_{i}}(t, \tilde{x})\right|_{N}=0, \quad i=2, \ldots, n \Rightarrow \\
a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right)-\left.a_{i \varepsilon}\left(u_{x_{i}}(t, \tilde{x})\right)\right|_{N}=0
\end{gathered}
$$

and thus, from (3.4) we obtain

$$
a_{1 \varepsilon}\left(u_{x_{1}}(t, x)\right) \tilde{v}_{x_{1} x_{1}}+a_{1 \varepsilon}\left(u_{\xi}(t, \tilde{x})\right) \tilde{v}_{\xi \xi}+\sum_{i=2}^{n} a_{i \varepsilon}\left(u_{x_{i}}(t, x)\right) \tilde{v}_{x_{i} x_{i}}-\tilde{v}_{t}-\left.\tilde{v}\right|_{N}=0 .
$$

Hence $\tilde{v}$ cannot attain its positive maximum in $\bar{P}_{T} \backslash \Gamma$. Consider $\Gamma$ which consists of four parts:

1. $\xi=F_{1}, x_{1} \in\left[F_{1}, G_{1}\right],\left(x_{2}, \ldots, x_{n}\right) \in \bar{\Omega}_{1}, t \in[0, T]$;
2. $x_{1}=G_{1}, \xi \in\left[F_{1}, G_{1}\right],\left(x_{2}, \ldots, x_{n}\right) \in \bar{\Omega}_{1}, t \in[0, T]$;
3. $x_{1}=\xi \in\left[F_{1}, G_{1}\right],\left(x_{2}, \ldots, x_{n}\right) \in \bar{\Omega}_{1}, t \in[0, T]$;
4. $t=0, x_{1}, \xi \in\left[F_{1}, G_{1}\right],\left(x_{2}, \ldots, x_{n}\right) \in \bar{\Omega}_{1}$.

According to the previous lemma, on the first and second parts we have

$$
\begin{gathered}
\tilde{v}=e^{-t}\left(u(t, x)-C_{1}\left(x_{1}-F_{1}\right)\right) \leq 0 \\
\tilde{v}=e^{-t}\left(-u(t, \tilde{x})-C_{1}\left(G_{1}-\xi\right)\right) \leq 0
\end{gathered}
$$

respectively. For $x_{1}=\xi$ we have $\tilde{v}=0$ and for $t=0$ :

$$
\tilde{v}=u_{0}(x)-u_{0}(\tilde{x})-C_{1}\left(x_{1}-\xi\right) \leq 0 .
$$

The last is due to the inequality $\left|u_{0 x_{1}}\right| \leq C_{1}$. Thus we conclude that $\tilde{v} \leq 0$ in $\bar{P}_{T}$ and consequently

$$
\begin{equation*}
u(t, x)-u(t, \tilde{x}) \leq C_{1}\left(x_{1}-\xi\right) \text { in } \bar{P}_{T} \tag{3.5}
\end{equation*}
$$

Similarly, subtracting (3.2) from (3.3) and considering the function

$$
\tilde{v}_{1}=e^{-t}\left(u(t, \tilde{x})-u(t, x)-C_{1}\left(x_{1}-\xi\right)\right),
$$

instead of $\tilde{v}$, we obtain

$$
u(t, \tilde{x})-u(t, x) \leq C_{1}\left(x_{1}-\xi\right) \text { in } \bar{P}_{T}
$$

From this inequality and inequality (3.5) we conclude that

$$
|u(t, x)-u(t, \tilde{x})| \leq C_{1}\left(x_{1}-\xi\right) \text { in } \bar{P}_{T} .
$$

Due to the symmetry of the variables $x_{1}$ and $\xi$ the case $x_{1}<\xi$ can be considered in the same way. Thus for

$$
x_{1} \in\left[F_{1}, G_{1}\right], \quad \xi \in\left[F_{1}, G_{1}\right], \quad\left(x_{2}, \ldots x_{n}\right) \in \Omega_{1}, \quad t \in[0, T]
$$

the inequality

$$
|u(t, x)-u(t, \tilde{x})| \leq C_{1}\left|x_{1}-\xi\right|
$$

holds, implying the needed estimate.
$2)$. The case $\Omega=\left(-l_{1}, l_{1}\right) \times \ldots \times\left(-l_{n}, l_{n}\right)$ is treated similarly. The only difference is in the construction of the domain $P_{T}$, here we should take

$$
\left.P_{T}=\left\{(t, \xi, x): t \in(0, T), \xi \in\left(-l_{1}, l_{1}\right), x_{1} \in\left(-l_{1}, l_{1}\right), x_{1}>\xi,\left|x_{i}\right|<l_{i}, i=2, \ldots, n\right)\right\}
$$

Remark 3.1. The a priori estimate on $\nabla u_{\varepsilon}$ can be obtained for more general case. Namely, instead of equation (2.3) we can take the following one

$$
u_{\varepsilon t}=\sum_{i=1}^{n} a_{i \varepsilon}\left(t, \nabla u_{\varepsilon}\right) u_{\varepsilon x_{i} x_{i}}+\sum_{i=1}^{n} b_{i}\left(t, \nabla u_{\varepsilon}\right)+f\left(t, x, u_{\varepsilon}, \nabla u_{\varepsilon}\right)
$$

for a wide class of functions $a_{i \varepsilon}, b_{i}$ and $f$ under assumptions similar to [14,16]. However the passage to the limit in this case is an open question. In some cases the passage to the limit is simple, for example if $a_{i \varepsilon}$ are as in (2.3), $b_{i}$ are linear with respect to $\nabla u$ and $f=f\left(t, u_{\varepsilon}\right)$ is a continuous non-increasing in $u_{\varepsilon}$ function such that $f(t, 0)=0$.

## 4. Proof of Theorem 3

In order to prove Theorem 3 we first obtain the estimates of $\left\|u_{\varepsilon x_{i} x_{j}}\right\|_{L_{2}\left(\Omega_{T}\right)}$ (independent of $\varepsilon$ ) and second, pass to the limit in the nonlinear term $a_{i \varepsilon}\left(u_{\varepsilon x_{i}}\right) u_{\varepsilon x_{i} x_{i}}$.

In this section we assume that $p_{i} \in(-1,0)$ for all $i$ and $\Omega$ is an orthogonal parallelepiped.

Lemma 4.1. For every $\varepsilon \in\left(0, \varepsilon_{0}\right]$ the following estimates take place

$$
\int_{\Omega_{T}}\left(\frac{\partial^{2} u_{\varepsilon}}{\partial x_{i} \partial x_{j}}\right)^{2} d t d x \leq \frac{1}{2\left(p_{i}+1\right)} K_{i}^{2}\left(C_{i}^{\alpha}+\varepsilon_{0}\right)^{-p_{i} / \alpha}, \quad i, j=1, \ldots, n
$$

Proof. We restrict ourselves with $i=1(j=1, \ldots, n)$, the considerations for $i=2, \ldots, n$ are similar. Multiply equation (2.3) by $u_{x_{1} x_{1}}$ and integrate by parts with respect to $x_{1}$ to obtain

$$
\begin{align*}
-\frac{1}{2} \frac{\partial}{\partial t} \int_{-l_{1}}^{l_{1}} u_{x_{1}}^{2} d x_{1}= & \int_{-l_{1}}^{l_{1}} a_{1 \varepsilon}\left(u_{x_{1}}\right) u_{x_{1} x_{1}}^{2} d x_{1} \\
& -\sum_{j=2}^{n} \int_{-l_{1}}^{l_{1}} a_{j \varepsilon}\left(u_{x_{j}}\right) u_{x_{j} x_{j} x_{1}} u_{x_{1}} d x_{1} \\
& -\sum_{j=2}^{n} \int_{-l_{1}}^{l_{1}} a_{j \varepsilon}^{\prime}\left(u_{x_{j}}\right) u_{x_{j} x_{1}} u_{x_{j} x_{j}} u_{x_{1}} d x_{1} \tag{4.1}
\end{align*}
$$

we use here the fact that $\left.u_{x_{j} x_{j}}\right|_{x_{1}= \pm l_{1}}=0$ for $j=2, \ldots, n$ and that $\left.u_{t}\right|_{x_{1}= \pm l_{1}}=0$. Integrate (4.1) by parts with respect to $x_{2}, \ldots, x_{n}$ to obtain

$$
-\frac{1}{2} \frac{\partial}{\partial t} \int_{\Omega} u_{x_{1}}^{2} d x=\int_{\Omega} a_{1 \varepsilon}\left(u_{x_{1}}\right) u_{x_{1} x_{1}}^{2} d x+\sum_{j=2}^{n} \int_{\Omega} a_{j \varepsilon}\left(u_{x_{j}}\right) u_{x_{j} x_{1}}^{2} d x
$$

We use here the fact that $\left.u_{x_{1}}\right|_{x_{j}= \pm l_{j}}=0$ for $j=2, \ldots, n$.
Integrate the last relation with respect to $t$ to obtain

$$
\int_{\Omega_{T}} a_{j \varepsilon}\left(u_{x_{j}}\right) u_{x_{j} x_{1}}^{2} d x d t \leq \frac{1}{2} \int_{\Omega} u_{0 x_{1}}^{2} d x, \quad j=1, \ldots, n
$$

Taking into account that
$a_{j \varepsilon}\left(u_{x_{j}}\right)=\left(u_{x_{j}}^{\alpha}+\varepsilon\right)^{\frac{p_{j}}{\alpha}-1}\left(\left(p_{j}+1\right) u_{x_{j}}^{\alpha}+\varepsilon\right) \geq\left(p_{j}+1\right)\left(u_{x_{j}}^{\alpha}+\varepsilon\right)^{\frac{p_{j}}{\alpha}} \geq\left(p_{j}+1\right)\left(C_{j}^{\alpha}+\varepsilon_{0}\right)^{\frac{p_{j}}{\alpha}}$ we obtain the needed estimates.

Recall that for the solution of problem (2.3), (2.4) the estimates of the previous sections hold as well. Thus we have that there exists a sequence $\varepsilon_{k}$ such that

$$
\begin{aligned}
& u_{\varepsilon_{k}} \rightarrow u \text { uniformly, } \\
& \frac{\partial u_{\varepsilon_{k}}}{\partial x_{i}} \rightarrow \frac{\partial u}{\partial x_{i}}{\text { *-weakly in } \quad L_{\infty}\left(\Omega_{T}\right), \quad i=1, \ldots, n, ~}_{\text {- }} \text {, } \\
& \frac{u_{\varepsilon_{k}}}{\partial t} \rightarrow \frac{\partial u}{\partial t} *_{\text {-weakly in }} L_{\infty}\left(\Omega_{T}\right), \\
& \frac{\partial^{2} u_{\varepsilon_{k}}}{\partial x_{i} \partial x_{j}} \rightarrow \frac{\partial^{2} u}{\partial x_{i} \partial x_{j}} \text { weakly in } L_{2}\left(\Omega_{T}\right), \quad i=1, \ldots, n,
\end{aligned}
$$

as $\varepsilon_{k} \rightarrow 0$.

Multiply equation (2.3) by an arbitrary smooth function $\phi$ and integrate to obtain

$$
\begin{equation*}
\int_{\Omega_{T}}\left[u_{\varepsilon t}-\sum_{i=1}^{n} a_{i \varepsilon}\left(u_{\varepsilon x_{i}}\right) u_{\varepsilon x_{i} x_{i}}\right] \phi d x d t=0 . \tag{4.2}
\end{equation*}
$$

In order to pass to the limit in (4.2) we show that in some sense

$$
a_{i \varepsilon}\left(u_{\varepsilon_{k} x_{i}}\right) \rightarrow a\left(u_{x_{i}}\right)=\left(1+p_{i}\right)\left|u_{x_{i}}\right|^{p_{i}} .
$$

To this end we will show that

$$
\begin{equation*}
\frac{\partial u_{\varepsilon_{k}}}{\partial x_{i}} \rightarrow \frac{\partial u}{\partial x_{i}} \quad \text { in } \quad L_{2}\left(\Omega_{T}\right), \quad i=1, \ldots, n \tag{4.3}
\end{equation*}
$$

In fact, consider

$$
\mathcal{W} \equiv\left\{u: u \in L_{2}\left(0, T ; H^{2}(\Omega)\right), u_{t} \in L_{2}\left(0, T ; L_{2}(\Omega)\right)\right\}
$$

(actually $\left.u_{t} \in L_{\infty}\left(0, T ; L_{\infty}(\Omega)\right)\right)$. From the compactness lemma (see, for example, [10], Ch. 1, Section 5) it follows that the embedding $\mathcal{W} \subset L_{2}\left(0, T ; H^{1}(\Omega)\right)$ is compact and consequently (4.3) holds.

Thus we can pass to the limit in (4.2) and obtain strong solution (according to Definition 2).

The last step in the proof of Theorem 3 is to pass to the limit $\varepsilon_{0} \rightarrow 0$ in order to obtain the declared estimate $\left\|u_{x_{i} x_{j}}\right\|_{L_{2}\left(\Omega_{T}\right)}^{2} \leq \frac{1}{2\left(p_{i}+1\right)} K_{i}^{2} C_{i}^{-p_{i}}$.

## 5. Proof of Theorems 4 and 5

In order to prove Theorems 4 and 5 consider the problem (1.1)-(1.3) taking $\Omega=\Omega_{l}=$ $(-l, l)^{n}$ and choosing $l>0$ so that the support of $u_{0}(x)$ lies in $\Omega_{l}$. Denote the solution of this problem by $u_{l}$. Note that all estimates obtained in the previous sections are independent of the size of the domain $\Omega$ i.e. of $l$ in this case. The solution of the Cauchy problem is obtained as a limit of a sequence of solutions $u_{l}$ of problem (1.1)-(1.3) under an unlimited dilatation of the domain $\Omega_{l}$ when $l \rightarrow \infty$ applying the diagonal process (see, for example, [9]).

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