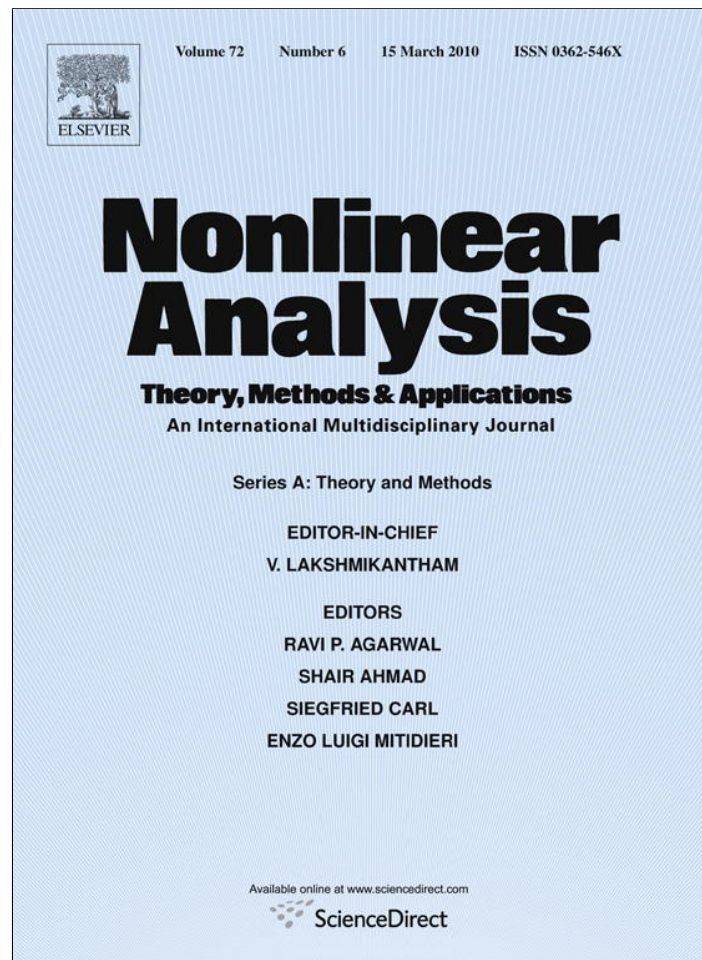


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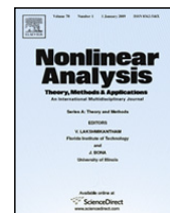
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## Nonlinear Analysis

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## Singular and degenerate anisotropic parabolic equations with a nonlinear source

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## ABSTRACT

The Dirichlet problem in arbitrary domain for degenerate and singular anisotropic parabolic equations with a nonlinear source term is considered. We state conditions that guarantee the existence and uniqueness of a global weak solution to the problem. A similar result is proved for the parabolic  $p$ -Laplace equation.

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## 1. Introduction and main results

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  and  $Q_T = \Omega \times (0, T)$  with an arbitrary  $T \in (0, \infty)$ . By  $\mathbf{x} = (x_1, \dots, x_n)$  we denote points in  $\Omega$  and by  $t$  the time variable that varies in the interval  $[0, T]$ . The goal of the present paper is to prove the solvability of the following quasilinear parabolic equation

$$u_t - \sum_{i=1}^n (|u_{x_i}|^{p_i} u_{x_i})_{x_i} = \lambda g(u) + f \quad \text{in } Q_T, \quad (1.1)$$

coupled with the homogeneous Dirichlet boundary condition

$$u = 0 \quad \text{on } \partial\Omega \times (0, T) \quad (1.2)$$

and the initial condition

$$u(\mathbf{x}, 0) = u_0(\mathbf{x}) \quad \text{in } \Omega. \quad (1.3)$$

Here  $u = u(\mathbf{x}, t)$  is the unknown function that has to be found, the function  $f = f(\mathbf{x}, t)$  is prescribed,  $p_i > -1$ ,  $i = 1, \dots, n$  and  $\lambda$  are constants, the function  $g$  will be discussed later.

The unique solvability of problem (1.1)–(1.3) with  $g \equiv 0$  was proved in [1, Ch. 2]. It is well known that the solution of this problem can blow-up in finite time if  $g \neq 0$  (see [2] and the references there for the case  $p_i = 0$ ,  $i = 1, \dots, n$  and [3,4]

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for the general case). Anisotropic elliptic and parabolic equations have received much attention in recent years, see [5–16]. The goal of the present paper is to obtain sufficient conditions guaranteeing the global solvability of problem (1.1)–(1.3) in general case. We will look for bounded weak solutions. Before we give the definition of the weak solution let us introduce some notations. Denote

$$p^* = \max\{p_1, p_2, \dots, p_n\}, \quad p_* = \min\{p_1, p_2, \dots, p_n\}.$$

Without loss of generality we may suppose that  $p_1 = p^*$ . Let  $l$  be a positive constant such that  $\Omega \subset \{\mathbf{x} \in \mathbb{R}^n \mid -l \leq x_1 \leq l\}$ .

Besides the usual Lebesgue and Sobolev function spaces, we will use spaces that are specific for our problem. For  $i = 1, \dots, n$ , we introduce the Banach space  $U_i(\Omega)$  as the closure of  $C_0^\infty(\Omega)$  with respect to the norm  $\|u\|_{U_i(\Omega)} = \|u\|_{L^2(\Omega)} + \|u_{x_i}\|_{L^{p_i+2}(\Omega)}$ . Define the space

$$U(\Omega) = \bigcap_{i=1}^n U_i(\Omega)$$

with the norm  $\|u\|_{U(\Omega)} = \max_{i=1, \dots, n} \|u\|_{U_i(\Omega)}$ . Clearly, the trace of function from  $U(\Omega)$  at  $\partial\Omega$  exists and is equal to zero. We denote by  $U_i^*(\Omega)$  the space adjoint (topologically) to  $U_i(\Omega)$ . Notice that  $U^*(\Omega) = \sum_{i=1}^n U_i^*(\Omega)$  (the sum in the space of distributions  $C_0^\infty(\Omega)^*$ ).

We shall meet spaces of functions depending on  $t$ . Let us introduce the following Banach space

$$V(Q_T) = \bigcap_{i=1}^n L^{p_i+2}(0, T; U_i(\Omega)).$$

Its adjoint is

$$V^*(Q_T) = \sum_{i=1}^n L^{q_i+2}(0, T; U_i^*(\Omega)),$$

where  $q_i$  is such that  $(p_i + 2)^{-1} + (q_i + 2)^{-1} = 1$ . It is not difficult to see that

$$L^{p^*+2}(0, T; U(\Omega)) \subset V(Q_T) \subset L^{p_*+2}(0, T; U(\Omega))$$

and, by duality,

$$L^{q_*+2}(0, T; U^*(\Omega)) \subset V^*(Q_T) \subset L^{q^*+2}(0, T; U^*(\Omega)),$$

where  $q_*$  and  $q^*$  are such that  $(q_* + 2)^{-1} + (p_* + 2)^{-1} = 1$  and  $(q^* + 2)^{-1} + (p^* + 2)^{-1} = 1$ .

**Definition 1.** We say that a function  $u : Q_T \rightarrow \mathbb{R}$  is a weak solution of problem (1.1)–(1.3) if

$$u \in L^\infty(Q_T) \cap V(Q_T) \cap C([0, T]; L^s(\Omega)) \quad \text{for all } s \in [1, \infty), \quad u_t \in V^*(Q_T)$$

and the following integral identity

$$\int_{Q_T} \left( u\phi_t - \sum_{i=1}^n |u_{x_i}|^{p_i} u_{x_i} \phi_{x_i} + \lambda g(u)\phi + f\phi \right) dxdt = - \int_{\Omega} u_0 \phi_0 dx$$

holds for an arbitrary smooth function  $\phi : Q_T \rightarrow \mathbb{R}$  which is equal to zero for  $\mathbf{x} \in \partial\Omega$  and for  $t = T$  (here  $\phi_0(\mathbf{x}) = \phi(\mathbf{x}, 0)$ ).

Let us denote

$$m = \|u_0\|_{L^\infty(\Omega)}, \quad f^* = \|f\|_{L^\infty(Q_T)},$$

$$\mathfrak{M} = \left\{ M \in (0, \infty) \mid f^* + |\lambda|g(M+m) < (p^* + 1) \left( \frac{2M}{3l^2 + 2l} \right)^{p^*+1} \right\},$$

$$M_* = \inf \mathfrak{M}.$$

We shall prove the existence of a weak solution to the problem under the following assumptions on  $g$ :

$$\text{the function } g : \mathbb{R} \rightarrow \mathbb{R} \text{ is continuous;} \tag{1.4}$$

$$|g(\xi)| \leq g(\eta) \quad \text{for all } \xi \text{ and } \eta \text{ such that } |\xi| \leq \eta; \tag{1.5}$$

$$\mathfrak{M} \neq \emptyset. \tag{1.6}$$

For example, functions  $g(u) = \log(|u| + 1)$ ,  $g(u) = |u|^{q-1}u$  (or  $g(u) = u^q$  if defined) with an arbitrary  $q \geq 0$ ,  $g(u) = |u|^q$ , and  $g(u) = e^u$  satisfy (1.4) and (1.5). Condition (1.6) will be discussed in examples below.

**Theorem 1.** Suppose that  $\Omega$  satisfies the exterior sphere condition,  $u_0 \in L^\infty(\Omega)$ ,  $f \in L^\infty(Q_T)$  and conditions (1.4)–(1.6) are fulfilled. Then for an arbitrary  $T > 0$ , there exists a weak solution of problem (1.1)–(1.3) such that

$$\|u\|_{L^\infty(Q_T)} \leq M_* + m. \tag{1.7}$$

If, in addition,  $g$  is Lipschitz continuous function, then the solution is unique.

Now let us give several examples concerning assumption (1.6).

**Example 1.** It is not difficult to see that for  $g(u) = \ln(|u| + 1)$  as well as for the functions  $g(u) = |u|^{q-1}u$ ,  $g(u) = |u|^q$  and  $g(u) = u^q$  (if defined) with  $0 \leq q < p^* + 1$  one can always find a positive  $M$  that belongs to  $\mathfrak{M}$ . That is  $\mathfrak{M} \neq \emptyset$ . As a consequence, **Theorem 1** guarantees the existence of a global (i.e., for an arbitrary  $T > 0$ ) weak solution to problem (1.1)–(1.3) with such functions  $g$  and arbitrary bounded  $u_0$  and  $f$ .

**Example 2.** Suppose that  $f \equiv 0$ ,  $\lambda \neq 0$ ,  $g(u) = |u|^{q-1}u$  and  $q = p^* + 1$ . In this case, the set  $\mathfrak{M}$  consists of numbers  $M$  that satisfy the following inequality

$$\frac{M + m}{M} < \frac{2}{3l^2 + 2l} \left( \frac{q}{|\lambda|} \right)^{1/q}$$

which is equivalent to

$$\frac{m}{M} < \frac{2}{3l^2 + 2l} \left( \frac{q}{|\lambda|} \right)^{1/q} - 1.$$

Obviously, if the right-hand side is strictly positive, then  $\mathfrak{M} \neq \emptyset$ . Thus, if

$$3l^2 + 2l < 2 \left( \frac{q}{|\lambda|} \right)^{1/q}, \tag{1.8}$$

then there exists a global weak solution of the problem. Condition (1.8) is the restriction on the size of the domain  $\Omega$  but only in one direction (in the direction of  $x_1$ ). Notice that this condition does not depend on  $\|u_0\|_{L^\infty(\Omega)}$ .

Instead of  $g(u) = |u|^{q-1}u$ , we can take  $g(u) = |u|^q$  (or  $g(u) = u^q$  if defined).

**Example 3.** Let us take  $g(u) = u^4$ ,  $f \equiv 0$ ,  $\lambda = 1$ , and  $p_i = 1$  for all  $i = 1, \dots, n$ . The set  $\mathfrak{M}$  is described by the following inequality

$$(M + m)^4 < \frac{8M^2}{(3l^2 + 2l)^2}$$

that can be rewritten as

$$M^2 + 2 \left( m - \frac{\sqrt{2}}{3l^2 + 2l} \right) M + m^2 < 0.$$

Therefore,  $\mathfrak{M} \neq \emptyset$  if

$$\|u_0\|_{L^\infty(\Omega)} = m < \frac{1}{\sqrt{2}(3l^2 + 2l)}. \tag{1.9}$$

This is the smallness condition which guarantees the existence of a global weak solution of problem (1.1)–(1.3).

**Example 4.** Similarly to the previous example, direct calculations show that condition (1.9) guarantees the existence of a global weak solution of problem (1.1)–(1.3) with  $g(u) = u$ ,  $f \equiv 0$ ,  $\lambda = 2^{-5/4}$ , and  $p_i = -1/2$  for all  $i = 1, \dots, n$ .

**Example 5.** Let us take  $g(u) = e^u$ ,  $f \equiv 0$ ,  $\lambda = 1$ , and  $p_i > -1$  for all  $i = 1, \dots, n$ . The set  $\mathfrak{M}$  consists of numbers  $M$  such that

$$e^{M+m} < (p^* + 1) \left( \frac{2M}{3l^2 + 2l} \right)^{p^*+1}.$$

This condition can be rewritten as follows

$$e^M < C M^{p^*+1}, \quad C = \frac{(p^* + 1)2^{p^*+1}}{e^m(3l^2 + 2l)^{p^*+1}}.$$

If the constant  $C$  is sufficiently large, then there exists  $M > 0$  that satisfies the last inequality, i.e.,  $\mathfrak{M} \neq \emptyset$ . Actually, this is the smallness condition.

**Example 6.** If  $\lambda = 0$ , then

$$\mathfrak{M} = \left\{ M \in (0, \infty) \mid f^* < (p^* + 1) \left( \frac{2M}{3l^2 + 2l} \right)^{p^*+1} \right\}.$$

This set is always nonempty and

$$M_* = \frac{3l^2 + 2l}{2} \left( \frac{f^*}{p^* + 1} \right)^{1/(p^*+1)}.$$

The approach developed in this paper can be easily extended to the  $p$ -Laplace equation. Consider the following parabolic equation

$$u_t - \operatorname{div}(|\nabla u|^p \nabla u) = \lambda g(u) + f(\mathbf{x}, t), \tag{1.10}$$

in  $Q_T = \Omega \times (0, T)$ , coupled with conditions (1.2) and (1.3).

**Definition 2.** We say that a function  $u : Q_T \rightarrow \mathbb{R}$  is a weak solution of problem (1.10), (1.2) and (1.3) if

$$\begin{aligned} u &\in L^\infty(Q_T) \cap L^{p+2}(0, T; W_0^{1,p+2}(\Omega)) \cap C(0, T; L^2(\Omega)), \\ u_t &\in L^{q+2}(0, T; W^{-1,q+2}(\Omega)), \quad (p+2)^{-1} + (q+2)^{-1} = 1, \end{aligned}$$

and

$$\int_{Q_T} (u\phi_t - |\nabla u|^p \nabla u \cdot \nabla \phi + \lambda g(u)\phi + f\phi) \, dxdt = - \int_{\Omega} u_0 \phi_0 \, dx$$

for an arbitrary smooth function  $\phi : Q_T \rightarrow \mathbb{R}$  which is equal to zero for  $\mathbf{x} \in \partial\Omega$  and for  $t = T$  ( $\phi_0 = \phi(\mathbf{x}, 0)$ ).

Let us introduce the following set

$$\mathfrak{N} = \left\{ M \in (0, \infty) \mid f^* + |\lambda|g(M+m) < (p+1) \left( \frac{2M}{3l_*^2 + 2l_*} \right)^{p+1} \right\},$$

where  $m$  and  $f^*$  are the same as in the definition of the set  $\mathfrak{N}$ ,  $l_* = \min\{l_1, \dots, l_n\}$  and numbers  $l_1, \dots, l_n$  are such that  $\Omega \subset \{\mathbf{x} : |x_i| \leq l_i\}$ . Denote  $N_* = \inf \mathfrak{N}$ .

**Theorem 2.** Suppose that  $\Omega$ ,  $u_0$  and  $f$  are the same as in Theorem 1,  $\mathfrak{N} \neq \emptyset$  and the function  $g$  satisfies conditions (1.4) and (1.5). Then for an arbitrary  $T > 0$  there exists a weak solution of problem (1.10), (1.2) and (1.3) such that

$$\|u\|_{L^\infty(Q_T)} \leq N_* + m.$$

If, in addition,  $g$  is Lipschitz continuous function then the solution is unique.

Similarly to problem (1.1)–(1.3) (see Examples 1–5), we can show that Theorem 2 guarantees the existence of a weak solution of problem (1.10), (1.2) and (1.3) for arbitrary  $T > 0$  in the following cases:

1.  $g(u) = \ln(|u| + 1)$  and  $g(u) = |u|^{q-1}u$  or  $g(u) = |u|^q$  or  $g(u) = u^q$  (if defined) with  $0 \leq q < p + 1$  and arbitrary bounded  $u_0, f$ ;
2.  $f \equiv 0, \lambda \neq 0, g(u) = |u|^{q-1}u$  (or  $u^q$  if defined) with  $q = p + 1$  and

$$3l_*^2 + 2l_* < 2 \left( \frac{q}{|\lambda|} \right)^{\frac{1}{q}}$$

with arbitrary bounded  $u_0$ ;

3.  $f \equiv 0, g(u) = u^4, \lambda = 1, p = 1$  (or  $f \equiv 0, g(u) = u, \lambda = 2^{-5/4}, p = -1/2$ ) and

$$\|u_0\|_{L^\infty(\Omega)} = m < \frac{1}{\sqrt{2}(3l_*^2 + 2l_*)};$$

4.  $f \equiv 0, g(u) = e^u, \lambda = 1, p > -1$  and

$$e^M < \frac{(p+1)2^{p+1}}{e^m(3l_*^2 + 2l_*)^{p+1}} M^{p+1}$$

for some  $N \in \mathfrak{N}$ .

Let us compare the assertion of Theorem 2 with known results concerning the global solvability of problem (1.10), (1.2) and (1.3). From [17] it follows that if

$$|\lambda g(u) + f| \leq C_0(1 + |u|^q)$$

with  $q < p + 1$  then the global weak solution exists. The same conclusion follows from Theorem 2 (see case 1.). If the measure of the domain is sufficiently small then [17] guarantees the existence of the global weak solution for  $q = p + 1$  (the

critical case). For the critical case, [Theorem 2](#) guarantees the existence of the global weak solution under the assumption that the domain is small enough only in one direction (see case 2.). In [\[3,4\]](#), the problem was considered with the source  $g(u) = |u|^{q-1}u$  or  $g(u) = u^q$ . It was shown there that the global weak solution exists if  $q < p + 1$ . For  $q > p + 1$  the global existence was established for small initial data. [Theorem 2](#) guarantees the global weak solvability of the problem with small initial data for a wide class of nonlinear sources which grow up faster than  $u^{p+1}$  (see cases 3. and 4.).

For large initial data and  $q > p + 1$ , the finite time blow-up of the solution was proved in [\[3,4\]](#). The finite blow-up of the solution for  $q = p + 1$  in arbitrary domain (without smallness restriction on the measure of the domain) was demonstrated in [\[17\]](#). The case  $q = p + 1$  was also considered in [\[18\]](#). It was shown that global solutions exist only if  $\lambda \leq \lambda_1$ , where  $\lambda_1$  is the first eigenvalue of the problem

$$\operatorname{div}(|\nabla \psi|^p \nabla \psi) + \lambda |\psi|^p \psi = 0 \quad \text{in } \Omega, \quad \psi|_{\partial\Omega} = 0.$$

Obviously, for  $\lambda$  small enough [Theorem 2](#) guarantees the existence of global weak solution to problem [\(1.10\)](#), [\(1.2\)](#) and [\(1.3\)](#).

The paper is organized as follows. Sections 2 and 3 are devoted to the proof of [Theorems 1](#) and 2, respectively. In both cases, we first obtain a priori estimates for the regularized problem and then pass to the limit in order to obtain the required result. Finally, in [Appendix](#) we prove some auxiliary statements used in the proofs.

## 2. Proof of [Theorem 1](#)

### 2.1. Regularized problem

We regularize the functions  $f$  and  $u_0$  by sequences of smooth functions  $f_\varepsilon : \overline{Q_T} \rightarrow \mathbb{R}$  and  $u_{0\varepsilon} : \overline{\Omega} \rightarrow \mathbb{R}$  such that  $f_\varepsilon(\mathbf{x}, t) \rightarrow f(\mathbf{x}, t)$  as  $\varepsilon \rightarrow 0$  for almost all  $(\mathbf{x}, t) \in Q_T$  and  $u_{0\varepsilon}(\mathbf{x}) \rightarrow u_0(\mathbf{x})$  as  $\varepsilon \rightarrow 0$  for almost all  $\mathbf{x} \in \Omega$ . Besides, we suppose that  $\max_{(\mathbf{x}, t) \in \overline{Q_T}} |f_\varepsilon(\mathbf{x}, t)| \leq f^*$  and  $\max_{\mathbf{x} \in \overline{\Omega}} |u_{0\varepsilon}(\mathbf{x})| \leq m$  for all  $\varepsilon$ . It is not difficult to prove the existence of such sequences. Indeed, extend the function  $u_0$  by zero outside of  $\Omega$ . Clearly  $u_{0\varepsilon} \rightarrow u_0$  in  $L_s(\Omega)$  for any  $s \in [1, +\infty)$  where  $u_{0\varepsilon}$  is a standard mollification of  $u_0$ . Hence, there exists a subsequence  $u_{0\varepsilon_k} \rightarrow u_0$  almost everywhere in  $\Omega$  and  $\max_{\mathbf{x} \in \overline{\Omega}} |u_{0\varepsilon_k}(\mathbf{x})| \leq m$  for all  $\varepsilon_k$ . The function  $f$  can be treated in the same way.

Let  $\{g_\varepsilon\}$  be a sequence of continuously differentiable functions such that

- (i<sub>ε</sub>)  $g_\varepsilon \rightarrow g$  as  $\varepsilon \rightarrow 0$  uniformly on every compact subset of  $\mathbb{R}$ ;
- (ii<sub>ε</sub>) for every  $\varepsilon > 0$ , function  $g_\varepsilon$  satisfies [\(1.5\)](#):  $|g_\varepsilon(\xi)| \leq g_\varepsilon(\eta)$  for all real  $\xi$  and  $\eta$  such that  $|\xi| \leq \eta$ .

We prove the existence of such a sequence  $\{g_\varepsilon\}$  in [Appendix A.1](#).

**Lemma 2.1.** For every compact subset  $\mathfrak{M}_c$  of  $\mathfrak{M}$  there exists  $\varepsilon_0 > 0$  such that

$$f^* + |\lambda| g_\varepsilon(M + m) < (p^* + 1) \left( \frac{2M}{3l^2 + 2l} \right)^{p^*+1} \quad \text{for all } M \in \mathfrak{M}_c \text{ and } \varepsilon \in (0, \varepsilon_0).$$

**Proof.** Let us introduce the following functions

$$G(\xi) = f^* + |\lambda| g(\xi + m) - (p^* + 1) \left( \frac{2\xi}{3l^2 + 2l} \right)^{p^*+1},$$

$$G_\varepsilon(\xi) = f^* + |\lambda| g_\varepsilon(\xi + m) - (p^* + 1) \left( \frac{2\xi}{3l^2 + 2l} \right)^{p^*+1}.$$

Then  $\mathfrak{M} = \{\xi \mid G(\xi) < 0\}$ . For every compact  $\mathfrak{M}_c \subset \mathfrak{M}$ , there exists  $\delta > 0$  such that  $G(\xi) \leq -\delta$  for  $\xi \in \mathfrak{M}_c$ . According to (i<sub>ε</sub>), there exists  $\varepsilon_0 > 0$  such that  $|G(\xi) - G_\varepsilon(\xi)| < \delta$  and, as a consequence,  $G_\varepsilon(\xi) < 0$  for all  $\xi \in \mathfrak{M}_c$  and  $\varepsilon \in (0, \varepsilon_0)$ . The lemma is proved.  $\square$

Let us make two remarks concerning the previous lemma. First, if we have found  $\varepsilon_0$  corresponding a compact set  $\mathfrak{M}_c$ , we can take a smaller  $\varepsilon_0$  in the formulation of the lemma. Second, since  $\mathfrak{M}$  is the union of all its compact subsets,

$$M_* = \inf_{\mathfrak{M}_c \subset \mathfrak{M}} \min\{M \mid M \in \mathfrak{M}_c\}. \tag{2.1}$$

Let us fix an arbitrary compact set  $\mathfrak{M}_c \subset \mathfrak{M}$  and a positive number  $\varepsilon_0$  that corresponds to  $\mathfrak{M}_c$  according to [Lemma 2.1](#). For all  $\varepsilon \in (0, \varepsilon_0)$  and for arbitrary  $M \in \mathfrak{M}_c$ , we introduce the following cut-off function

$$\bar{g}_\varepsilon(z) = \begin{cases} g_\varepsilon(-M - m), & z < -M - m, \\ g_\varepsilon(z), & |z| \leq M + m, \\ g_\varepsilon(M + m), & z > M + m, \end{cases}$$

and consider the following regularized problem

$$u_{\varepsilon t} - \sum_{i=1}^n ((u_{\varepsilon x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{\varepsilon x_i})_{x_i} = \lambda \bar{g}_\varepsilon(u_\varepsilon) + f_\varepsilon \quad \text{in } Q_T, \tag{2.2}$$

$$u_\varepsilon = 0 \quad \text{on } \partial\Omega \times (0, T), \tag{2.3}$$

$$u_\varepsilon(\mathbf{x}, 0) = u_{0\varepsilon}(\mathbf{x}) \quad \text{in } \Omega, \tag{2.4}$$

where  $\alpha \in (0, 1)$  is a constant such that  $\alpha = r/m$  with positive integers  $r$  and  $m$ ,  $r < m$ , and  $r$  is even. In the singular case  $p^* \in (-1, 0)$ , we additionally require that  $\alpha$  satisfies the following conditions:

$$\alpha > p^* + 1 \quad \text{and} \quad (\alpha - p^* + 1) \left( \frac{2M}{3l^2 + 2l} \right)^\alpha \geq \varepsilon_0. \tag{2.5}$$

For example, if  $p^* \geq 0$ , one can take  $\alpha = 2/3$ ; if  $p^* = -1/2$ , one can also take  $\alpha = 2/3$ ; if  $p^* = -1/3$ , one can put  $\alpha = 4/5$ . Clearly, condition (2.5) can always be satisfied, if one takes  $\varepsilon_0$  small enough.

These conditions on  $\alpha$  are motivated by two reasons. The first one is that for such  $\alpha$

$$(z^\alpha)^{p_i/\alpha} = |z|^{p_i} \quad \text{and} \quad z^\alpha = (-z)^\alpha,$$

since  $\alpha$  is a rational number with an even numerator. The second reason is that, for such  $\alpha$ , the function  $a_1(\varepsilon, z)$  which is defined below is nondecreasing with respect to  $\varepsilon$  on the interval  $(0, \varepsilon_0)$ . This property of this function will be used in the proof of Lemma 2.2.

Concerning the existence of a classical solution  $u_\varepsilon$  of problem (2.2)–(2.4) see Appendix A.2. Our goal in this section is to obtain uniform estimates on this solution which would enable us to pass to the limit as  $\varepsilon \rightarrow 0$ . First we obtain a uniform estimate on  $u_\varepsilon$  in  $L^\infty$  norm.

**Lemma 2.2.** *For every compact set  $\mathfrak{M}_c \subset \mathfrak{M}$  and for every  $\varepsilon \in (0, \varepsilon_0)$ , the classical solution of problem (2.2)–(2.4) satisfies the following estimate:*

$$\|u_\varepsilon\|_{L^\infty(Q_T)} \leq m + M_c,$$

where  $M_c = \min\{M \mid M \in \mathfrak{M}_c\}$  and  $\varepsilon_0$  is the positive number corresponding to  $\mathfrak{M}_c$  according to Lemma 2.1.

**Proof.** In order to simplify the notation, we shall write  $u$  instead of  $u_\varepsilon$ . Let us take an arbitrary  $M \in \mathfrak{M}_c$  and rewrite Eq. (2.2) in the non-divergent form:

$$u_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon) u_{x_i x_i} = \lambda \bar{g}_\varepsilon(u) + f_\varepsilon \tag{2.6}$$

with

$$a_i(z, \varepsilon) = (z^\alpha + \varepsilon)^{\frac{p_i}{\alpha} - 1} ((p_i + 1)z^\alpha + \varepsilon).$$

Define a function  $h = h(x_1)$  as follows:

$$h(x_1) = \tilde{M} \left( \frac{l^2 - x_1^2}{2} + (1 + l)(l + x_1) \right) + m,$$

where

$$\tilde{M} = \frac{2M}{3l^2 + 2l}.$$

Let us introduce the following nonlinear differential operator

$$Lu = u_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon) u_{x_i x_i}.$$

With this notation, Eq. (2.2) can be rewritten as

$$Lu = \lambda \bar{g}_\varepsilon(u) + f_\varepsilon. \tag{2.7}$$

Besides that, since  $h$  depends only on  $x_1$ , (recall that  $p^* = p_1$ )

$$Lh = h_t - \sum_{i=1}^n a_i(h_{x_i}, \varepsilon) h_{x_i x_i} - a_1(h', \varepsilon) h'' = \tilde{M} a_1(h', \varepsilon). \tag{2.8}$$

Consider the function  $a_1(z, \varepsilon)$ . By direct calculations, we obtain

$$\frac{\partial a_1}{\partial \varepsilon}(z, \varepsilon) = \frac{p^*}{\alpha} (z^\alpha + \varepsilon)^{\frac{p^*}{\alpha} - 2} (z^\alpha (p^* + 1 - \alpha) + \varepsilon).$$

Due to the assumptions on  $\alpha$ , we find that

$$\frac{\partial a_1}{\partial \varepsilon}(z, \varepsilon) \geq 0 \quad \text{for } \varepsilon \in (0, \varepsilon_0) \text{ and } z \geq \tilde{M}.$$

Since  $h' \geq \tilde{M}$ , (2.8) implies that

$$Lh \geq \tilde{M}a_1(h', 0) = \tilde{M}(p^* + 1)h^{p^*} \geq (p^* + 1)\tilde{M}^{p^*+1}. \tag{2.9}$$

Let us denote  $v(\mathbf{x}, t) = u(\mathbf{x}, t) - h(x_1)$ . It is not difficult to deduce that

$$\begin{aligned} Lu - Lh &= u_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)u_{x_i x_i} - h_t + \sum_{i=1}^n a_i(h_{x_i}, \varepsilon)h_{x_i x_i} \\ &= v_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)v_{x_i x_i} + (a_1(h', \varepsilon) - a_1(u_{x_1}, \varepsilon))h''. \end{aligned}$$

On the other hand, due to (2.7) and (2.9), we have

$$Lu - Lh = \lambda \bar{g}_\varepsilon(u) + f_\varepsilon - Lh \leq \lambda \bar{g}_\varepsilon(u) + f_\varepsilon - (p^* + 1)\tilde{M}^{p^*+1}.$$

Hence,

$$v_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)v_{x_i x_i} \leq (a_1(u_{x_1}, \varepsilon) - a_1(h', \varepsilon))h'' + \lambda \bar{g}_\varepsilon(u) + f_\varepsilon - (p^* + 1)\tilde{M}^{p^*+1}. \tag{2.10}$$

Denote by  $\Gamma_T$  the parabolic boundary of  $Q_T$ , i.e.,  $\Gamma_T = \{(\mathbf{x}, t) \in \partial Q_T \mid t \neq T\}$ . Suppose that the function  $v$  attains its positive maximum at the point  $N \in \bar{Q}_T \setminus \Gamma_T$ . At this point,  $v > 0$  and  $v_{x_i} = 0$  or, in other words,  $u > h \geq m$  and  $u_{x_1} = h'$ . Thus,  $a_1(u_{x_1}, \varepsilon) = a_1(h', \varepsilon)$  and consequently, due to (2.10), at the point  $N$ , we have

$$\begin{aligned} v_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)v_{x_i x_i} &\leq \lambda \bar{g}_\varepsilon(u) + f_\varepsilon - (p^* + 1)\tilde{M}^{p^*+1} \\ &\leq |\lambda| \bar{g}_\varepsilon(M + m) + f^* - (p^* + 1)\tilde{M}^{p^*+1} \\ &= |\lambda| g_\varepsilon(M + m) + f^* - (p^* + 1) \left( \frac{2M}{3l^2 + 2l} \right)^{p^*+1}. \end{aligned}$$

We used the fact that  $0 \leq \bar{g}_\varepsilon(z) \leq g_\varepsilon(M + m)$  for positive  $z$ . Therefore, as it follows from Lemma 2.1,

$$v_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)v_{x_i x_i} < 0$$

at the point  $N$ . This inequality contradicts the assumption that  $v$  attains its maximum at  $N$ .

Due to (2.3),  $v = -h \leq 0$  on  $\partial \Omega \times (0, T)$ . Besides,  $v(\mathbf{x}, 0) = u_{0\varepsilon}(\mathbf{x}) - h(x_1) \leq u_{0\varepsilon}(\mathbf{x}) - m \leq 0$ . Thus,  $v \leq 0$  on  $\Gamma_T$ . This enables us to conclude that  $v \leq 0$  in  $\bar{Q}_T$ , i.e.,

$$u(\mathbf{x}, t) \leq h(x_1) \quad \text{for } (\mathbf{x}, t) \in \bar{Q}_T.$$

In order to obtain a similar estimate from below, let us introduce the function  $w(\mathbf{x}, t) = u(\mathbf{x}, t) + h(x_1)$ . We have

$$\begin{aligned} Lu + Lh &= u_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)u_{x_i x_i} + h_t - \sum_{i=1}^n a_i(h_{x_i}, \varepsilon)h_{x_i x_i} \\ &= w_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon)w_{x_i x_i} - (a_1(h', \varepsilon) - a_1(u_{x_1}, \varepsilon))h''. \end{aligned}$$

On the other hand, due to (2.7) and (2.9),

$$Lu + Lh = \lambda \bar{g}_\varepsilon(u) + f_\varepsilon + Lh \geq \lambda \bar{g}_\varepsilon(u) + f_\varepsilon + (p^* + 1)\tilde{M}^{p^*+1}.$$



Thus,

$$w_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon) w_{x_i x_i} \geq (a_1(h', \varepsilon) - a_1(u_{x_1}, \varepsilon)) h'' + \lambda \bar{g}_\varepsilon(u) + f_\varepsilon + (p^* + 1) \tilde{M}^{p^*+1}.$$

Suppose that at the point  $N_1 \in \bar{Q}_T \setminus \Gamma_T$  the function  $w$  attains its negative minimum. At this point we have  $w < 0$  and  $w_{x_i} = 0$ , i.e.,  $u < -h \leq 0$  and  $u_{x_1} = -h'$ . Therefore,  $a_1(u_{x_1}, \varepsilon) = a_1(h', \varepsilon)$  (recall that, due to the choice of  $\alpha$ ,  $a_i(z, \varepsilon) = a_i(-z, \varepsilon)$ ) and at the point  $N_1$ ,

$$\begin{aligned} w_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon) w_{x_i x_i} &\geq \lambda \bar{g}_\varepsilon(u) + f_\varepsilon + (p^* + 1) \tilde{M}^{p^*+1} \\ &\geq -|\lambda| g_\varepsilon(M + m) - f^* + (p^* + 1) \left( \frac{2M}{(3l^2 + 2l)} \right)^{p^*+1}. \end{aligned} \tag{2.11}$$

Here, we used the inequality

$$\lambda \bar{g}_\varepsilon(u(N_1)) \geq -|\lambda| g_\varepsilon(M + m)$$

which is true due to the following arguments. If  $\lambda \geq 0$ , then this inequality follows from the fact that  $\bar{g}_\varepsilon(u) \geq -g_\varepsilon(M + m)$  (see assumption (ii $_\varepsilon$ )). If  $\lambda < 0$ , then the inequality follows from the fact that  $\bar{g}_\varepsilon(u) \leq g_\varepsilon(M + m)$ . Inequality (2.11) and Lemma 2.1 imply that

$$w_t - \sum_{i=1}^n a_i(u_{x_i}, \varepsilon) w_{x_i x_i} > 0$$

at the point  $N_1$ . This contradicts the assumption that  $w$  attains its minimum at  $N_1$ .

Due to (2.3) and (2.4),  $w = h \geq 0$  on  $\partial\Omega \times (0, T)$ . Moreover  $w(\mathbf{x}, 0) = u_{0\varepsilon}(\mathbf{x}) + h(x_1) \geq u_{0\varepsilon}(\mathbf{x}) + m \geq 0$ . Taking into account that  $w$  cannot attain its positive maximum in  $\bar{Q}_T \setminus \Gamma_T$ , we conclude that  $w \geq 0$  in  $\bar{Q}_T$  and, as a consequence,

$$u(\mathbf{x}, t) \geq -h(x_1) \quad \text{for } (\mathbf{x}, t) \in \bar{Q}_T.$$

Thus,

$$-h(x_1) \leq u(\mathbf{x}, t) \leq h(x_1) \quad \text{for } (\mathbf{x}, t) \in \bar{Q}_T. \tag{2.12}$$

Let us introduce the function  $\tilde{h}(x_1) = h(-x_1)$ . Obviously  $\tilde{h}' \leq -\tilde{M}$  and  $\tilde{h}'' = -\tilde{M}$ . Moreover, since  $-\tilde{h}' \geq \tilde{M} \geq 0$ , due to the choice of  $\alpha$ , we have  $\tilde{h}^\alpha \geq \tilde{M}^\alpha$ . Hence,

$$L\tilde{h} \geq (p^* + 1) \tilde{M}^{p^*+1}.$$

Therefore, similarly to (2.12), we obtain

$$-\tilde{h}(x_1) \leq u(\mathbf{x}, t) \leq \tilde{h}(x_1) \quad \text{for } (\mathbf{x}, t) \in \bar{Q}_T.$$

This estimate together with (2.12) implies that

$$-\min\{h(x_1), \tilde{h}(x_1)\} \leq u(\mathbf{x}, t) \leq \min\{h(x_1), \tilde{h}(x_1)\} \quad \text{for } (\mathbf{x}, t) \in \bar{Q}_T.$$

Since  $\min\{h(x_1), \tilde{h}(x_1)\} \leq h(0)$ , we have

$$|u(\mathbf{x}, t)| \leq h(0) = \tilde{M} \frac{3l^2 + 2l}{2} + m = M + m \quad \text{for } (\mathbf{x}, t) \in \bar{Q}_T.$$

The assertion of the lemma follows now from the fact that  $M$  is an arbitrary number from the set  $\mathfrak{M}_c$ . Lemma 2.2 is proved.  $\square$

**Remark 1.** The estimate in Lemma 2.2 is weaker than the similar one in Theorem 1. The latter will be obtained in the limit as  $\varepsilon \rightarrow 0$ . Nevertheless, Lemma 2.2 gives us a uniform estimate of  $\|u_\varepsilon\|_{L^\infty(Q_T)}$  and this is enough to obtain other estimates and to perform the passage to the limit. Besides that, this estimate enables us to replace  $\bar{g}_\varepsilon$  by  $g_\varepsilon$  in (2.2).

Let us estimate the derivatives of  $u_\varepsilon$ .

**Lemma 2.3.** *Let  $\mathfrak{M}_c$  and  $\varepsilon_0$  be as in Lemma 2.2. There exists a constant  $C$  such that*

$$\int_{Q_T} |u_{\varepsilon x_i}(\mathbf{x}, t)|^{p_i+2} dx dt \leq C, \quad i = 1, \dots, n,$$

for every  $\varepsilon \in (0, \varepsilon_0)$ .

**Proof.** As in the proof of the previous lemma, we shall write  $u$  instead of  $u_\varepsilon$ . Multiplying Eq. (2.2) by  $u$  and integrating by parts we obtain

$$\int_{\Omega} u^2(\mathbf{x}, t) d\mathbf{x} + 2 \sum_{i=1}^n \int_{Q_T} (u_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{x_i}^2 d\mathbf{x} dt = 2 \int_{Q_T} (\lambda \bar{g}_\varepsilon(u) + f) u d\mathbf{x} dt + \int_{\Omega} u_0^2 d\mathbf{x}.$$

Due to Lemma 2.2, this equality implies the following estimate

$$\int_{Q_T} (u_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{x_i}^2 d\mathbf{x} dt \leq C_1, \quad i = 1, \dots, n, \tag{2.13}$$

with a constant  $C_1$  that does not depend on  $\varepsilon$ .

First, we suppose that  $p_i \geq 0$ . In this case,  $(z^\alpha + \varepsilon)^{p_i/\alpha} z^2 \geq |z|^{p_i+2}$  and consequently, from (2.13), we conclude that

$$\int_{Q_T} |u_{x_i}|^{p_i+2} d\mathbf{x} dt \leq C_1, \quad i = 1, \dots, n.$$

Now, consider the case  $p_i \in (-1, 0)$ . Let  $(Q_T)^\varepsilon$  be the subset of  $Q_T$  where  $u_{x_i}^\alpha > \varepsilon$  and  $(Q_T)_\varepsilon = Q_T \setminus (Q_T)^\varepsilon$ . Obviously,  $u_{x_i}^\alpha + \varepsilon < 2u_{x_i}^\alpha$  in  $(Q_T)^\varepsilon$  and, since  $p_i < 0$ ,

$$C_1 \geq \int_{(Q_T)^\varepsilon} (u_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} |u_{x_i}|^2 d\mathbf{x} dt > 2^{p_i/\alpha} \int_{(Q_T)^\varepsilon} |u_{x_i}|^{p_i+2} d\mathbf{x} dt.$$

At the same time,

$$\int_{(Q_T)_\varepsilon} |u_{x_i}|^{p_i+2} d\mathbf{x} dt \leq T \varepsilon^{p_i+2} \text{mes } \Omega.$$

Thus,

$$\int_{Q_T} |u_{x_i}|^{p_i+2} d\mathbf{x} dt \leq 2^{-p_i/\alpha} C_1 + T \varepsilon^{p_i+2} \text{mes } \Omega.$$

The lemma is proved.  $\square$

Let us prove the following auxiliary lemma.

**Lemma 2.4.** For any  $v \in L^\infty(\Omega) \cap U_i(\Omega)$ ,  $i \in \{1, \dots, n\}$  there exists a constant  $C$  (depending on  $\|v_{x_i}\|_{L^{p_i+2}(\Omega)}$ ) such that

$$\left| \int_{\Omega} (v_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} v_{x_i} \phi_{x_i} d\mathbf{x} \right| \leq C \|\phi_{x_i}\|_{L^{p_i+2}(\Omega)}, \quad i = 1, \dots, n,$$

for every function  $\phi \in U_i(\Omega)$  and for all  $\varepsilon \in (0, 1)$ .

**Proof.** For a fixed  $\varepsilon \in (0, 1)$ , denote by  $\Omega^\varepsilon$  the subset of  $\Omega$ , where  $v_{x_i}^\alpha > \varepsilon$ , and by  $\Omega_\varepsilon$  the subset of  $\Omega$ , where  $v_{x_i}^\alpha \leq \varepsilon$ . Recall that  $v_{x_i}^\alpha \geq 0$ , since  $\alpha$  has an even numerator. In  $\Omega^\varepsilon$ , we have

$$(v_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} |v_{x_i}| < 2^{p_i/\alpha} |v_{x_i}|^{p_i+1}.$$

Therefore,

$$\begin{aligned} \left| \int_{\Omega^\varepsilon} (v_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} v_{x_i} \phi_{x_i} d\mathbf{x} \right| &< 2^{p_i/\alpha} \int_{\Omega^\varepsilon} |v_{x_i}|^{p_i+1} |\phi_{x_i}| d\mathbf{x} \\ &\leq 2^{p_i/\alpha} \int_{\Omega} |v_{x_i}|^{p_i+1} |\phi_{x_i}| d\mathbf{x} \leq 2^{p_i/\alpha} \|v_{x_i}\|_{L^{p_i+2}(\Omega)}^{p_i+1} \|\phi_{x_i}\|_{L^{p_i+2}(\Omega)}. \end{aligned}$$

The integral over  $\Omega_\varepsilon$  can be estimated as follows

$$\left| \int_{\Omega_\varepsilon} (v_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} v_{x_i} \phi_{x_i} d\mathbf{x} \right| \leq (2\varepsilon)^{p_i/\alpha} \varepsilon^{1/\alpha} \int_{\Omega_\varepsilon} |\phi_{x_i}| d\mathbf{x} dt \leq 2^{p_i/\alpha} \varepsilon^{(p_i+1)/\alpha} \|\phi_{x_i}\|_{L^1(\Omega)}.$$

The assertion of the lemma follows from these estimates.  $\square$

**Lemma 2.5.** Let  $\mathfrak{M}_c$  and  $\varepsilon_0$  be as in Lemma 2.2. There exists a constant  $C$  such that

$$\left| \int_{Q_T} u_{\varepsilon t} \phi d\mathbf{x} dt \right| \leq C \|\phi\|_{V(Q_T)}$$

for every function  $\phi \in V(Q_T)$  and for all  $\varepsilon \in (0, \varepsilon_0)$ .

**Proof.** As earlier, we shall write  $u$  instead of  $u_\varepsilon$ . Multiplying (2.2) by an arbitrary function  $\phi \in V(Q_T)$  and integrating over  $Q_T$ , we obtain that

$$\left| \int_{Q_T} u_t \phi \, dx dt \right| \leq \sum_{i=1}^n \left| \int_{Q_T} (u_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{x_i} \phi_{x_i} \, dx dt \right| + \int_{Q_T} (|\lambda \bar{g}_\varepsilon(u)| + |f|) |\phi| \, dx dt. \tag{2.14}$$

From Lemmas 2.1 and 2.2 it follows that there exists a constant  $C_1$  such that

$$\int_{Q_T} (|\lambda \bar{g}_\varepsilon(u)| + |f|) |\phi| \, dx dt \leq C_1 \|\phi\|_{L^1(Q_T)}. \tag{2.15}$$

Consider the first term on the right-hand side of (2.14). Due to Lemmas 2.3 and 2.4, there exists a constant  $C_2$  such that

$$\left| \int_{Q_T} (u_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{x_i} \phi_{x_i} \, dx dt \right| \leq C_2 \|\phi_{x_i}\|_{L^{p_i+2}(Q_T)}, \quad i = 1, \dots, n. \tag{2.16}$$

The assertion of the lemma follows now from (2.14)–(2.16).  $\square$

### 2.2. Passage to the limit

We obtain a weak solution to problem (1.1)–(1.3) as a limit of the approximate solutions  $u_\varepsilon$  constructed in the previous section. Let  $\{\varepsilon_k\}$  be a monotone sequence of positive numbers which tends to zero as  $k \rightarrow \infty$ . In order to simplify the notations, we shall omit the index  $k$  and shall write  $\varepsilon$  and  $\varepsilon \rightarrow 0$ .

The generalized formulation of the regularized problem (2.2)–(2.4) reads as follows

$$\int_{Q_T} \left( u_\varepsilon \phi_t - \sum_{i=1}^n (u_{\varepsilon x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{\varepsilon x_i} \phi_{x_i} + \lambda g_\varepsilon(u_\varepsilon) \phi + f_\varepsilon \phi \right) dx dt = - \int_{\Omega} u_{0\varepsilon} \phi_0 \, dx, \tag{2.17}$$

where  $\phi_0 = \phi(\mathbf{x}, 0)$  and  $\phi$  is an arbitrary smooth function which vanishes on  $\partial\Omega \times (0, T)$  and on  $\Omega \times \{T\}$ . Notice that we replaced here  $\bar{g}_\varepsilon$  by  $g_\varepsilon$ , which is explained in Remark 1 in the previous section.

First of all, by the definition of the sequences  $\{f_\varepsilon\}$  and  $\{u_{0\varepsilon}\}$  we have that

$$f_\varepsilon \rightarrow f \quad \text{in } L^s(Q_T), \quad u_{0\varepsilon} \rightarrow u_0 \quad \text{in } L^s(\Omega)$$

as  $\varepsilon \rightarrow 0$  for all  $s \in [6, \infty)$ . This implies that

$$\int_{Q_T} f_\varepsilon \phi \, dx dt \rightarrow \int_{Q_T} f \phi \, dx dt \quad \text{and} \quad \int_{\Omega} u_{0\varepsilon} \phi_0 \, dx \rightarrow \int_{\Omega} u_0 \phi_0 \, dx \tag{2.18}$$

as  $\varepsilon \rightarrow 0$ .

Let us investigate the convergence of the sequence  $\{u_\varepsilon\}$ . As it follows from Lemmas 2.2, 2.3 and 2.5, this sequence has a subsequence which will be denoted again by  $\{u_\varepsilon\}$  such that

$$u_\varepsilon \rightarrow u \quad \text{* -weakly in } L^\infty(Q_T), \tag{2.19}$$

$$u_{\varepsilon x_i} \rightarrow u_{x_i} \quad \text{weakly in } L^{p_i+2}(Q_T), \quad i = 1, \dots, n, \tag{2.20}$$

$$u_{\varepsilon t} \rightarrow u_t \quad \text{* -weakly in } V^*(Q_T) \tag{2.21}$$

as  $\varepsilon \rightarrow 0$ . Obviously (2.19) and (2.21) imply that

$$\int_{Q_T} u_\varepsilon \phi_t \, dx dt \rightarrow \int_{Q_T} u \phi_t \, dx dt \quad \text{as } \varepsilon \rightarrow 0. \tag{2.22}$$

Our next step is the proof of the strong convergence of  $\{u_\varepsilon\}$  in  $L^s(Q_T)$  for all  $s \in [1, \infty)$ . We shall do this by the Aubin–Lions compactness theorem (see [1, Ch. 1.5] and [19]). Lemmas 2.2, 2.3 and 2.5 imply that the sequences  $\{u_\varepsilon\}$  and  $\{u_{\varepsilon t}\}$  are bounded in the spaces  $L^{p^*+2}(0, T; W_0^{1, p^*+2}(\Omega))$  and  $L^{q^*+2}(0, T; W^{-1, q^*+2}(\Omega))$ , respectively. Here,  $q^*$  is such that  $(q^* + 2)^{-1} + (p^* + 2)^{-1} = 1$  and  $W^{-1, q^*+2}(\Omega)$  is the space adjoint to  $W_0^{1, p^*+2}(\Omega)$ . The space  $W_0^{1, p^*+2}(\Omega)$  is compactly and densely embedded into  $L^{p^*+2}(\Omega)$ , but it can occur that  $L^{p^*+2}(\Omega)$  is not embedded into  $W^{-1, q^*+2}(\Omega)$ . However, we can take a larger space instead of  $W^{-1, q^*+2}(\Omega)$ . For instance,  $W^{-k, q^*+2}(\Omega)$  with  $k > \max\{n/(p^* + 2), 1\}$  is suitable. As it follows from the embedding theorems,  $L^{p^*+2}(\Omega) \subset W^{-k, q^*+2}(\Omega)$  and  $W^{-1, q^*+2}(\Omega) \subset W^{-k, q^*+2}(\Omega)$ . Therefore, the Aubin–Lions theorem implies that the sequence  $\{u_\varepsilon\}$  is compact in  $L^{p^*+2}(Q_T)$ . Thus, there exists a subsequence  $\{u_\varepsilon\}$  such that

$$u_\varepsilon \rightarrow u \quad \text{almost everywhere in } Q_T. \tag{2.23}$$

Moreover, since the sequence  $\{u_\varepsilon\}$  is bounded in  $L^\infty(Q_T)$ , the Lebesgue dominated convergence theorem yields that

$$u_\varepsilon \rightarrow u \quad \text{in } L^s(Q_T) \text{ for all } s \in [1, \infty).$$

From (2.23), we can easily deduce that

$$\int_{Q_T} \lambda g_\varepsilon(u_\varepsilon) \phi \, dx \, dt \rightarrow \int_{Q_T} \lambda g(u) \phi \, dx \, dt \quad \text{as } \varepsilon \rightarrow 0. \tag{2.24}$$

Indeed, there exists a constant  $M$  such that  $|u_\varepsilon(\mathbf{x}, t)| \leq M$  for all  $(\mathbf{x}, t) \in Q_T$  and for all  $\varepsilon \in (0, \varepsilon_0)$ . At the same time, property  $(i_\varepsilon)$  of the sequence  $\{g_\varepsilon\}$  implies that for every  $\gamma > 0$  there exists  $\varepsilon_\gamma$  such that  $\max_{\xi \in [-M, M]} |g_\varepsilon(\xi) - g(\xi)| < \gamma$  for  $\varepsilon \in (0, \varepsilon_\gamma)$ . Therefore,  $\max_{(\mathbf{x}, t) \in Q_T} |g_\varepsilon(u_\varepsilon(\mathbf{x}, t)) - g(u_\varepsilon(\mathbf{x}, t))| < \gamma$  for  $\varepsilon \in (0, \varepsilon_\gamma)$  and, as a consequence,

$$\begin{aligned} \left| \int_{Q_T} \lambda (g_\varepsilon(u_\varepsilon) - g(u)) \phi \, dx \, dt \right| &\leq \int_{Q_T} |g_\varepsilon(u_\varepsilon) - g(u_\varepsilon)| |\lambda \phi| \, dx \, dt + \int_{Q_T} |g(u_\varepsilon) - g(u)| |\lambda \phi| \, dx \, dt \\ &\leq \gamma \operatorname{mes} Q_T \max_{(\mathbf{x}, t) \in Q_T} |\lambda \phi(\mathbf{x}, t)| + \int_{Q_T} |g(u_\varepsilon) - g(u)| |\lambda \phi| \, dx \, dt. \end{aligned}$$

Due to (2.23) and the Lebesgue dominated convergence theorem, the integral term on the right-hand side of the last inequality tends to zero as  $\varepsilon \rightarrow 0$ . Since  $\gamma$  can be taken arbitrary small, (2.24) holds true.

Thus, in order to complete the passage to the limit in (2.17), we only have to prove that

$$\int_{Q_T} \sum_{i=1}^n (u_{\varepsilon x_i}^\alpha + \varepsilon)^{p_i/\alpha} u_{\varepsilon x_i} \phi_{x_i} \, dx \, dt \rightarrow \int_{Q_T} \sum_{i=1}^n |u_{x_i}|^{p_i} u_{x_i} \phi_{x_i} \, dx \, dt \quad \text{as } \varepsilon \rightarrow 0. \tag{2.25}$$

For this purpose, we employ the monotonicity method described in [1, Ch. 2]. Notice that we will slightly modify this method. Namely, unlike in [1], we shall use the monotonicity of the approximate operator.

For  $i = 1, \dots, n$ , define nonlinear operators  $A_{i\varepsilon}$  and  $A_i$  which act from  $U_i(\Omega)$  to  $U_i^*(\Omega)$ . For arbitrary functions  $v$  and  $w$  from the space  $U_i(\Omega)$ , we put

$$\begin{aligned} \langle A_{i\varepsilon}(v), w \rangle &= \sum_{i=1}^n \int_{\Omega} (v_{x_i}^\alpha + \varepsilon)^{p_i/\alpha} v_{x_i} w_{x_i} \, dx, \\ \langle A_i(v), w \rangle &= \sum_{i=1}^n \int_{\Omega} |v_{x_i}|^{p_i} v_{x_i} w_{x_i} \, dx, \end{aligned}$$

where  $\langle \cdot, \cdot \rangle$  is the duality pairing between  $U_i^*(\Omega)$  and  $U_i(\Omega)$ . It is not difficult to see that the operators  $A_{i\varepsilon}$  and  $A_i$  indeed map  $U_i(\Omega)$  into  $U_i^*(\Omega)$ . For the operator  $A_{i\varepsilon}$  it follows from Lemma 2.4, whereas for the operator  $A_i$ , this fact is the direct consequence of the Hölder inequality:

$$\int_{\Omega} |v_{x_i}|^{p_i} v_{x_i} w_{x_i} \, dx \leq \left( \int_{\Omega} |v_{x_i}|^{p_i+2} \, dx \right)^{(p_i+1)/(p_i+2)} \left( \int_{\Omega} |w_{x_i}|^{p_i+2} \, dx \right)^{1/(p_i+2)}.$$

For every  $v \in U(\Omega)$  we denote

$$A_\varepsilon(v) = \sum_{i=1}^n A_{i\varepsilon}(v), \quad A(v) = \sum_{i=1}^n A_i(v).$$

Clearly, operators  $A_\varepsilon$  and  $A$  act from  $U(\Omega)$  to  $U^*(\Omega)$ .

Thus, (2.25) is equivalent to the following assertion

$$\int_0^T \langle A_\varepsilon(u_\varepsilon), \phi \rangle \, dt \rightarrow \int_0^T \langle A(u), \phi \rangle \, dt \quad \text{as } \varepsilon \rightarrow 0,$$

where  $\langle \cdot, \cdot \rangle$  is the duality pairing between  $U^*(\Omega)$  and  $U(\Omega)$ .

Notice that, since the sequence  $\{A_\varepsilon(u_\varepsilon)\}$  is bounded in  $V^*(Q_T)$  (Lemma 2.4), there exists  $\chi \in V^*(Q_T)$  such that up to a subsequence

$$A_\varepsilon(u_\varepsilon) \rightarrow \chi \quad \text{* -weakly in } V^*(Q_T). \tag{2.26}$$

Our goal is to prove that  $\chi = A(u)$ .

Relations (2.18), (2.21), (2.24) and (2.26) imply that the limit function  $u$  satisfies the equation:

$$u_t + \chi = \lambda g(u) + f \quad \text{in } V^*(Q_T).$$

Obviously  $U(\Omega) \subset L^2(\Omega) \subset U^*(\Omega)$  and these embeddings are dense. Therefore, exactly as in [1] we obtain that

$$u \in C(0, T; L^2(\Omega)) \tag{2.27}$$

and

$$\int_{Q_T} (\lambda g(u) + f) u \, dx \, dt + \frac{1}{2} \int_{\Omega} u_0^2 \, dx - \frac{1}{2} \int_{\Omega} u^2(\mathbf{x}, T) \, dx = \int_0^T \langle \chi, u \rangle \, dt. \tag{2.28}$$

Multiplying Eq. (2.2) by  $u_\varepsilon$  and integrating over  $Q_T$ , we obtain

$$\int_0^T \langle A_\varepsilon(u_\varepsilon), u_\varepsilon \rangle \, dt = \int_{Q_T} (\lambda g_\varepsilon(u_\varepsilon) + f_\varepsilon) u_\varepsilon \, dx \, dt + \frac{1}{2} \int_{\Omega} u_{0\varepsilon}^2 \, dx - \frac{1}{2} \int_{\Omega} u_\varepsilon^2(\mathbf{x}, T) \, dx. \tag{2.29}$$

Operator  $A_\varepsilon$  is monotone (see Appendix A.3), i.e.,

$$\langle A_\varepsilon(u_\varepsilon) - A_\varepsilon(v), u_\varepsilon - v \rangle \geq 0$$

for an arbitrary  $v \in U(\Omega)$  and for all  $t \in [0, T]$ . This means that

$$\int_0^T \langle A_\varepsilon(u_\varepsilon), u_\varepsilon \rangle \, dt \geq \int_0^T \langle A_\varepsilon(u_\varepsilon), \phi \rangle \, dt + \int_0^T \langle A_\varepsilon(\phi), u_\varepsilon - \phi \rangle \, dt$$

for an arbitrary  $\phi \in V(Q_T)$ . Therefore, (2.29) yields

$$\int_{Q_T} (\lambda g_\varepsilon(u_\varepsilon) + f_\varepsilon) u_\varepsilon \, dx \, dt + \frac{1}{2} \int_{\Omega} u_{0\varepsilon}^2 \, dx - \frac{1}{2} \int_{\Omega} u_\varepsilon^2(\mathbf{x}, T) \, dx - \int_0^T \langle A_\varepsilon(u_\varepsilon), \phi \rangle \, dt - \int_0^T \langle A_\varepsilon(\phi), u_\varepsilon - \phi \rangle \, dt \geq 0.$$

The passage to the limit as  $\varepsilon \rightarrow 0$  in this inequality together with (2.28) implies that

$$\int_0^T \langle \chi - A(\phi), u - \phi \rangle \, dt \geq 0. \tag{2.30}$$

Here, we used the facts that (see Appendix A.4)

$$\int_{\Omega} u^2(\mathbf{x}, T) \, dx \leq \liminf_{\varepsilon \rightarrow 0} \int_{\Omega} u_\varepsilon^2(\mathbf{x}, T) \, dx \tag{2.31}$$

and that

$$\lim_{\varepsilon \rightarrow 0} \int_0^T \langle A_\varepsilon(\phi), u_\varepsilon - \phi \rangle \, dt = \int_0^T \langle A(\phi), u - \phi \rangle \, dt.$$

From (2.30) by standard arguments ([1, Ch. 2]), we conclude that

$$\chi = A(u).$$

The existence of a weak solution to the problem is proved.

As it follows from (2.21), for the constructed solution  $u$  we have  $u_t \in V^*(Q_T)$ . Inclusion  $u \in C([0, T]; L^s(\Omega))$  follows from (2.27) and (1.7) due to the Lebesgue dominated convergence theorem. Let us prove (1.7). Lemma 2.2 implies that  $\|u\|_{L^\infty(Q_T)} \leq m + M_c$  for every compact set  $\mathfrak{M}_c \subset \mathfrak{M}$ . Taking now infimum in this inequality over all  $\mathfrak{M}_c \subset \mathfrak{M}$ , we obtain (1.7) thanks to (2.1).

In order to complete the proof of the theorem, we have only to establish the uniqueness of the weak solution. Suppose that there exist two solutions  $u_1$  and  $u_2$ . Then the function  $w = u_1 - u_2$  satisfies the following equation

$$v^*(Q_{t_0}) \langle w_t, w \rangle_{V(Q_{t_0})} + \int_0^{t_0} v^* \langle A(u_1) - A(u_2), u_1 - u_2 \rangle_{V} \, dt = \lambda \int_{Q_{t_0}} (g(u_1) - g(u_2))(u_1 - u_2) \, dx \, dt$$

with an arbitrary  $t_0 \in (0, T]$ . Taking into account the monotonicity of  $A$ , the Lipschitz continuity of  $g$  and the fact that  $w(\mathbf{x}, 0) = 0$ , we obtain the following inequality

$$\frac{1}{2} \|w(t_0)\|_{L^2(\Omega)}^2 = v^*(Q_{t_0}) \langle w_t, w \rangle_{V(Q_{t_0})} \leq 2|\lambda|C \int_0^{t_0} \frac{1}{2} \|w(t)\|_{L^2(\Omega)}^2 \, dt,$$

where the constant  $C$  is such that  $|g(u_1) - g(u_2)| \leq C|u_1 - u_2|$ . Due to the Gronwall lemma this implies that  $u_1 = u_2$ .

Theorem 1 is proved.

### 3. Proof of Theorem 2

The proof of Theorem 2 is similar to that of Theorem 1. We regularize the problem, obtain uniform estimates and pass to the limit. Consider the regularized equation

$$u_{\varepsilon t} - \operatorname{div}((|\nabla u_{\varepsilon}|^{\alpha} + \varepsilon)^{p/\alpha} \nabla u_{\varepsilon}) = \lambda \bar{g}(u_{\varepsilon}) + f_{\varepsilon}, \tag{3.1}$$

with boundary conditions (2.3) and (2.4). The functions  $g_{\varepsilon}$ ,  $\bar{g}_{\varepsilon}$  and  $f_{\varepsilon}$  are the same as in Section 2.1. If  $p \geq 1$  then we take arbitrary positive  $\varepsilon$  and  $\alpha = 2$ . If  $p \leq 0$  then we again take  $\alpha = 2$  but we require  $\varepsilon$  to be small enough, namely

$$0 < \varepsilon < (1 - p) \left( \frac{2M}{3l_*^2 + 2l_*} \right)^2.$$

If  $p \in (0, 1)$  we require that, as in Section 2,  $\alpha = r/m$  with positive integers  $r$  and  $m$  such that  $r < m$  and  $r$  is even.

Notice that for every compact subset  $\mathfrak{N}_c$  of  $\mathfrak{N}$  there exists  $\varepsilon_0 > 0$  such that

$$f^* + |\lambda|g_{\varepsilon}(M + m) < (p + 1) \left( \frac{2M}{3l_*^2 + 2l_*} \right)^{p+1}$$

for all  $M \in \mathfrak{N}$  and  $\varepsilon \in (0, \varepsilon_0)$ . This fact can be proved similar to Lemma 2.1. We shall say that  $\varepsilon_0$  corresponds to  $\mathfrak{N}_c$ .

Let us estimate a classical solution  $u_{\varepsilon}$  of problem (3.1), (2.3) and (2.4) in  $L^{\infty}$  norm. To simplify the notation, in the proofs of Lemmas 3.1–3.4 we will omit the subscript  $\varepsilon$ .

**Lemma 3.1.** *For every compact set  $\mathfrak{N}_c \subset \mathfrak{N}$  and for every  $\varepsilon \in (0, \varepsilon_0)$ , the classical solution of problem (3.1), (2.3) and (2.4) satisfies the following estimate:*

$$\|u_{\varepsilon}\|_{L^{\infty}(Q_T)} \leq m + M_c,$$

where  $M_c = \min\{M \mid M \in \mathfrak{N}_c\}$  and  $\varepsilon_0$  is the positive number corresponding to  $\mathfrak{N}_c$ .

**Proof.** Without loss of generality suppose that  $l_* = l_1$ . Let us take an arbitrary  $M \in \mathfrak{M}_c$ . Define the function  $h(x_1)$  by the following:

$$h(x_1) = \tilde{M} \left( \frac{l_1^2 - x_1^2}{2} + (1 + l_1)(l_1 + x_1) \right) + m,$$

where

$$\tilde{M} = \frac{M}{d_1}, \quad d_1 = \frac{3l_1^2 + 2l_1}{2}.$$

Define the operator  $L$ :

$$Lu \equiv u_t - \operatorname{div}((|\nabla u|^{\alpha} + \varepsilon)^{p/\alpha} \nabla u).$$

We have

$$Lu = |\lambda| \bar{g}(u) + f(\mathbf{x}, t)$$

and

$$Lh = h_t - \operatorname{div}((|\nabla h|^{\alpha} + \varepsilon)^{p/\alpha} \nabla h) - (h'^{\alpha} + \varepsilon)(\varepsilon + (1 + p)h'^{\alpha})h'' = (h'^{\alpha} + \varepsilon)(\varepsilon + (1 + p)h'^{\alpha}) \frac{M}{d_1}.$$

Consider function

$$E(\varepsilon) \equiv (h'^{\alpha} + \varepsilon)^{(p-\alpha)/\alpha} (h'^{\alpha} (1 + p) + \varepsilon).$$

Due to the assumptions on  $\alpha$  and  $\varepsilon$  we conclude that

$$E'(\varepsilon) = \frac{p}{\alpha} (h'^{\alpha} + \varepsilon)^{\frac{p-2\alpha}{\alpha}} (h'^{\alpha} (1 + p - \alpha) + \varepsilon) \geq 0.$$

This inequality implies that

$$E(\varepsilon) \geq E(0)$$

and

$$Lh \geq |h'|^p (1 + p) \frac{M}{d_1} \geq \left( 1 + p \left( \frac{M}{d_1} \right)^{p+1} \right).$$

Now, similarly to the proof of Lemma 2.2, we deduce that

$$-h(x_1) \leq u(\mathbf{x}, t) \leq h(x_1) \quad \text{in } \bar{Q}_T$$

and

$$-h(-x_1) \leq u(\mathbf{x}, t) \leq h(-x_1) \quad \text{in } \bar{Q}_T.$$

As a consequence we conclude that

$$\|u(\mathbf{x}, t)\|_{L^\infty(Q_T)} \leq h(0) = M + m.$$

The assertion of the lemma follows now from the fact that  $M$  is an arbitrary number from  $\mathfrak{N}_c$ .  $\square$

**Remark 2.** Due to the estimates in the previous lemmas, we can take  $g(u)$  instead of  $\bar{g}(u)$  in Eq. (3.1).

Let us turn now to integral estimates.

**Lemma 3.2.** Suppose that conditions of Lemma 3.1 are fulfilled, then for any classical solution of problem (3.1), (2.3) and (2.4) the following estimate is valid

$$\int_{Q_T} |\nabla u_\varepsilon(t, \mathbf{x})|^{p+2} d\mathbf{x}dt \leq C,$$

where the constant  $C$  is independent of  $\varepsilon$ .

**Proof.** Multiply Eq. (3.1) by  $u$ , integrating by parts and taking into account that  $|u| \leq M + m$ , we find that

$$\int_{Q_T} (|\nabla u|^\alpha + \varepsilon)^{p/\alpha} |\nabla u|^2 d\mathbf{x}dt \leq C_1 \tag{3.2}$$

for some independent of  $\varepsilon$  constant  $C_1$ .

Suppose that  $p \geq 0$ . In this case  $(z^\alpha + \varepsilon)^{p/\alpha} z^2 \geq |z|^{p+2}$  and consequently (3.2) implies that

$$\int_{Q_T} |\nabla u|^{p+2} d\mathbf{x}dt \leq C_1.$$

Consider the case  $p \in (-1, 0)$ . Let  $(Q_T)^\varepsilon$  be the subset of  $Q_T$  where  $|\nabla u|^\alpha > \varepsilon$  and  $(Q_T)_\varepsilon = Q_T \setminus (Q_T)^\varepsilon$ . Obviously,  $|\nabla u|^\alpha + \varepsilon < 2|\nabla u|^\alpha$  in  $(Q_T)^\varepsilon$  and, since  $p$  is negative,

$$C_1 \geq \int_{(Q_T)^\varepsilon} (|\nabla u|^\alpha + \varepsilon)^{p/\alpha} |\nabla u|^2 d\mathbf{x}dt > 2^{p/\alpha} \int_{(Q_T)^\varepsilon} |\nabla u|^{p+2} d\mathbf{x}dt.$$

At the same time

$$\int_{(Q_T)_\varepsilon} |\nabla u|^{p+2} d\mathbf{x}dt \leq T\varepsilon^{p+2} \text{mes } \Omega.$$

Thus

$$\int_{Q_T} |\nabla u|^{p+2} d\mathbf{x}dt \leq 2^{-p/\alpha} C_1 + T\varepsilon^{p+2} \text{mes } \Omega.$$

Without loss of generality we can assume that  $\varepsilon \leq 1$ , hence the lemma is proved.  $\square$

Let us prove the following auxiliary lemma.

**Lemma 3.3.** Let functions  $w$  and  $\phi$  be in  $W_0^{1,p+2}(\Omega)$ ,  $p > -1$ . Then

$$\left| \int_{\Omega} (|\nabla w|^\alpha + \varepsilon)^{p/\alpha} \nabla w \cdot \nabla \phi d\mathbf{x} \right| \leq 2^{p/\alpha} (\|\nabla w\|_{L^{p+2}(\Omega)}^{p+1} + \varepsilon^{(p+1)/\alpha}) \|\nabla \phi\|_{L^{p+2}(\Omega)}$$

for all  $\varepsilon \in (0, 1)$ .

**Proof.** For a fixed  $\varepsilon \in (0, 1)$ , denote by  $\Omega^\varepsilon$  the subset of  $\Omega$ , where  $|\nabla w|^\alpha > \varepsilon$ , and by  $\Omega_\varepsilon$  the subset of  $\Omega$ , where  $|\nabla w|^\alpha \leq \varepsilon$ . In  $\Omega^\varepsilon$ , we have

$$(|\nabla w|^\alpha + \varepsilon)^{p/\alpha} |\nabla w| < 2^{p/\alpha} |\nabla w|^{p+1}.$$

Therefore,

$$\left| \int_{\Omega_\varepsilon} (|\nabla w|^\alpha + \varepsilon)^{p/\alpha} \nabla w \cdot \nabla \phi \, d\mathbf{x} \right| < 2^{p/\alpha} \int_{\Omega_\varepsilon} |\nabla w|^{p+1} |\nabla \phi| \, d\mathbf{x} \leq 2^{p/\alpha} \|\nabla w\|_{L^{p+2}(\Omega)}^{p+1} \|\nabla \phi\|_{L^{p+2}(\Omega)}.$$

The integral over  $\Omega_\varepsilon$  can be estimated as follows

$$\left| \int_{\Omega_\varepsilon} (|\nabla w|^\alpha + \varepsilon)^{p/\alpha} \nabla w \cdot \nabla \phi \, d\mathbf{x} \right| \leq (2\varepsilon)^{p/\alpha} \varepsilon^{1/\alpha} \int_{\Omega_\varepsilon} |\nabla \phi| \, d\mathbf{x} \leq 2^{p/\alpha} \varepsilon^{(p+1)/\alpha} \|\nabla \phi\|_{L^1(\Omega)}.$$

The assertion of the lemma follows from these estimates.  $\square$

**Lemma 3.4.** *There exists a constant  $C$  such that*

$$\left| \int_{Q_T} u_{\varepsilon t} \phi \, d\mathbf{x} \, dt \right| \leq C \|\phi\|_{L^{p+2}(0, T; W_0^{1, p+2}(\Omega))}$$

for every function  $\phi \in L^{p+2}(0, T; W_0^{1, p+2}(\Omega)) \cap L^{(p+2)/(p+1)}(Q_T)$  and for all  $\varepsilon \in (0, \varepsilon_0)$ .

**Proof.** As earlier, we shall write  $u$  instead of  $u_\varepsilon$ . Multiplying (3.1) by an arbitrary smooth function  $\phi(t, \mathbf{x})$  that is equal to zero on  $\partial\Omega$  and integrating over  $Q_T$ , we find that

$$\left| \int_{Q_T} u_t \phi \, d\mathbf{x} \, dt \right| \leq \left| \int_{Q_T} (|\nabla u|^\alpha + \varepsilon)^{p/\alpha} \nabla u \nabla \phi \, d\mathbf{x} \, dt \right| + \int_{Q_T} |\lambda \bar{g}_\varepsilon(u) + f_\varepsilon| |\phi| \, d\mathbf{x} \, dt. \tag{3.3}$$

From Lemma 3.1, it follows that there exists a constant  $C_1$  such that

$$\int_{Q_T} |\bar{g}_\varepsilon(u) + f| |\phi| \, d\mathbf{x} \, dt \leq C_2 \|\phi\|_{L^1(Q_T)} \leq C_3 \|\phi\|_{L^{p+2}(0, T; W_0^{1, p+2}(\Omega))}. \tag{3.4}$$

Consider the first term on the right-hand side of (3.3). Due to Lemma 3.3, there exists a constant  $C_2$  such that

$$\left| \int_{Q_T} (|\nabla u|^\alpha + \varepsilon)^{p/\alpha} \nabla u \cdot \nabla \phi \, d\mathbf{x} \, dt \right| \leq C_2 \|\nabla \phi\|_{L^{p+2}(Q_T)}. \tag{3.5}$$

The assertion of the lemma follows now from (3.4) and (3.5).  $\square$

We have obtained all estimates needed to pass to the limit as  $\varepsilon \rightarrow 0$  in Eqs. (3.1), (2.3) and (2.4). It can be done absolutely in the same way as in Section 2.2. The only difference is in the definition of operators  $A_\varepsilon$  and  $A$ . We define operators acting from  $W_0^{1, p+2}(\Omega)$  to  $W^{-1, q+2}(\Omega)$  with  $(p+2)^{-1} + (q+2)^{-1} = 1$ . For arbitrary functions  $v$  and  $w$  from the space  $W_0^{1, p+2}(\Omega)$ , we put

$$\begin{aligned} \langle \mathcal{A}_\varepsilon(v), w \rangle &= \int_{\Omega} (|\nabla v|^\alpha + \varepsilon)^{p/\alpha} \nabla v \cdot \nabla w \, d\mathbf{x}, \\ \langle \mathcal{A}(v), w \rangle &= \int_{\Omega} |\nabla v|^p \nabla v \cdot \nabla w \, d\mathbf{x}, \end{aligned}$$

where  $\langle \cdot, \cdot \rangle$  is the duality pairing between  $W^{-1, q+2}(\Omega)$  and  $W_0^{1, p+2}(\Omega)$ .

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### Appendix

#### A.1. Approximation of the function $g$

Let  $g : \mathbb{R} \rightarrow \mathbb{R}$  be a continuous function such that  $|g(\xi)| \leq g(\eta)$  whenever  $|\xi| \leq \eta$ . We want to prove that there exists a sequence of functions  $g_\varepsilon : \mathbb{R} \rightarrow \mathbb{R}$  that satisfy the following conditions:

- (1) they are continuously differentiable on every compact subset of  $\mathbb{R}$ ;
- (2)  $|g_\varepsilon(\xi)| \leq g_\varepsilon(\eta)$  for all real  $\xi$  and  $\eta$  such that  $|\xi| \leq \eta$ ;
- (3) the sequence  $\{g_\varepsilon\}$  converges to the function  $g$  as  $\varepsilon \rightarrow 0$  uniformly on every compact subset of  $\mathbb{R}$ .



Let us define

$$g_\varepsilon(\xi) = \frac{1}{2\varepsilon} \int_{\xi-\varepsilon}^{\xi+\varepsilon} g(\eta) d\eta$$

and verify the properties formulated above. The first and the third properties are obvious. Moreover,  $g_\varepsilon$  is continuously differentiable since the function  $g$  is continuous. Let us turn to the proof of the second property.

Note that the function  $g$  is nondecreasing and nonnegative on  $[0, \infty)$ . Let us prove that the function  $g_\varepsilon$  has the same properties, which implies property (2) for  $\xi \geq 0$ . Indeed,  $g'_\varepsilon(\xi) = (2\varepsilon)^{-1}(g(\xi + \varepsilon) - g(\xi - \varepsilon))$ . If  $\xi \geq \varepsilon$ , then  $g'_\varepsilon(\xi) \geq 0$ . If  $\xi \in [0, \varepsilon]$ , then  $|g(\xi - \varepsilon)| \leq g(|\xi - \varepsilon|) \leq g(\xi + \varepsilon)$  and we have again  $g'_\varepsilon(\xi) \geq 0$ . In order to prove that  $g_\varepsilon \geq 0$  on  $[0, \infty)$ , it is enough to show that  $g_\varepsilon(0) \geq 0$ . This fact is an obvious consequence of the following relations

$$g_\varepsilon(0) = \frac{1}{2\varepsilon} \int_{-\varepsilon}^{\varepsilon} g(\eta) d\eta = \frac{1}{2\varepsilon} \int_{-\varepsilon}^0 g(\eta) d\eta + \frac{1}{2\varepsilon} \int_0^{\varepsilon} g(\eta) d\eta,$$

$$\left| \int_{-\varepsilon}^0 g(\eta) d\eta \right| \leq \int_{-\varepsilon}^0 |g(\eta)| d\eta \leq \int_{-\varepsilon}^0 g(-\eta) d\eta = \int_0^{\varepsilon} g(\eta) d\eta.$$

Thus,  $g_\varepsilon(\xi)$  satisfies (2) for  $\xi \geq 0$ .

For negative  $\xi$ , due to the monotonicity of the function  $g_\varepsilon$  on  $[0, \infty)$ , we have to prove that  $|g_\varepsilon(\xi)| \leq g_\varepsilon(|\xi|) = g_\varepsilon(-\xi)$ . If  $\xi \in (-\infty, -\varepsilon]$ , then

$$|g_\varepsilon(\xi)| \leq \frac{1}{2\varepsilon} \int_{\xi-\varepsilon}^{\xi+\varepsilon} |g(\eta)| d\eta \leq \frac{1}{2\varepsilon} \int_{\xi-\varepsilon}^{\xi+\varepsilon} g(-\eta) d\eta$$

$$= -\frac{1}{2\varepsilon} \int_{-\xi-\varepsilon}^{-\xi+\varepsilon} g(\eta) d\eta = \frac{1}{2\varepsilon} \int_{|\xi|-\varepsilon}^{|\xi|+\varepsilon} g(\eta) d\eta = g_\varepsilon(|\xi|).$$

Finally, suppose that  $\xi \in (-\varepsilon, 0)$ . Since  $\int_{-\xi-\varepsilon}^{-\xi+\varepsilon} g(\eta) d\eta \geq 0$ , we have

$$|g_\varepsilon(\xi)| = \left| \frac{1}{2\varepsilon} \int_{\xi-\varepsilon}^{\xi+\varepsilon} g(\eta) d\eta \right| \leq \frac{1}{2\varepsilon} \int_{\xi-\varepsilon}^{-\xi-\varepsilon} |g(\eta)| d\eta + \frac{1}{2\varepsilon} \int_{-\xi-\varepsilon}^{\xi+\varepsilon} g(\eta) d\eta$$

$$\leq \frac{1}{2\varepsilon} \int_{\xi-\varepsilon}^{-\xi-\varepsilon} g(-\eta) d\eta + \frac{1}{2\varepsilon} \int_{-\xi-\varepsilon}^{\xi+\varepsilon} g(\eta) d\eta = \frac{1}{2\varepsilon} \int_{\xi+\varepsilon}^{-\xi+\varepsilon} g(\eta) d\eta + \frac{1}{2\varepsilon} \int_{-\xi-\varepsilon}^{\xi+\varepsilon} g(\eta) d\eta$$

$$= \frac{1}{2\varepsilon} \int_{-\xi-\varepsilon}^{-\xi+\varepsilon} g(\eta) d\eta = g_\varepsilon(-\xi) = g_\varepsilon(|\xi|).$$

Thus, property (2) is entirely proved.

### A.2. Proof of a classical solvability of the regularized problems

Regularized equation (3.1) is uniformly parabolic equation and the global solvability of problem (3.1), (2.3) and (2.4) follows, for example, from [20].

Regularized equation (2.2) is strictly parabolic but not uniformly parabolic equation. In order to prove the global classical solvability of problem (2.2)–(2.4) it is sufficient to prove the a priori estimate of  $|\nabla u|$ . After this, Eq. (2.2) can be considered as uniformly parabolic and the required existence follows from [20]. In order to prove this estimate we will apply the classical Bernstein method (see [21,20]), which involves differentiation of Eq. (2.2) with respect to  $x_i$ ,  $i = 1, \dots, n$  followed by multiplication by  $u_{x_i}$  and summation over  $i$ . The maximum principle is then applied to the resulting equation in the function  $v = |\nabla u|^2$ . For  $v$  we obtain

$$\sum_{i=1}^n a_i(u_{x_i}, \varepsilon) v_{x_i x_i} - v_t + \sum_{i=1}^n \frac{\partial a_i(u_{x_i}, \varepsilon)}{\partial u_{x_i}} u_{x_i x_i} v_{x_i} + 2 \left( \lambda g'_\varepsilon(u) + \frac{\sum_{i=1}^n f_{x_i} u_{x_i}}{|\nabla u|^2} \right) v \geq 0.$$

If  $v \geq 1$  then there exists a constant  $K$  depending on  $g(M)$  and  $\max |f_{x_i}|$  such that

$$2 \left( \lambda g'_\varepsilon(u) + \frac{\sum_{i=1}^n f_{x_i} u_{x_i}}{|\nabla u|^2} \right) < K.$$

For  $\omega = ve^{-Kt}$  we obtain

$$\sum_{i=1}^n a_i(u_{x_i}, \varepsilon)\omega_{x_i x_i} - \omega_t + \sum_{i=1}^n \frac{\partial a_i(u_{x_i}, \varepsilon)}{\partial u_{x_i}} u_{x_i x_i} \omega_{x_i} + \left( 2 \left( \lambda g'_\varepsilon(u) + \frac{\sum_{i=1}^n f_{x_i} u_{x_i}}{v} \right) - K \right) \omega \geq 0,$$

from the classical maximum principle, we conclude that  $\omega \leq \max_{\Gamma_T} \omega$  where  $\Gamma_T$  is the parabolic boundary of the domain, and hence

$$v \leq \max\{e^{KT} \max_{\Gamma_T} v, 1\}.$$

Thus, it is sufficient to estimate  $\max v$  on the set  $\partial\Omega \times (0, T]$ . Recall that  $\Omega$  satisfies an exterior sphere condition at a point  $\mathbf{x}^0 \in \partial\Omega$  so that there exists a ball  $B_R(\mathbf{y}^0)$  (with center at a point  $\mathbf{y}^0 \notin \Omega$  and radius  $R$ ) such that  $\mathbf{x}^0 = \partial\Omega \cap \bar{B}_R(\mathbf{y}^0)$ . Consider the distance function  $r(\mathbf{x}) \equiv |\mathbf{x} - \mathbf{y}^0| - R$ . Let  $w = w(r)$  be a smooth function such that  $w'(r) \geq 1$ . We have

$$\begin{aligned} Lw(r) &\equiv \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)w_{x_i x_i} + \lambda g(u) + f - w_t \\ &= w' \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)r_{x_i x_i} + \frac{w''}{w'^2} \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)r_{x_i}^2 w'^2 + \lambda g(u) + f \\ &\leq w' \frac{n-1}{R} \sum_{i=1}^n a_i(w_{x_i}, \varepsilon) + \frac{w''}{w'^2} \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)w_{x_i}^2 + |\lambda|g(M) + f^*. \end{aligned}$$

Since  $|\nabla w| = |w'| = w' \geq 1$ , for sufficiently large  $\mu$  we have

$$|\nabla w| \sum_{i=1}^n a_i(w_{x_i}, \varepsilon) \leq \mu \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)w_{x_i}^2,$$

and

$$|\lambda|g(M) + f^* \leq \mu \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)w_{x_i}^2.$$

Hence

$$Lw(r) \leq \left( \frac{w''}{w'^2} + v \right) \sum_{i=1}^n a_i(w_{x_i}, \varepsilon)w_{x_i}^2,$$

where  $v = (1 + (n-1)R^{-1})\mu$ .

Consider the cylinder

$$Q_{\mathbf{x}_0, d} = \{(\mathbf{x}, t) : 0 < r(\mathbf{x}) < d, 0 < t \leq T\} \cap Q_T,$$

where the quantity  $d$  will be defined below. Let  $w(r)$  be a solution of the problem

$$w'' + vw'^2 = 0, \quad w(0) = 0, \quad w(d) = M$$

such that  $w' \geq 1$ . Obviously,

$$w(r) = \frac{1}{v} \ln \left( 1 + \frac{e^{Mv-1}}{d} r \right).$$

In order to satisfy condition  $w' \geq 1$  we select  $d$  small enough (such that  $e^{Mv}(1-dv) \geq 1$ ).

In  $Q_{\mathbf{x}_0, d}$  we have

$$Lw \leq 0.$$

On the part of parabolic boundary of  $Q_{\mathbf{x}_0, d}$  belonging to  $\partial\Omega \times (0, T]$  we have  $u - w = -w < 0$ , on the part of parabolic boundary of  $Q_{\mathbf{x}_0, d}$  which is lying inside of the domain  $Q_T$  ( $t > 0$ ) we have  $u - w = u - M \leq 0$ . For  $t = 0$  we obtain the inequality  $u_0 \leq w$  by selecting  $d$  small enough (and as a consequence  $w'$  will be big enough). So, due to the maximum principle we obtain

$$u(\mathbf{x}, t) \leq w(r(\mathbf{x})) \quad \text{in } \bar{Q}_{\mathbf{x}_0, d}.$$

Similarly we prove that

$$u(\mathbf{x}, t) \geq -w(r(\mathbf{x})) \quad \text{in } \bar{Q}_{\mathbf{x}_0, d},$$

from where we obtain the needed estimate

$$v(\mathbf{x}_0, t) = |\nabla u(\mathbf{x}_0, t)|^2 \leq w^2(0)n.$$

A.3. Monotonicity of operators  $A_\varepsilon$  and  $A$

In this section, we prove that the operators  $A_i$  and  $A_{i\varepsilon}$  are monotone. This will imply that the operators  $A$  and  $A_\varepsilon$  are also monotone. As it follows from Proposition 1.1 in [1, Ch. 2], it is sufficient to prove that these operators are Gateau derivatives of convex functionals. Let us define functionals  $\Phi_i$  and  $\Psi_i : U_i(\Omega) \rightarrow \mathbb{R}$  as follows

$$\Phi_i(u) = \int_{\Omega} |u_{x_i}|^{p_i+2} dx, \quad \Psi_i(u) = \int_{\Omega} F_i(|u_{x_i}|^2) dx,$$

where

$$F_i(\eta) = \int_0^\eta (\xi^{\alpha/2} + \varepsilon)^{p_i/\alpha} d\xi.$$

It is not difficult to see that  $\Phi'_i(u) = A(u)$  and  $\Psi'_i(u) = A_{i\varepsilon}(u)$ . Convexity of the functional  $\Phi_i$  is obvious. Convexity of  $\Psi_i$  will be proved if we establish convexity of the function  $F_i(|\xi|^2)$  with respect to  $\xi$ . However this fact is a direct consequence of the following properties of the function  $F_i$ :

$$F'_i(\eta) \geq 0 \quad \text{and} \quad F''_i(\eta) \geq 0 \quad \text{for } \eta \geq 0.$$

Similarly we can prove here that the operators  $\mathcal{A}$  and  $\mathcal{A}_\varepsilon$  are monotone. We have to prove that these operators are Gateau derivatives of convex functionals. Let us define functionals  $\Phi$  and  $\Psi : W_0^{1,p+2}(\Omega) \rightarrow \mathbb{R}$  as follows

$$\Phi(u) = \int_{\Omega} |\nabla u|^{p+2} dx, \quad \Psi(u) = \int_{\Omega} F(|\nabla u|^2) dx,$$

where

$$F(\eta) = \int_0^\eta (\xi^{\alpha/2} + \varepsilon)^{p/\alpha} d\xi.$$

It is not difficult to see that  $\Phi'(u) = \mathcal{A}(u)$  and  $\Psi'(u) = \mathcal{A}_\varepsilon(u)$ . Convexity of the functional  $\Phi$  is obvious. Convexity of  $\Psi$  will be proved if we establish convexity of the function  $\xi \mapsto F(|\xi|^2)$ . But this fact is a direct consequence of the following properties of the function  $F$ :

$$F'(\eta) \geq 0 \quad \text{and} \quad F''(\eta) \geq 0 \quad \text{for } \eta \geq 0.$$

A.4. Proof of relation (2.31)

In order to prove (2.31), we consider the following equality

$$\int_{\Omega} u_\varepsilon(\mathbf{x}, T)v(\mathbf{x}, T)dx = \int_0^T \int_{\Omega} (u_{\varepsilon t}v + u_\varepsilon v_t)dxdt + \int_{\Omega} u_{0\varepsilon}(\mathbf{x})v(\mathbf{x}, 0)dx$$

with a smooth function  $v$ . Passing to the limit, we obtain

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \int_{\Omega} u_\varepsilon(\mathbf{x}, T)v(\mathbf{x}, T)dx &= v^*(Q_T)\langle u_t, v \rangle_{V(Q_T)} + v^*(Q_T)\langle u, v_t \rangle_{V(Q_T)} + \int_{\Omega} u_0(\mathbf{x})v(\mathbf{x}, 0)dx \\ &= \int_{\Omega} u(\mathbf{x}, T)v(\mathbf{x}, T)dx. \end{aligned}$$

Since  $C_0^\infty(\Omega)$  is dense in  $L^2(\Omega)$ ,  $u_\varepsilon(T, \mathbf{x}) \rightarrow u(T, \mathbf{x})$  weakly in  $L^2(\Omega)$ . Thus, due to the weak lower semicontinuity of the norm in  $L^2(\Omega)$ , we obtain (2.31).

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